

Derivation of Loop Gain from Output Impedances in DC-DC Buck Converter

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JAPAN



Outline

- Research Background
- Purpose of This Work
- Derivation of Proposed Method
- Simulation and Measurement Result
- Summary

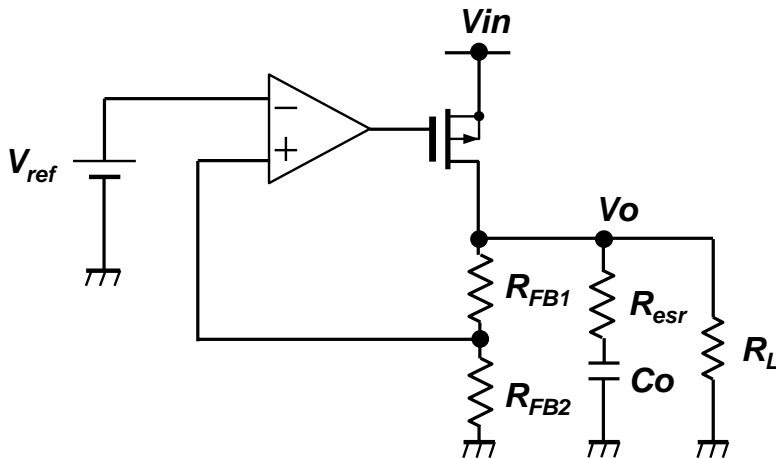
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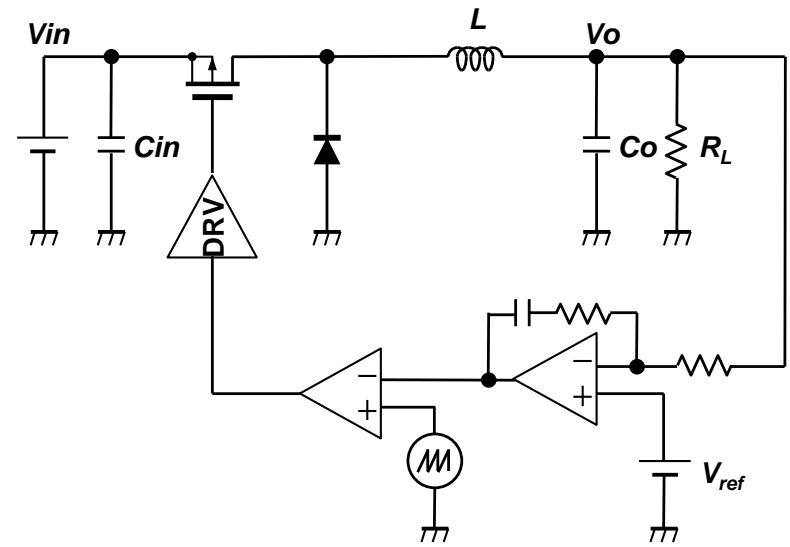
Research Background(1)

- There are a lot of applications using negative feedback systems.

Low Drop Out Regulator



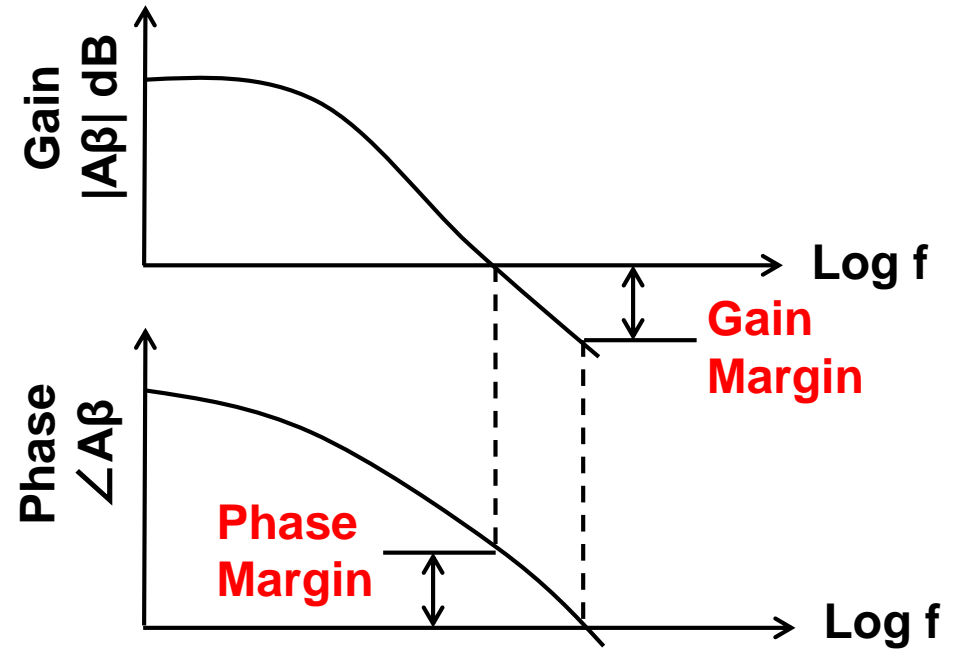
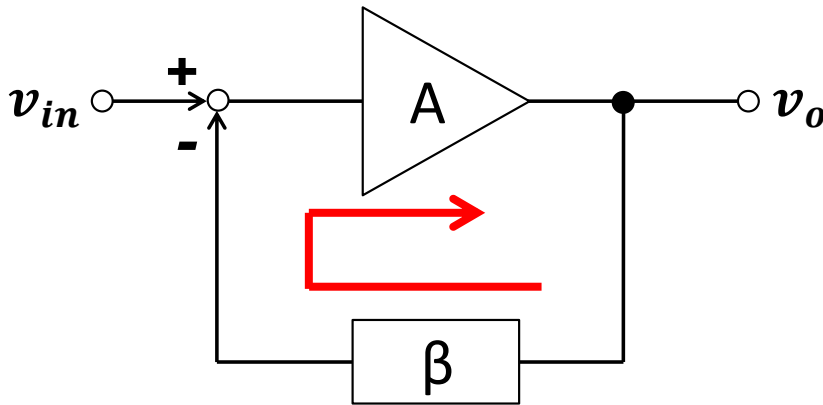
Switching Regulator



Research Background(2)

