

The 22th IEEE Asian Test Symposium (ATS'13) , Yilan, Taiwan, Nov. 20, 2013

# An Analysis of Stochastic Self-Calibration of TDC Using Two Ring Oscillators

Kentaroh Katoh, Yuta Doi, Satoshi Ito, Haruo Kobayashi,  
Ensi Li, Nobukazu Takai, Osamu Kobayashi



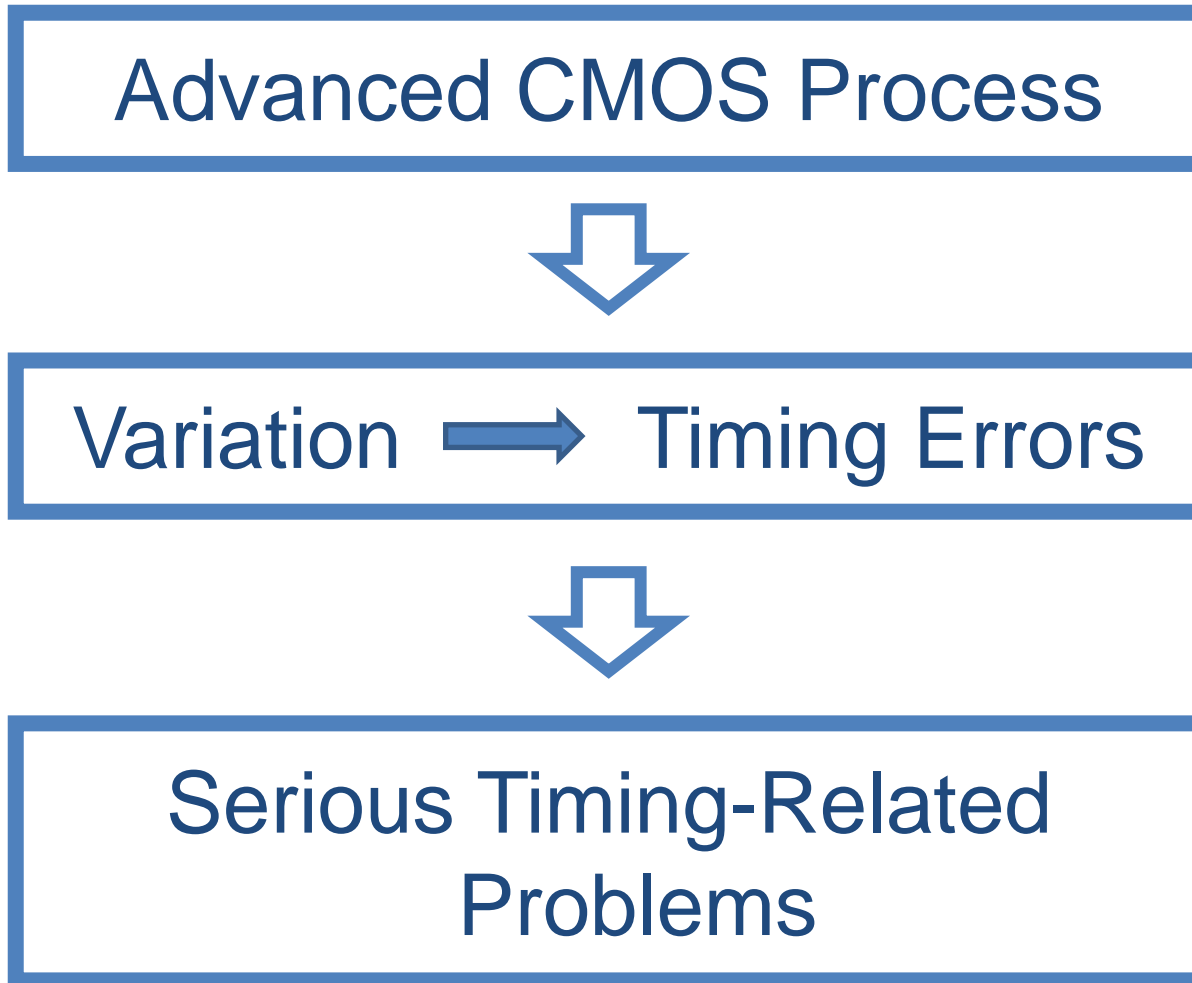
# Contents



- Background
  - Motivation
  - TDC
  - Abstract of Stochastic Calibration
  - Aim of Study
- Preliminaries for Simulation
- Simulation Results
- Conclusion