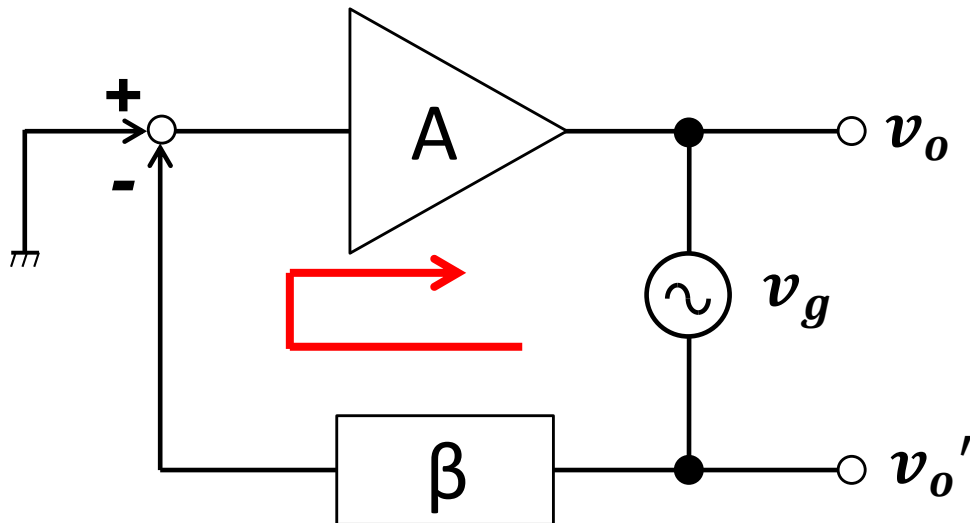
- Measurement of the loop gain is important to evaluate the stability of the negative feedback system.

Loop Gain $T = A\beta$



Research Background(3)

- Conventional loop gain measurement method

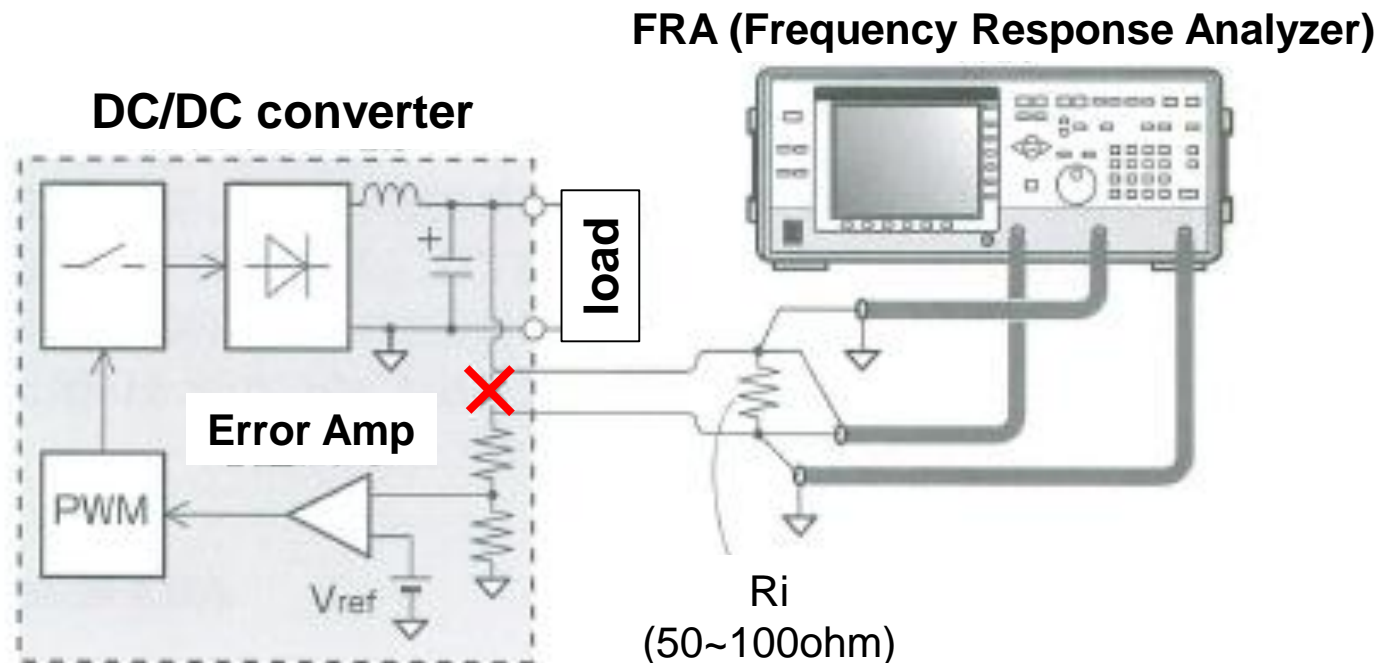


Loop Gain T

$$|T| = \frac{v_o}{v_o'} = A\beta$$

Disadvantage of Conventional Method

- It is necessary to inject a voltage signal into the feedback loop by breaking the loop.
- If the control circuits are implemented on an IC, this method is NOT applicable.



Outline

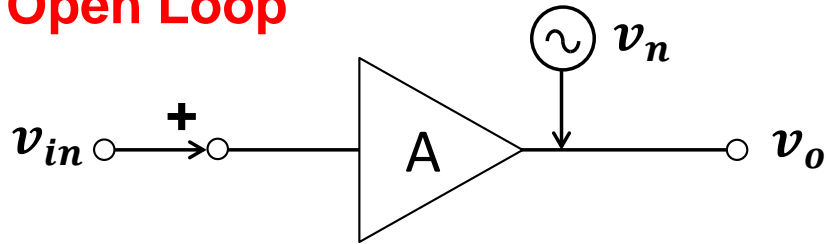
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Purpose of This Work

- To measure the loop gain
without breaking the feedback loop.
- To develop a new method
to derive the loop gain from output impedances
in dc-dc buck converter.
- To demonstrate the proposed method
by simulation and experimental evaluations.

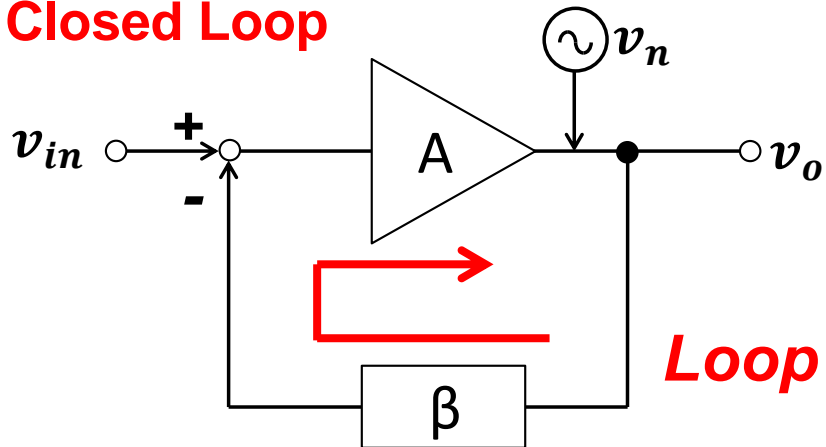
Keypoint of Proposed Method

Open Loop



$$v_o = Av_{in} + v_n$$

Closed Loop



$$v_o = \frac{1}{\beta} \cdot \frac{T}{1+T} v_{in} + \frac{v_n}{1+T}$$

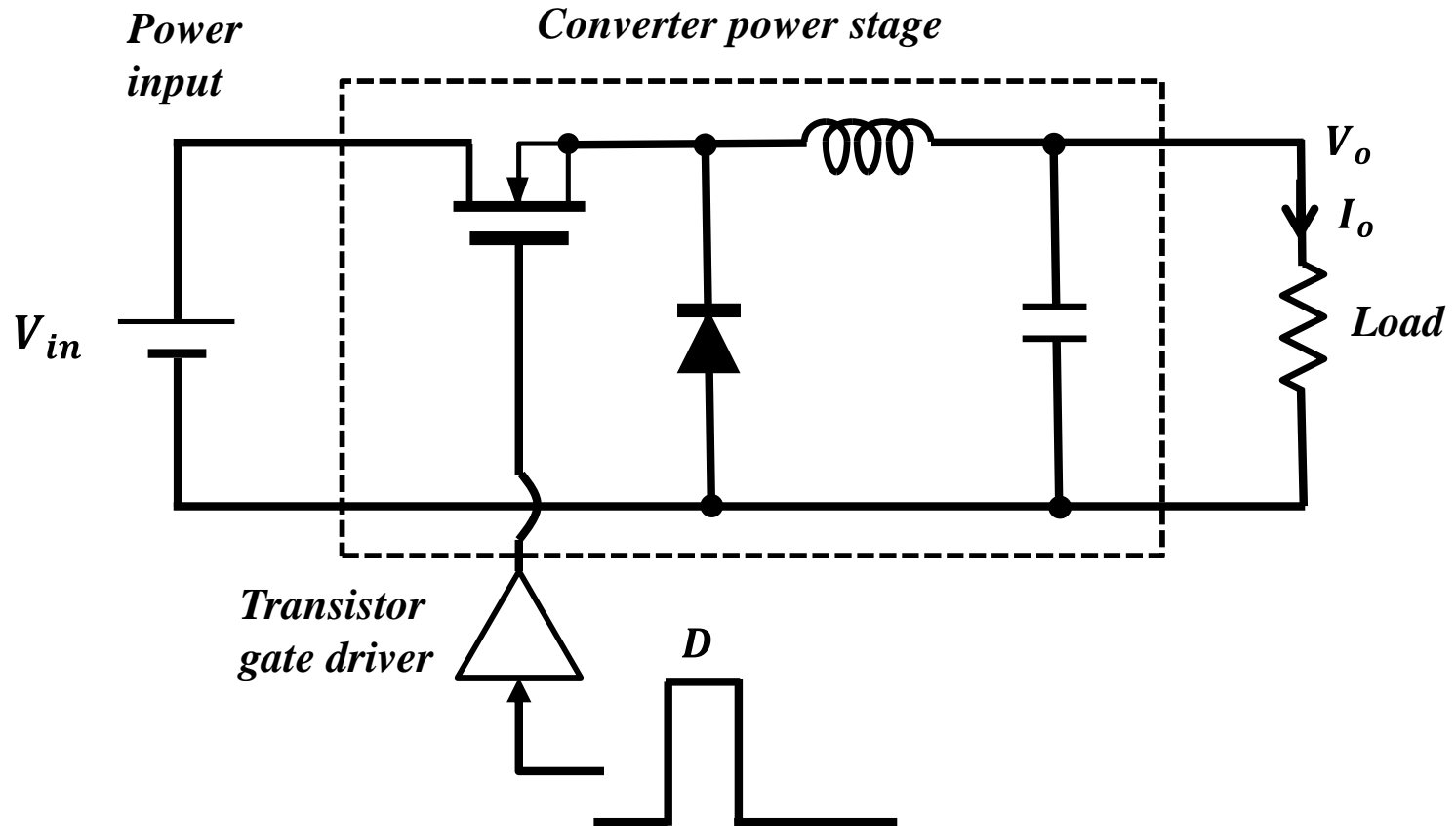
Loop Gain $T = A\beta$

Negative feedback reduces the noise by a factor of $1/(1+T)$.
This theory can be applied to loop gain measurement .

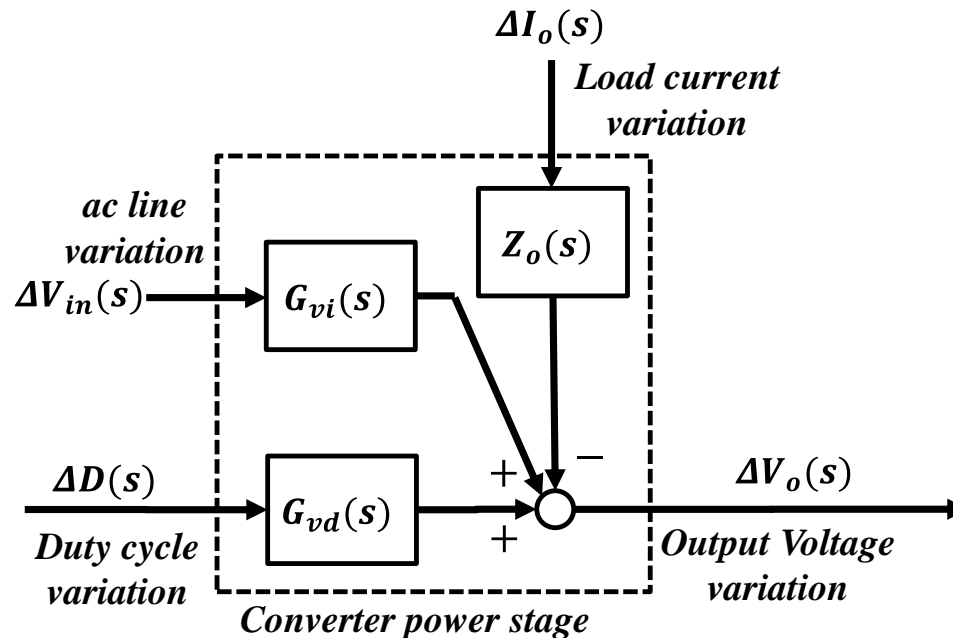
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DC-DC Buck Converter Circuit in Open Loop