# Motivation



# TDC for solution of timing-related problems



## Examples of Timing-Related Problems

Jitter of High-Speed Serial Interface  
Delay Fault of Logic Circuit



## Solution

On-Chip Delay Measurement

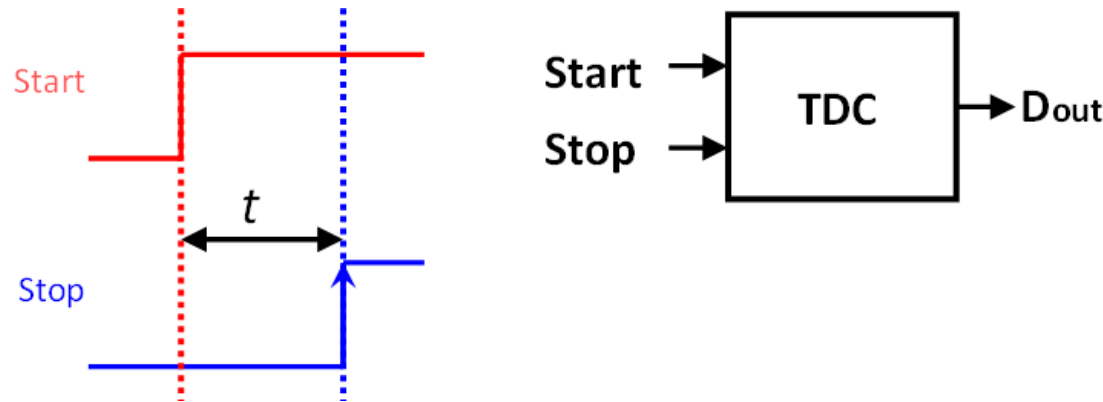


**TDC** (Time to Digital Converter)



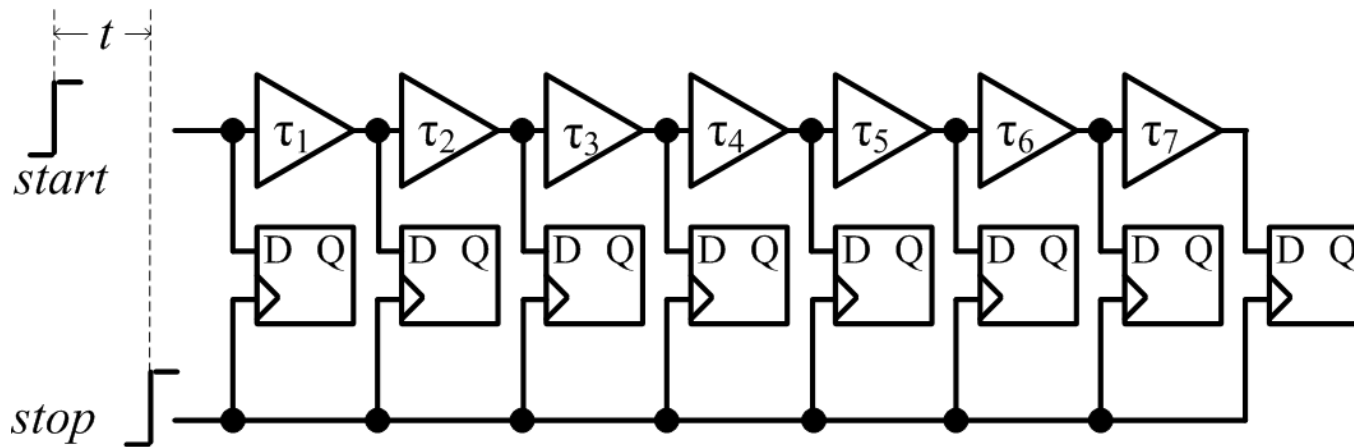
# TDC (Time to Digital Converter)

- An On-Chip Delay Measurement Circuit
- Time Interval  $\longrightarrow$  Digital Value



- Consists of CMOS digital elements  
 $\longrightarrow$  can be embedded in advanced VLSI

# Basic TDC



$t$	TDC Code	$t$	TDC Code
$0 < t < \tau_1$	10000000	$\tau_4 < t < \tau_5$	11111000
$\tau_1 < t < \tau_2$	11000000	$\tau_5 < t < \tau_6$	11111100
$\tau_2 < t < \tau_3$	11100000	$\tau_6 < t < \tau_7$	11111110
$\tau_3 < t < \tau_4$	11110000	$\tau_7 < t$	11111111

# Problems of TDC



Advanced CMOS Process



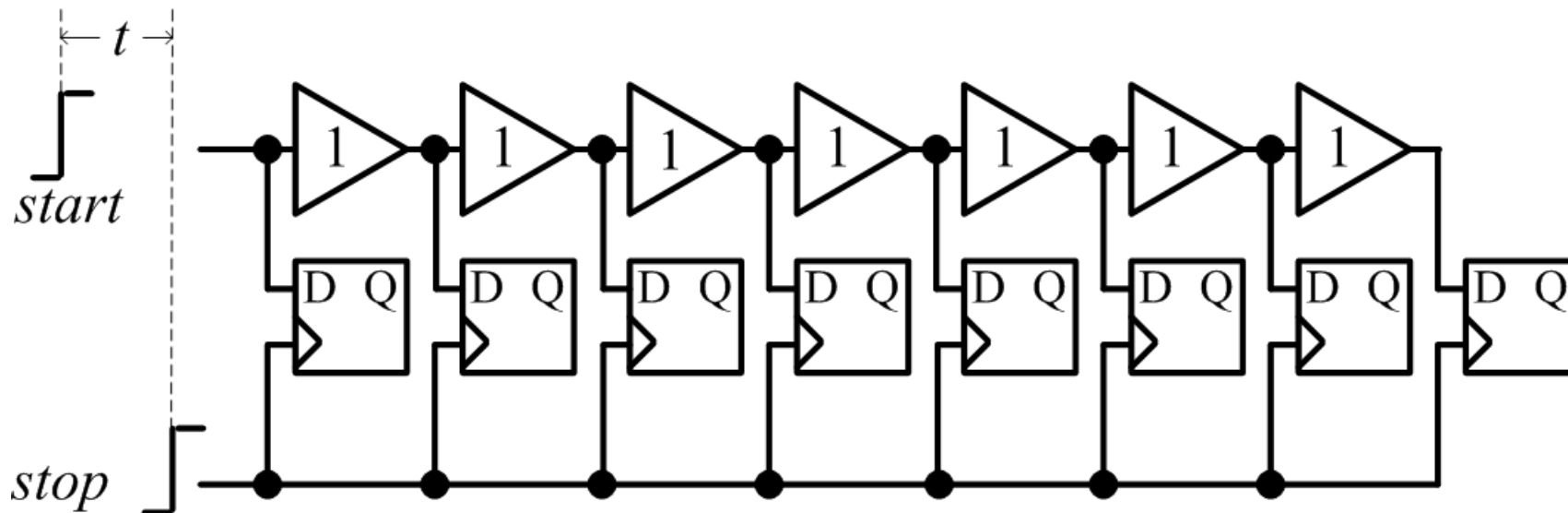
Variation  $\Rightarrow$  Delay Variation of Buffers



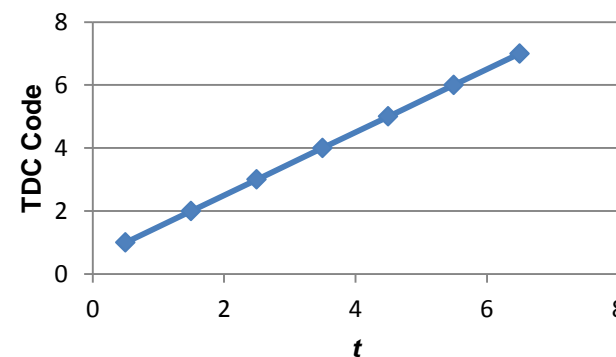
Non-linearity Characteristics  $\Rightarrow$  Problem