Functional Block Diagram in Open Loop

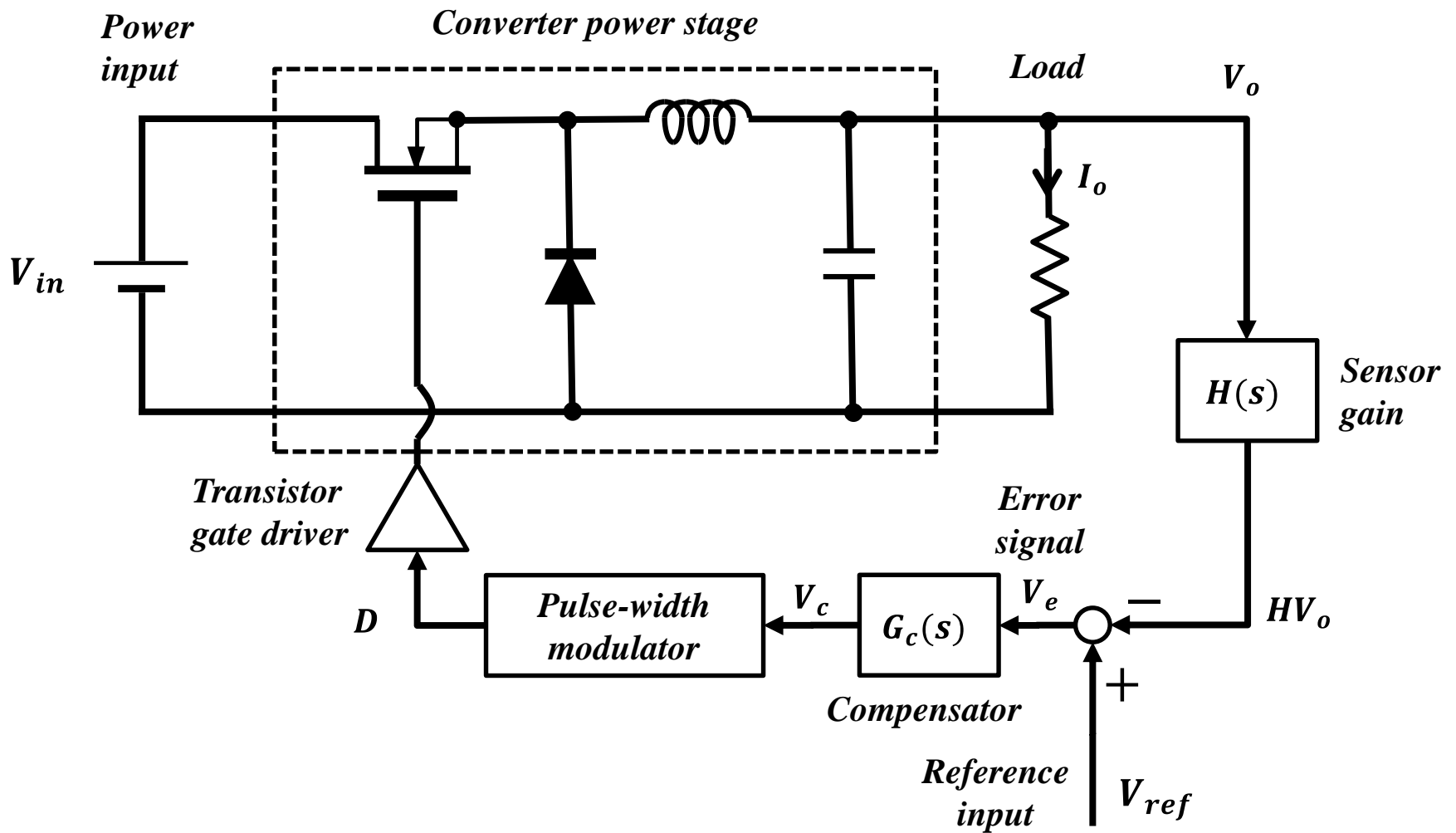


$$\Delta V_o = G_{vd}\Delta D + G_{vi}\Delta V_{in} - Z_o\Delta I_o$$

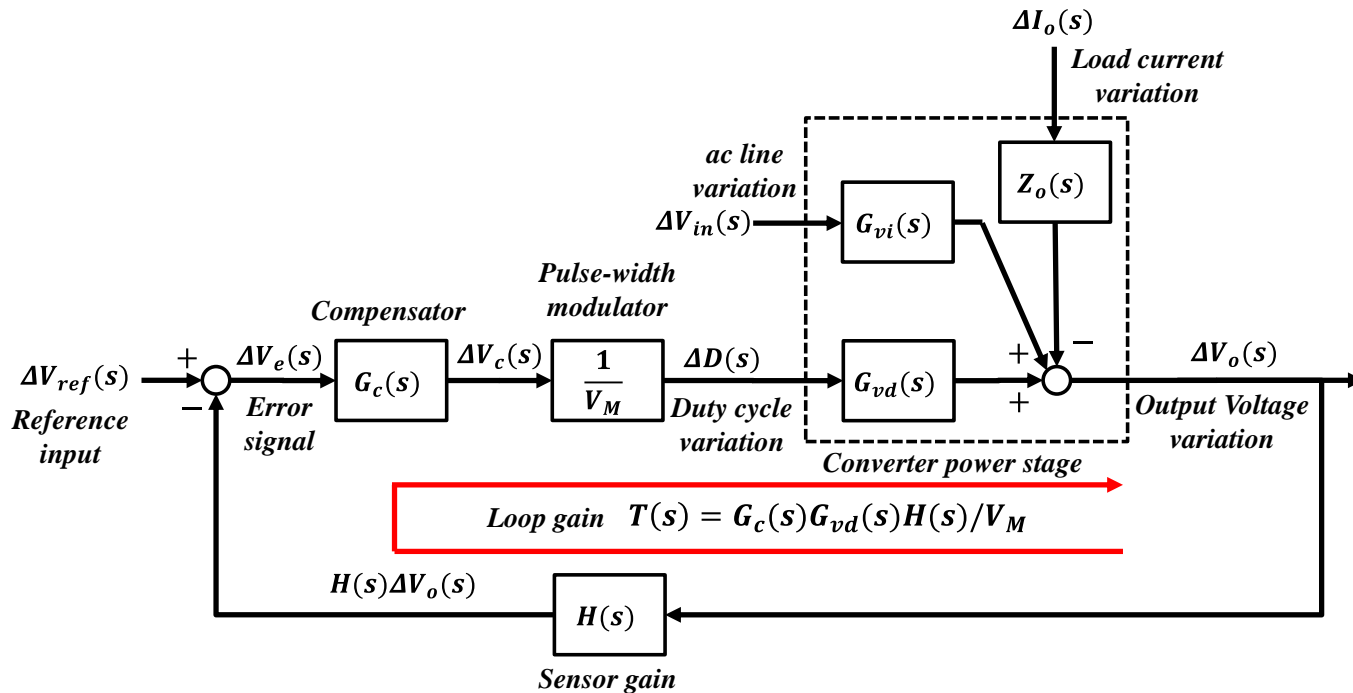
$$Z_o \equiv - \left. \frac{\Delta V_o}{\Delta I_o} \right|_{\Delta D=0, \Delta V_{in}=0}$$

**converter output impedance
in open loop**

DC-DC Buck Converter Circuit in Closed Loop



Functional Block Diagram in Closed Loop



$$\Delta V_o = \frac{1}{H} \frac{T}{1+T} \Delta V_{ref} + \frac{G_{vi}}{1+T} \Delta V_{in} - \frac{Z_o}{1+T} \Delta I_o$$

$$Z_{oc} \equiv - \left. \frac{\Delta V_o}{\Delta I_o} \right|_{\Delta V_{ref}=0, \Delta V_{in}=0} = \frac{Z_o}{1+T} \quad \text{converter output impedance in closed loop}$$

Derivation of Proposed Method

$$Z_{oc}(s) = \frac{Z_o(s)}{1 + T(s)} \quad \Rightarrow \quad T(s) = \frac{Z_o(s) - Z_{oc}(s)}{Z_{oc}(s)}$$

Magnitude of Loop Gain

$$20 \log_{10} |T| = 20 \log_{10} \left[\frac{|Z_o - Z_{oc}|}{|Z_{oc}|} \right]$$

Phase of Loop Gain

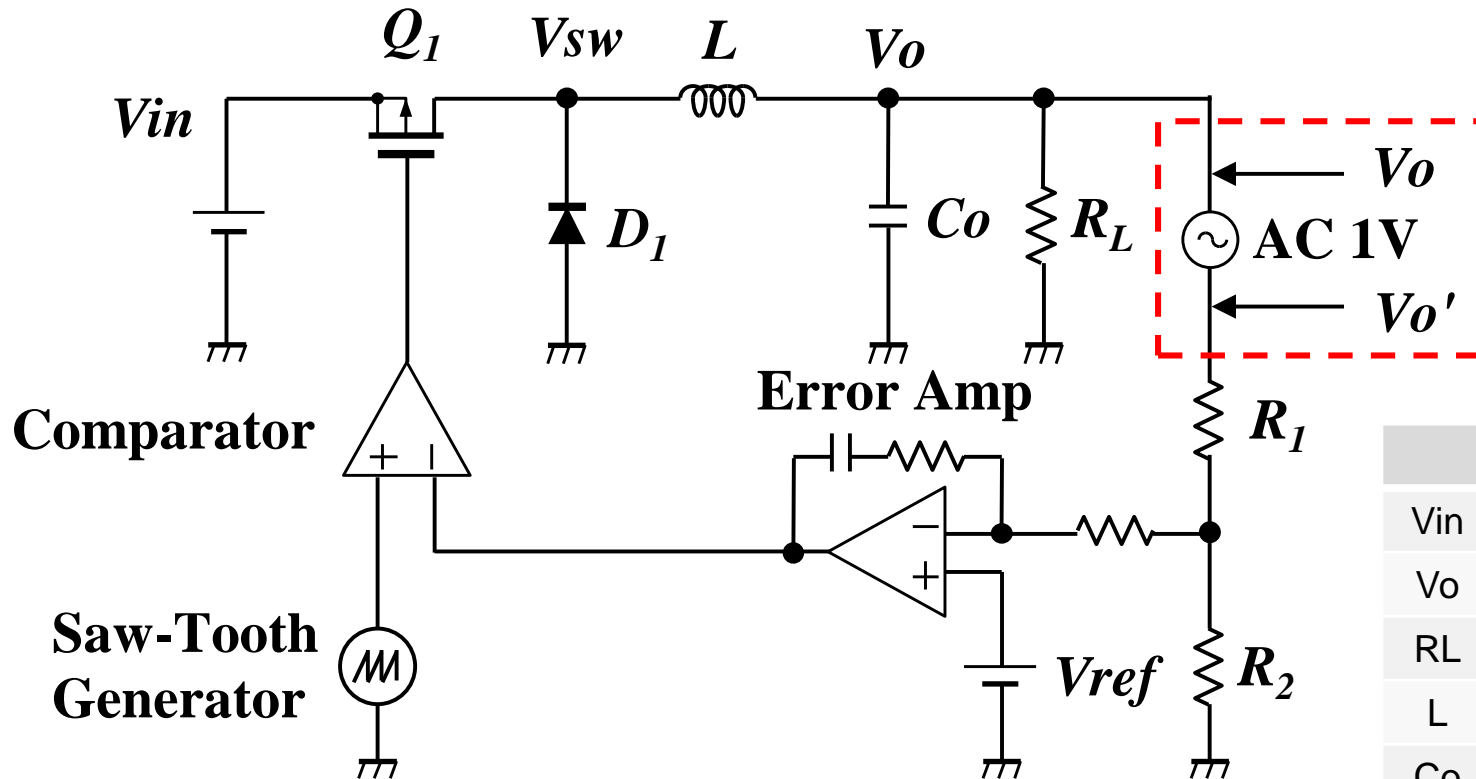
$$\arg(T) = \arg(Z_o - Z_{oc}) - \arg(Z_{oc})$$