# Problems of TDC (Cont.)

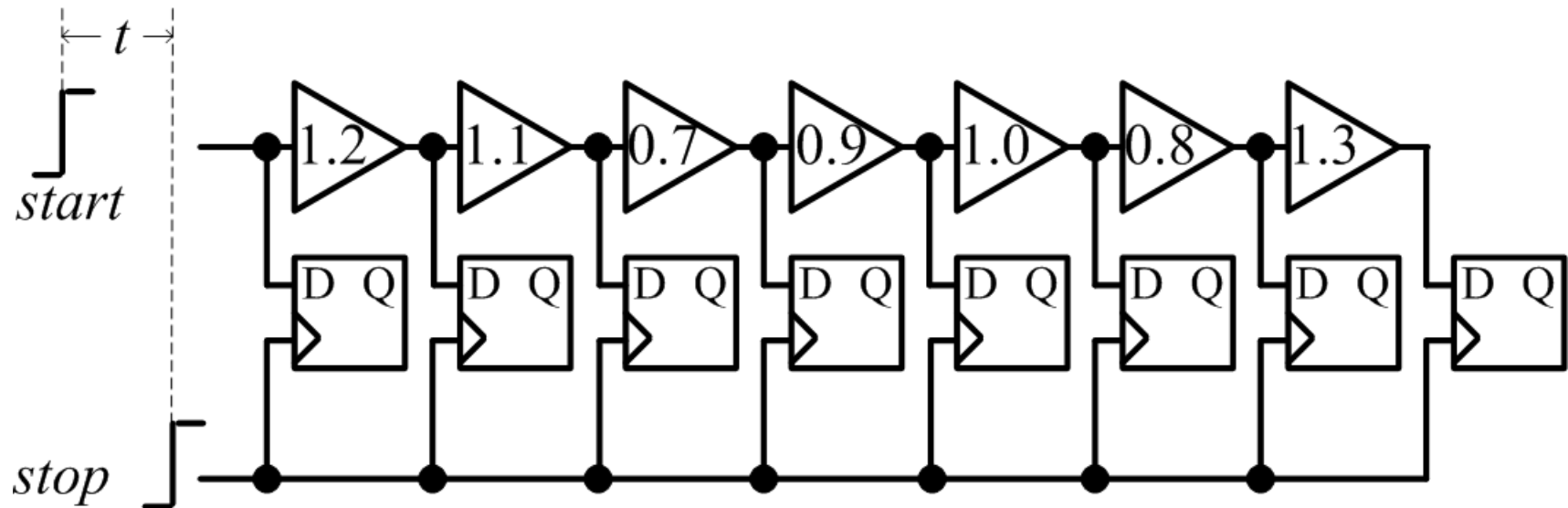


$t$	TDC Code	$t$	TDC Code
$0.0 < t < 1.0$	10000000	$4.0 < t < 5.0$	11111000
$1.0 < t < 2.0$	11000000	$5.0 < t < 6.0$	11111100
$2.0 < t < 3.0$	11100000	$6.0 < t < 7.0$	11111110
$3.0 < t < 4.0$	11110000	$7.0 < t$	11111111

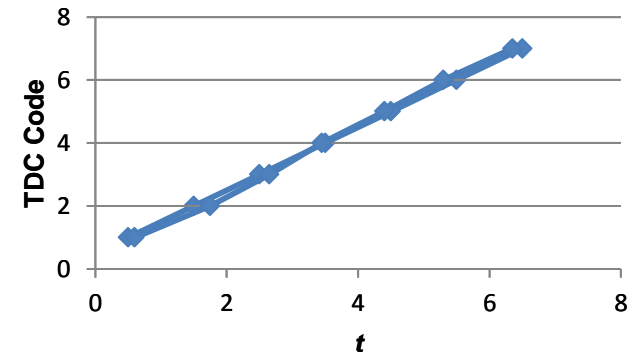




# Problems of TDC (Cont.)

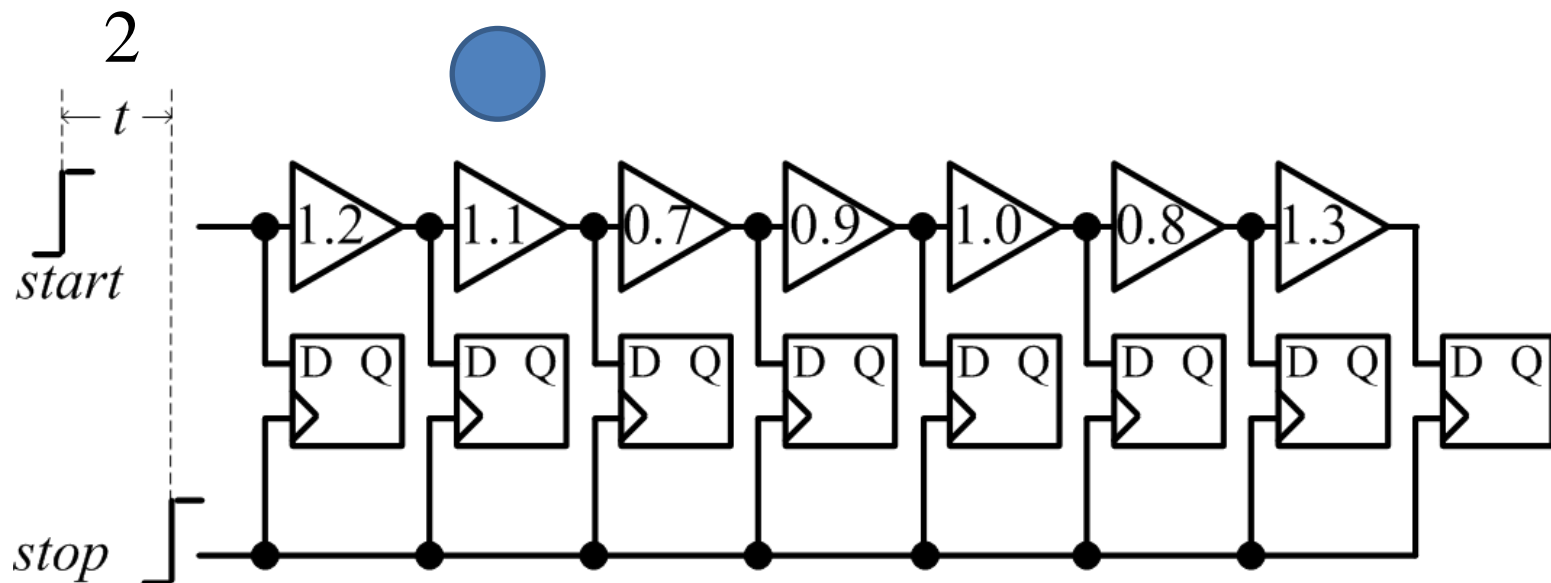


$t$	TDC Code	$t$	TDC Code
$0.0 < t < 1.0$	10000000	$4.0 < t < 5.0$	11111000
$1.0 < t < 2.0$	11000000	$5.0 < t < 6.0$	11111100
$2.0 < t < 3.0$	11100000	$6.0 < t < 7.0$	11111110
$3.0 < t < 4.0$	11110000	$7.0 < t$	11111111