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Simulation Circuits

Conventional

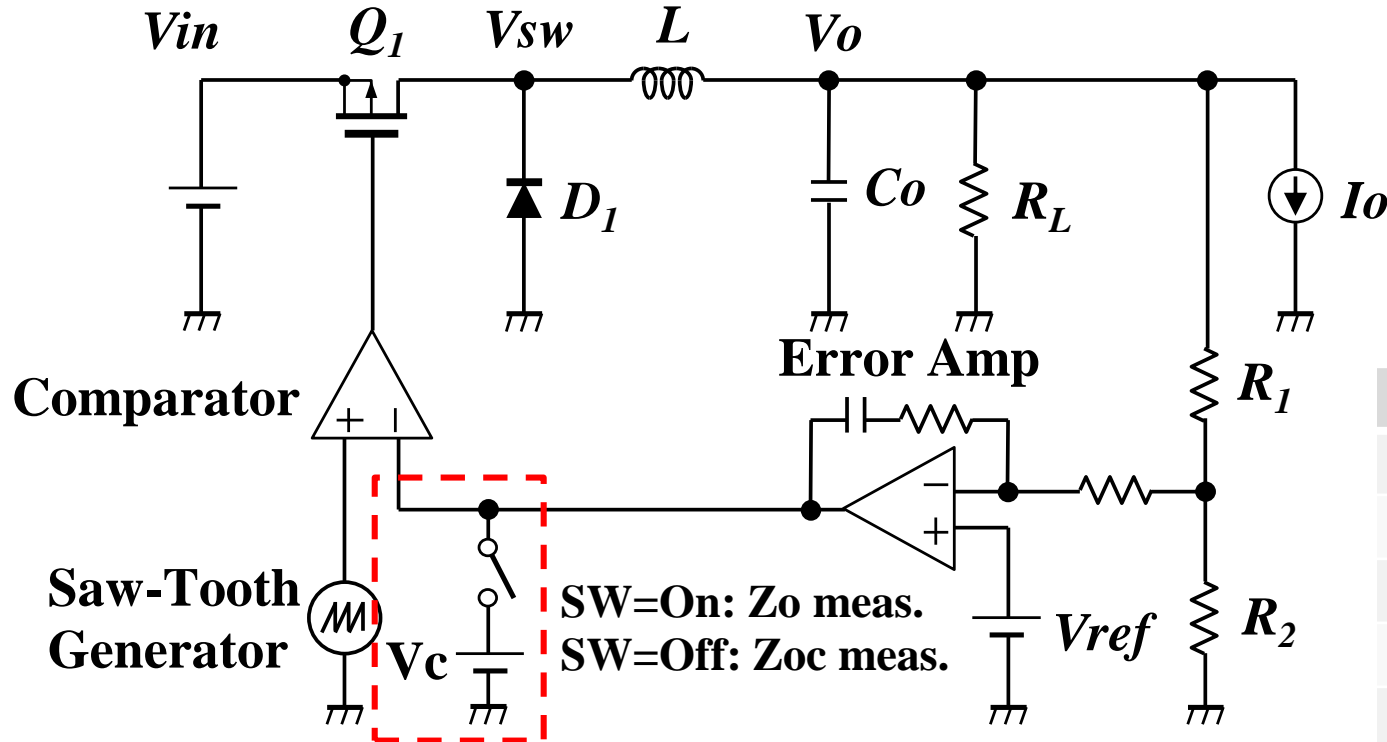


Parameter	
V_{in}	12V
V_o	5V
R_L	5Ω
L	120μH
C_o	1.2mF x 2 (ESR=40mΩ)

Loop Gain $T = V_o/V_o'$

Simulation Circuits

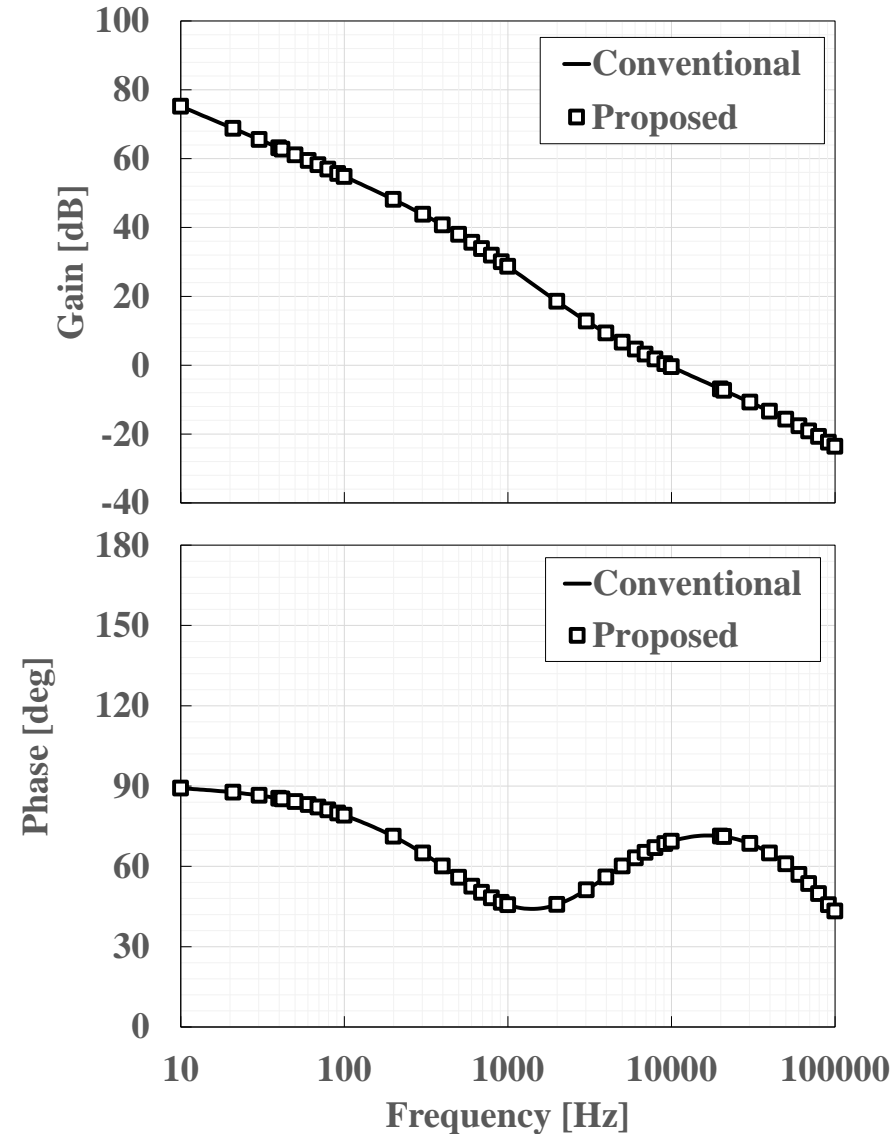
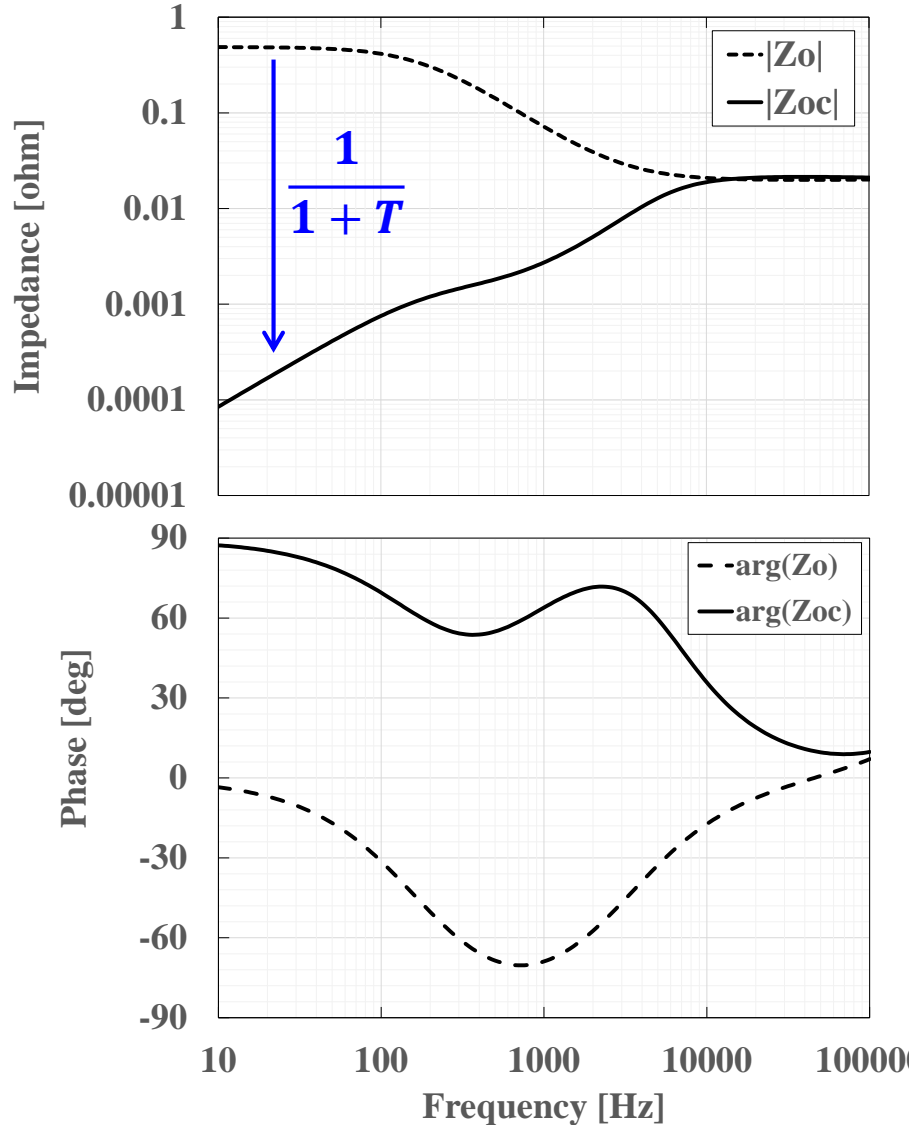
Proposed