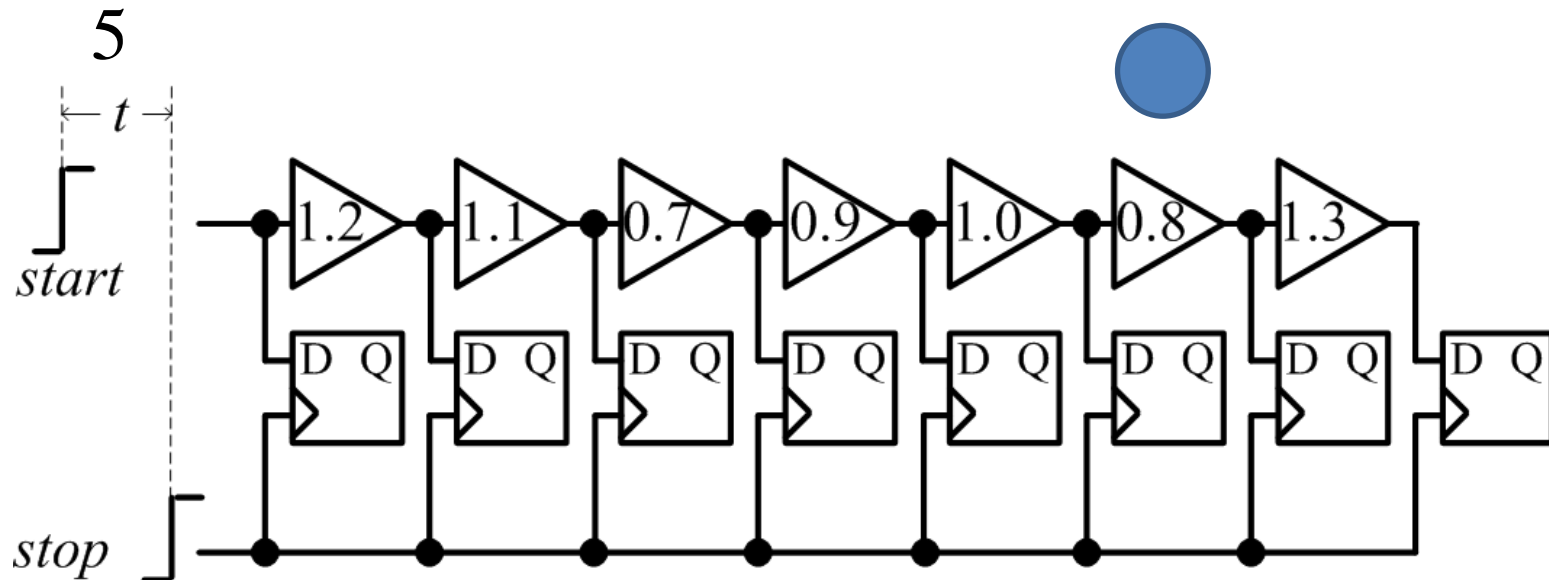
# Basics of stochastic calibration

- Stochastic Calibration
  - ➔ Applied Histogram Method
- Stochastic Time Interval is launched from
- *start* and *stop* input



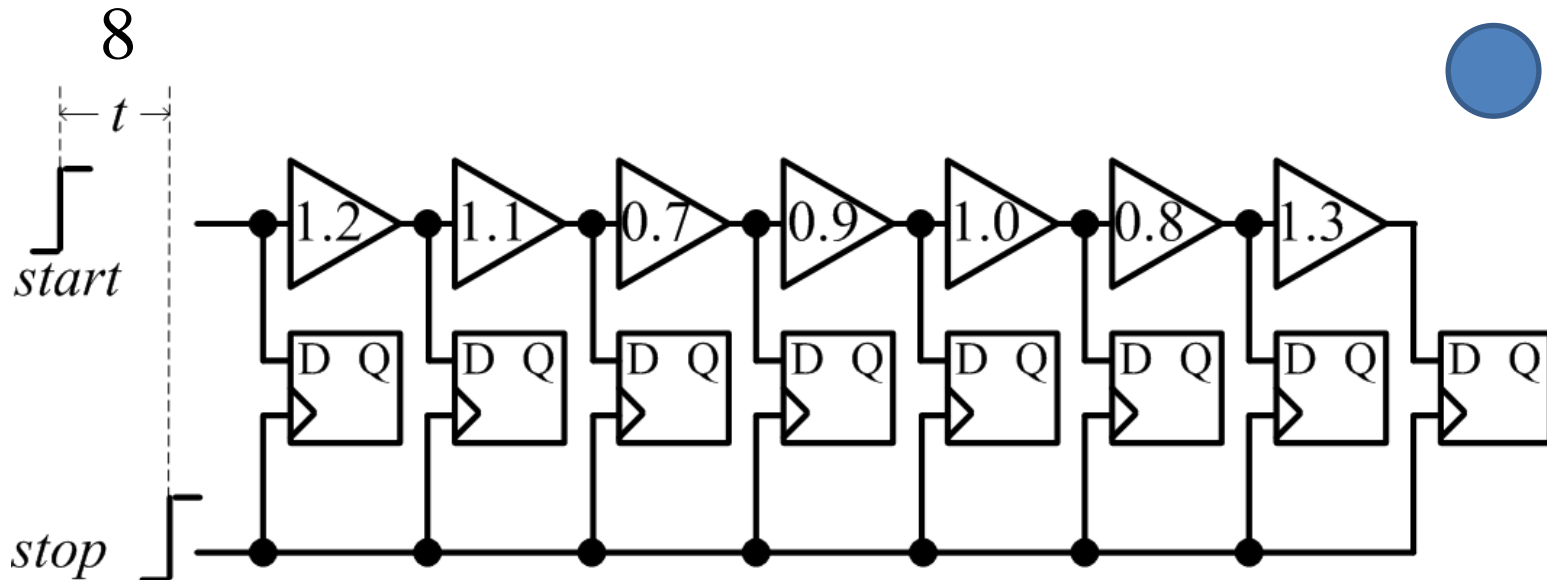
# Basics of stochastic calibration

- Stochastic Calibration
  - ➔ Applied Histogram Method
- Stochastic Time Interval is launched from
- *start* and *stop* input



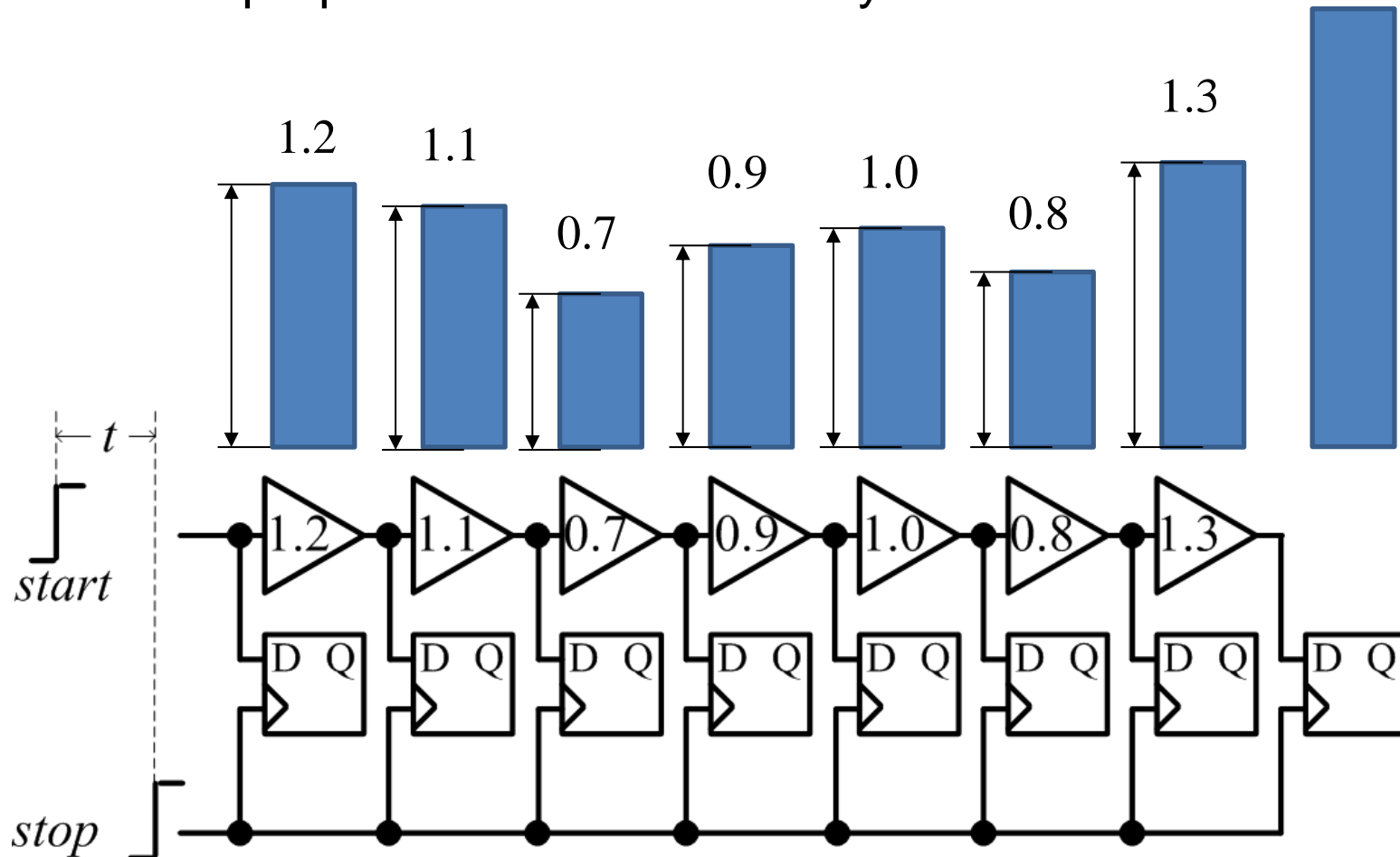
# Basics of stochastic calibration

- Stochastic Calibration
  - ➔ Applied Histogram Method
- Stochastic Time Interval is launched from
- *start* and *stop* input



# Basics of stochastic calibration

- When Distribution of time interval is uniform
- Each length of each bin is convergent in proportion to relative delay of each buffer



# Basics of stochastic calibration 2

- Time interval following uniform dist.



- Two ring oscillators with no correlation



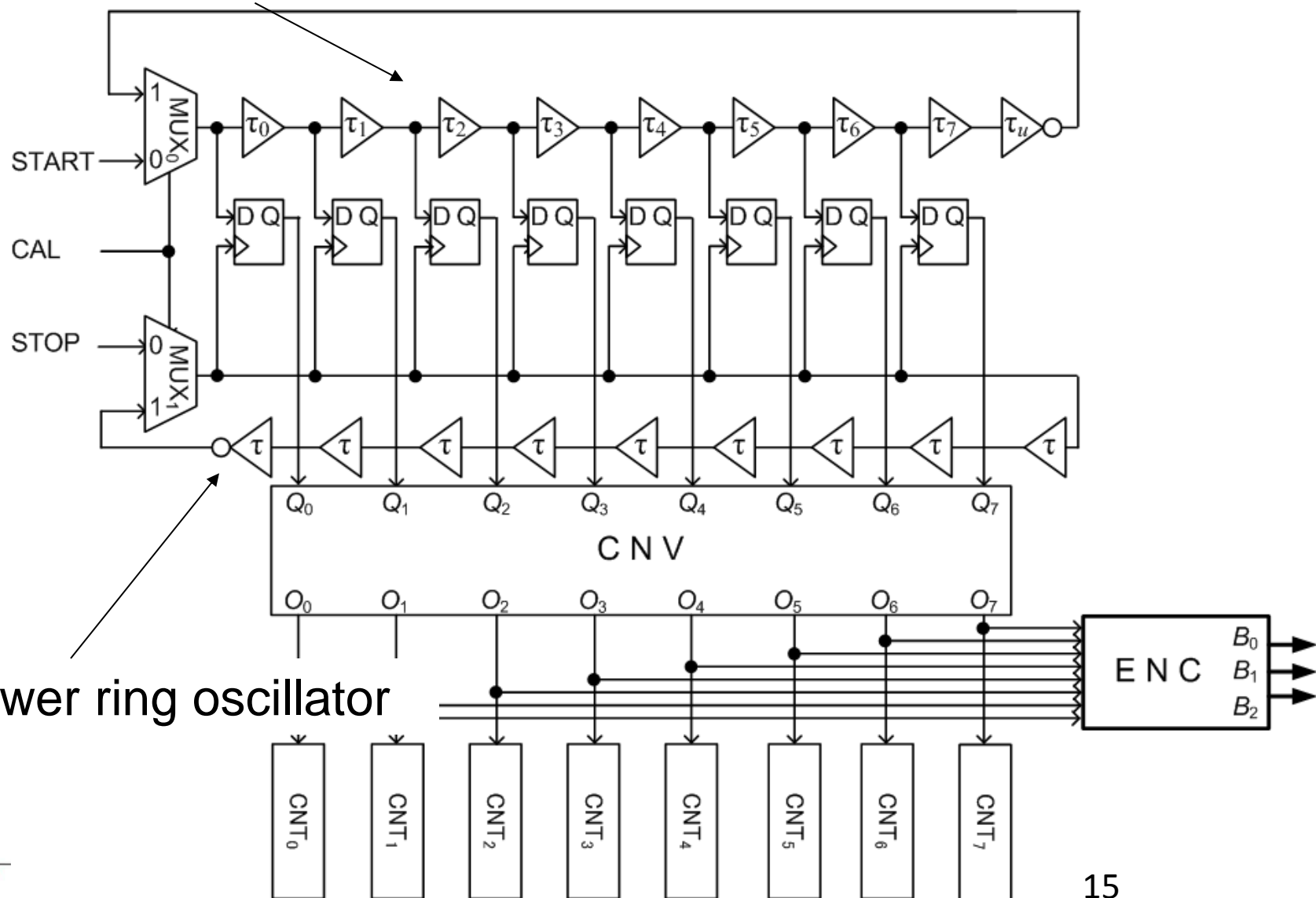
- Generate time interval following uniform dist. with low extra area



- Apply two ring oscillators as generator of time interval

# Stochastic calibration architecture [10]

## Upper ring oscillator



## Lower ring oscillator

# Calibration and design parameters



- Calibration Parameters
  - Probability of convergence
  - Time required for convergencedepend on
- Design Parameters
  - Cycles of ring oscillators
  - Number of stages
  - Phase difference of ring oscillators





# Aim of study



- For top-down design of calibration
- designer need relation between calibration parameters and design parameters



- Analyze relation between calibration parameters and design parameters to get **guideline of calibration design**