Parameter	
V_{in}	12V
V_o	5V
R_L	5Ω
L	120uH
C_o	1.2mF x 2 (ESR=40mΩ)

$$\text{Loop Gain } T = (Z_o - Z_{oc}) / Z_{oc}$$

Simulation Results

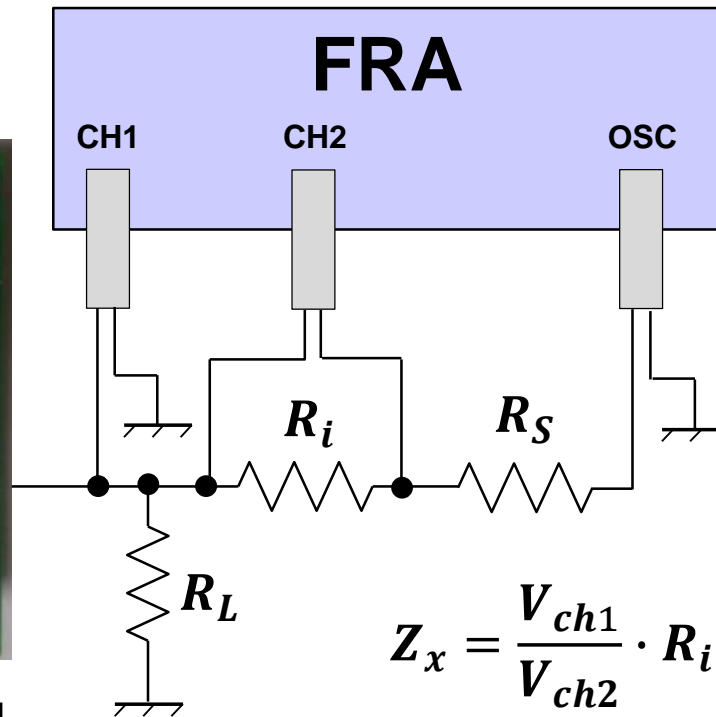


Experimental Setup

- IC:BD9329A (Rohm Semiconductor)
 - Synchronous buck converter with integrated FET
 - Switching frequency: 380kHz