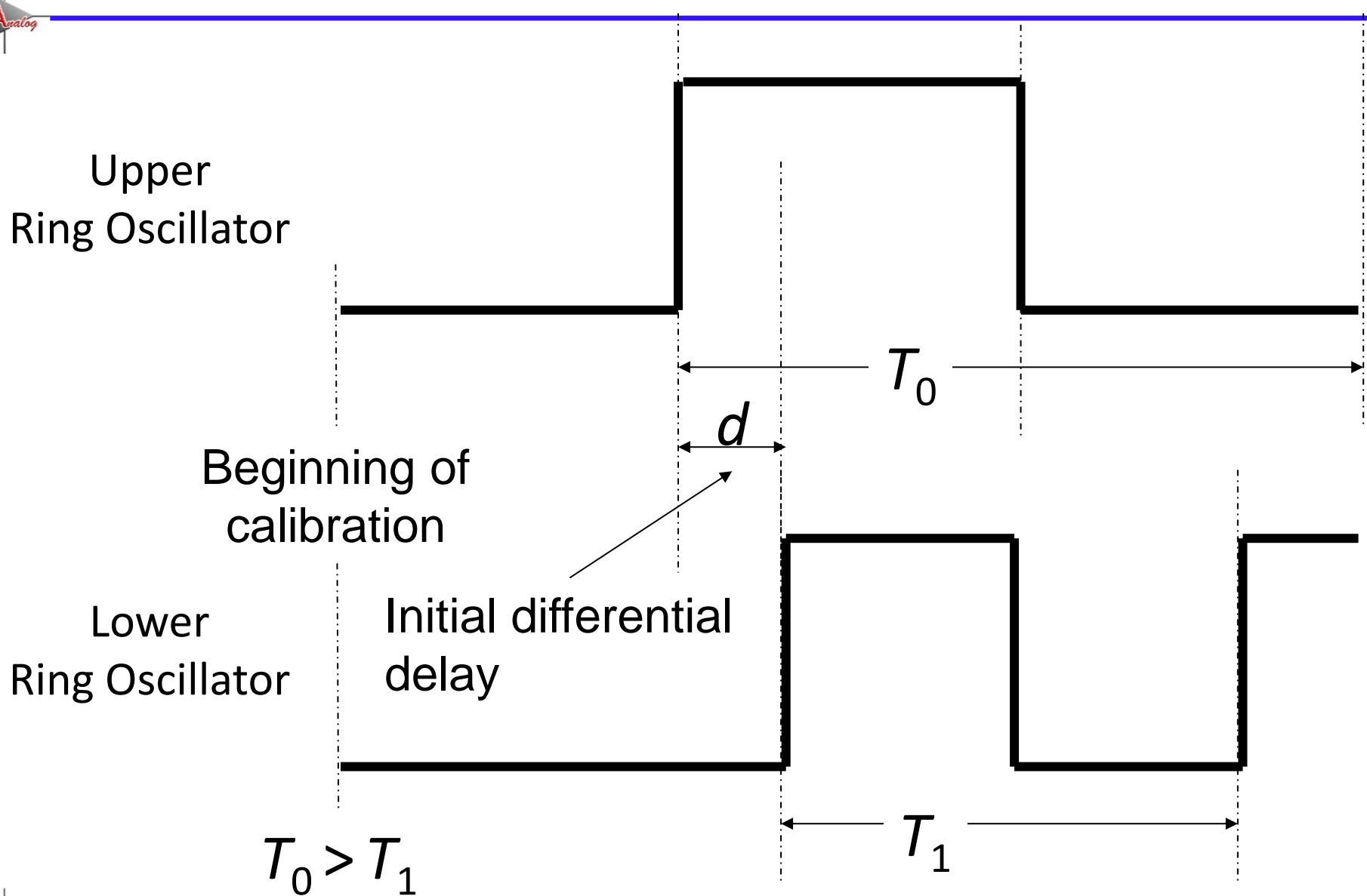
# Contents



- Background
  - Abstract
  - TDC
  - Abstract of Stochastic Calibration
  - Aim of Study
- **Preliminaries for Simulation**
- Simulation Results
- Conclusion



# Definition of cycles of two ring oscillators



# Definition of DNL

$$dnl_{ij} = \frac{T_i}{\sum_{i=1}^{N_{STG}-2} T_i} - \frac{b_{ij}}{\sum_{i=1}^{N_{STG}-2} b_{ij}}$$

$$DNL_j = \max(|dnl_{1j}|, \dots, |dnl_{(N_{MEAS}-2)j}|)$$

$dnl_{ij}$ : differential non-linearity error of  $i$ -th stage after  $j$ -th sampling

$DNL_j$ : differential non-linearity error after  $j$ -th sampling

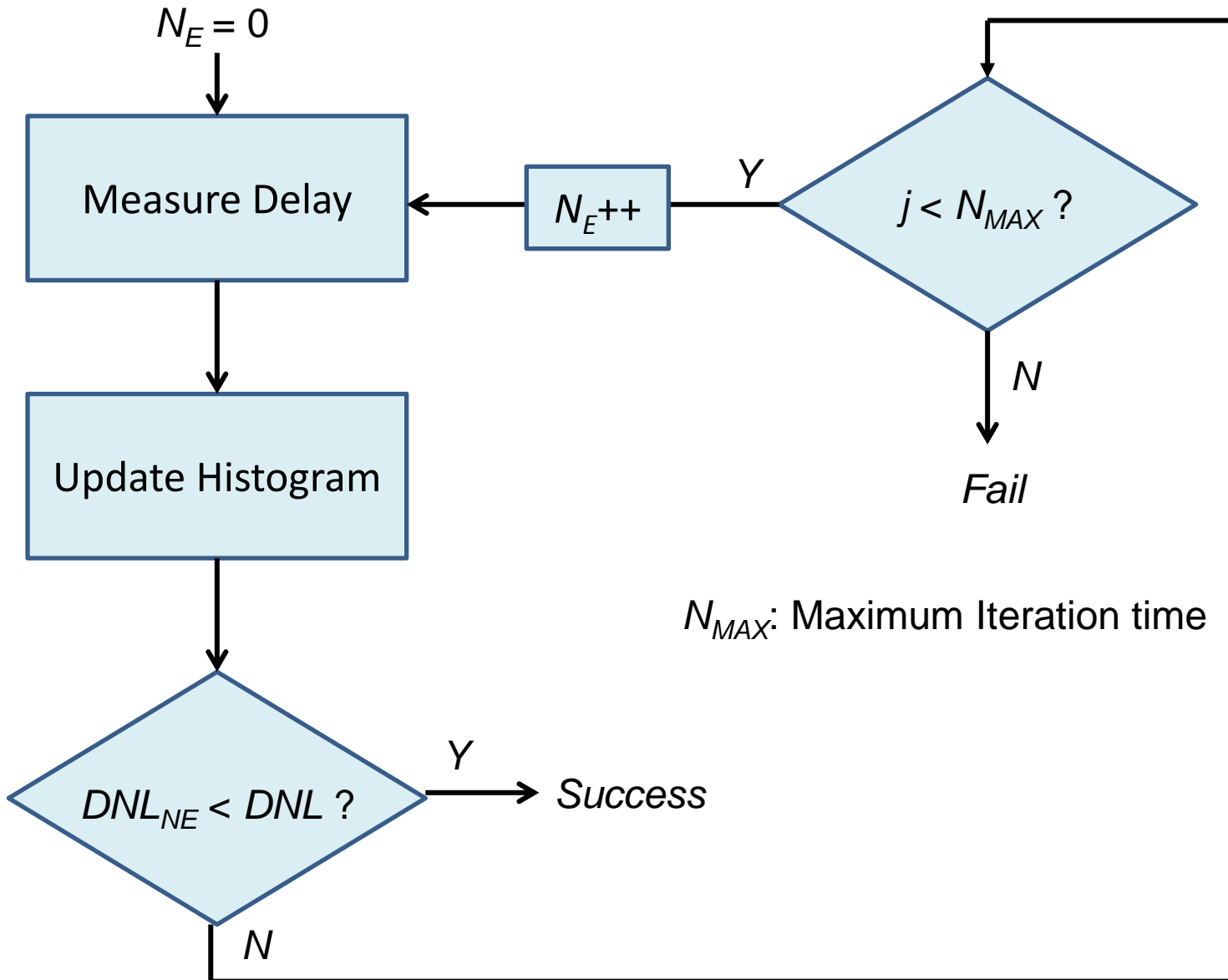
$T_i$ : Delay of buffer of  $i$ -th buffer

$b_{ij}$ : Length of bin of  $i$ -th stage after  $j$ -th sampling

# Definition of required measurement for convergence

- $N_E(TDC, T_0, T_1, d, DNL)$  : Number of required measurement for convergence of TDC within target DNL when cycles of upper and lower ring oscillator are  $T_0$  and  $T_1$ .

# Calculation of $N_E$



# Definition of convergent probability

- Convergent probability  $P_E(DNL)$ : Probability of success of calibration within a pre-defined error DNL when calibration is performed multiple times

$$P_E(DNL) = N_{SCAL} / N_{CAL} \times 100.0$$

$N_{SCAL}$ : Times of which calibration is success

$N_{CAL}$ : Execution times of calibration

# Definition of prime cycles

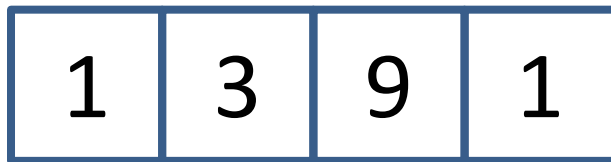
- A prime cycle  $c$  is defined as follows

$$c = p / 10^n$$

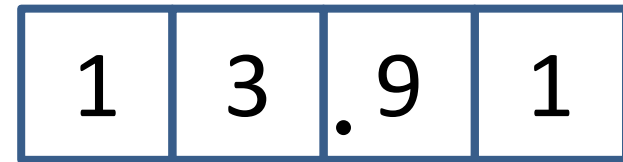
$p$ : prime number

$n$ : number of figures of the fraction part

$$n = 2$$



Prime number



Prime cycle



# Contents



- Background
  - Abstract
  - TDC
  - Abstract of Stochastic Calibration
  - Aim of Study
- Preliminaries for Simulation
- **Simulation Results**
- Conclusion



# Experiments

- Design Parameters

- Cycles of two ring oscillators ( $T_0$ ,  $T_1$ ) VS

- Convergent probability ( $P_E$ )

- Required measurement time to convergent ( $N_E$ )

- Initial differential delay ( $d$ ) VS

- Required measurement time to convergent ( $N_E$ )

- Bit length of each counter

# Experimental setup

- Buffer delay is set to 1 (unit delay)
- Varied 100 TDCs ( $TDC_0$ - $TDC_{99}$ ) are constructed
- Variation is 10% of buffer delay following gaussian distribution
- Maximum delay measurement times:  $N_{MAX}=2^{14}$
- Number of figure of fraction:  $n=2$

# Cycle of two ring oscillators ( $T_0$ , $T_1$ ) Spec.

- $T_0 > T_1$
- Evaluate in following three cases
  - Case 1 : Both  $T_0$  and  $T_1$  are prime cycles
  - Case 2 :  $T_0$  is multiple of  $T_1$
  - Case 3 : Arbitrary values of  $T_0$  and  $T_1$

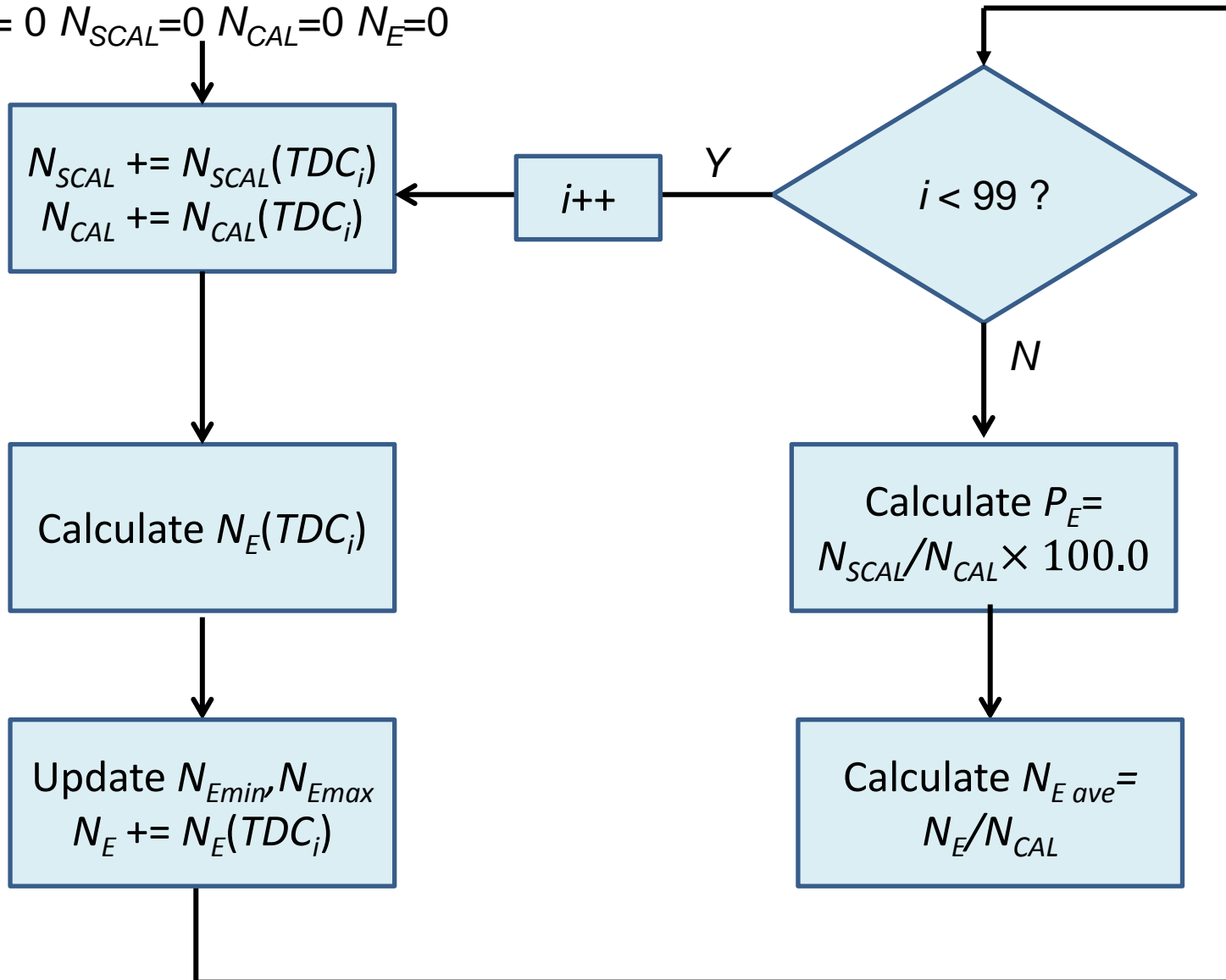
# Cycle of two ring oscillators ( $T_0$ , $T_1$ ) Spec. 2