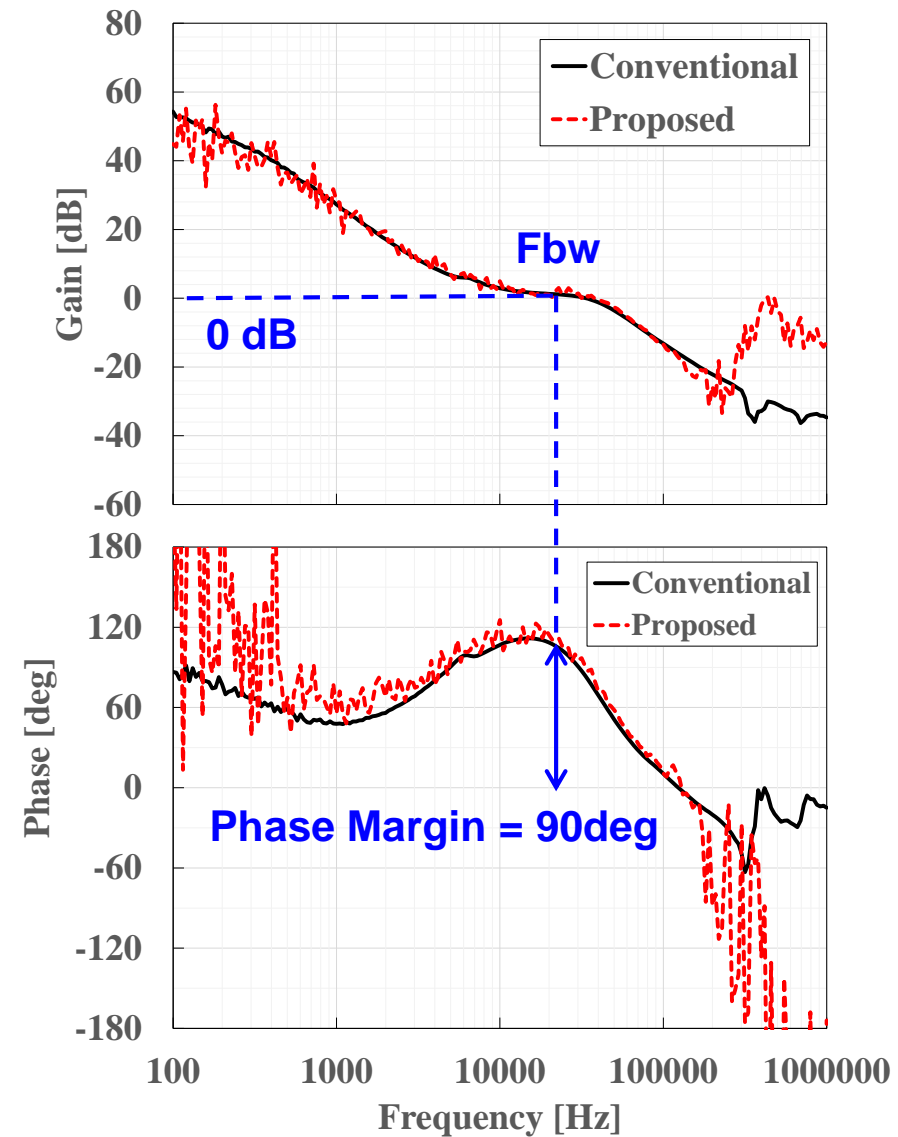
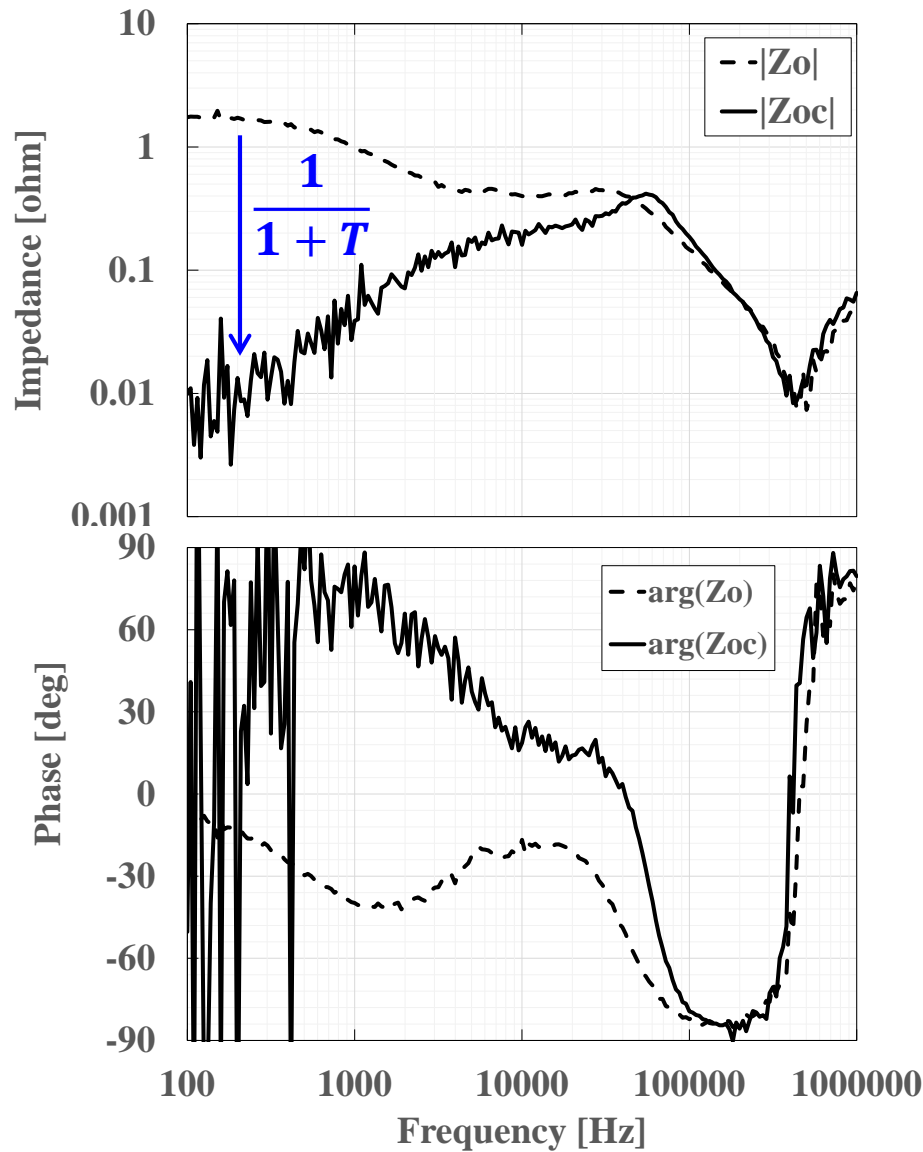


Evaluation board



Parameter	
Vin	12V
Vo	3.3V
RL	3Ω
L	10uH
Co	10uF x 2
Ri	1Ω
Rs	1kΩ

Experimental Results



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Summary

- We have proposed a method to derive the loop gain from the output impedances in dc-dc buck converter.
- We showed effectiveness of the proposed method with simulations and experiments of dc-dc buck converter.
- We found out that sufficient evaluation of phase margin and gain margin is possible.

Thank you for listening !!

Q & A

- Q1:主な用途は何か？
- A1:例えば、DC-DC電源、LDO、増幅回路に使用できる。この方法は負帰還回路を使用していれば、どんな回路でも応用可能です。
- Q2:どんなときにこの方法を使用するの？
- A2:テスト時を想定しています。フィードバックループが集積化されている場合は従来方法が使用できません。