- Parameter set up
  - $N_{STG}$  : 8 16 32 64 128
  - Upper ring oscillator cycle  $T_0$  is fixed to  $T_{p0}$
  - Lower ring oscillator cycle  $T_1$  is swept up from  $T_{min}$  to  $T_{max}$
  - $DNL$  1/1,024
  - Calibrate multiple times and calculate  $P_E$  and  $N_E$
  - Initial differential delay  $d$  0

$N_{STG}$	$T_{min}$	$T_{max}$	$T_{p0}$
8	2	12	11.93
16	2	18	17.89
32	2	36	35.93
64	2	68	67.93
128	2	132	131.87

# Simulation Sequence

$i = 0$   $N_{SCAL} = 0$   $N_{CAL} = 0$   $N_E = 0$



# Cycle of two ring oscillators ( $T_0$ , $T_1$ ) Spec. 3

- Convergent probability  $P_E$  spec.

Case	$N_{STG}$				
	8	16	32	64	128
Case 1	100.0	100.0	100.0	100.0	100.0
Case 2	0.0	0.0	0.0	0.0	0.0
Case 3	38.6	43.9	56.4	75.8	78.5

# Cycle of two ring oscillators ( $T_0$ , $T_1$ ) Spec. 4

- Required Measurement Time  $N_E$  spec.

$N_E$	Case	$N_{STG}$				
		8	16	32	64	128
$N_{Emin}$	Case 1	367	517	605	772	802
	Case 2	0	0	0	0	0
	Case 3	359	464	640	731	984
$N_{Eave}$	Case 1	633.1	1,060.0	1,509.6	1,976.3	2,323.3
	Case 2	0	0	0	0	0
	Case 3	648.7	1,052.4	1,303.8	1,724.8	1,911.7
$N_{Emax}$	Case 1	798	1,597	3,178	6,324	10,000
	Case 2	0	0	0	0	0
	Case 3	3,427	10,000	10,000	6,381	10,000



# Initial differential delay specification



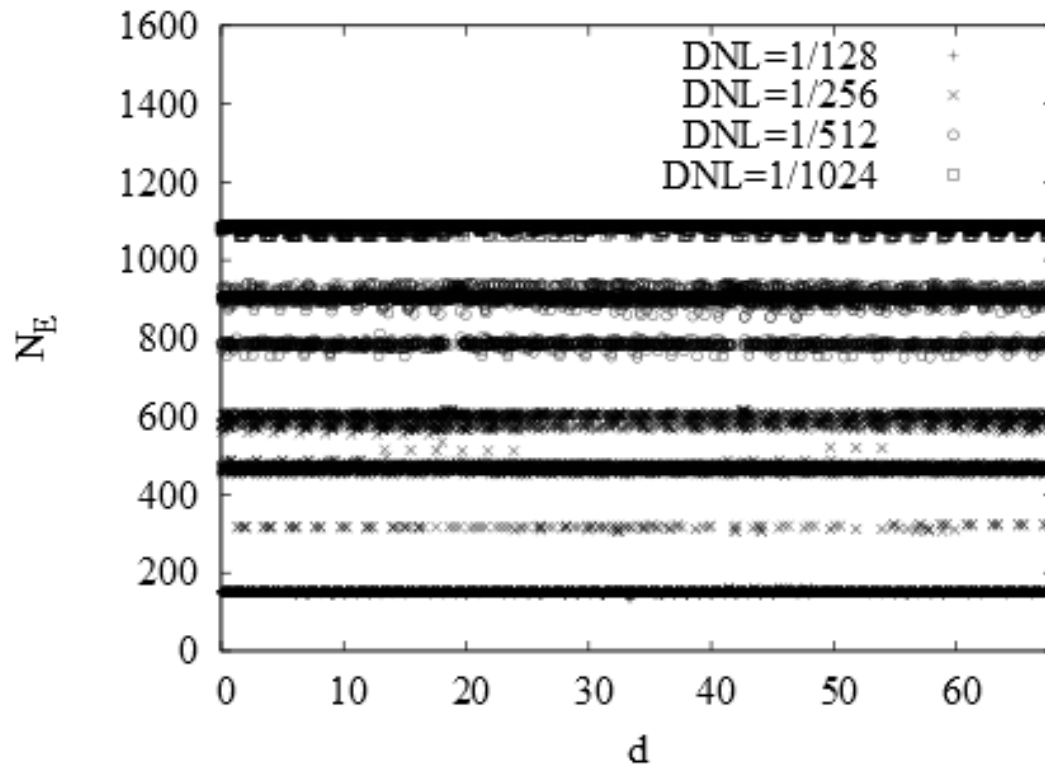
- Parameter setup
  - $T_0 \rightarrow T_{p0}$ ,  $T_1 \rightarrow 2.11$  fixed
  - $d$  is swept up from 0 to  $T_0$
  - $N_{Eave}$  is calculated
  - $DNL = 1/128, 1/256, 1/512, 1/1,024$



# Initial differential delay specification



- Result




# Bit length of each counter

- Calculate bit length of each counter with the following equation assuming 10% variation
- DNL 1/1,024

$$L_{CNT} = \log_2 \left[ 1.1 \times N_E / N_{STG} \right]$$

$N_{STG}$	8	16	32	64	128
$L_{CNT}$	9	10	9	7	7

# Conclusion

- 
- Analyze the relation between calibration parameters and design parameters
  - Analyze not with mathematical analysis but with computer simulation → higher accuracy
  - Get the following two conclusions
    - Both of the frequencies of the two ring oscillators should be the prime frequencies
    - When both of the frequencies are the prime frequencies, we estimate the required number of the times of measurement from the target DNL.

# Questions

- Q. プロセスばらつきを考慮しなかったのはなぜか？
- A. 本研究は設計者への設計ガイドラインを目的としており、特に設計パラメータとキャリブレーション特性の関係について研究を行っているため.