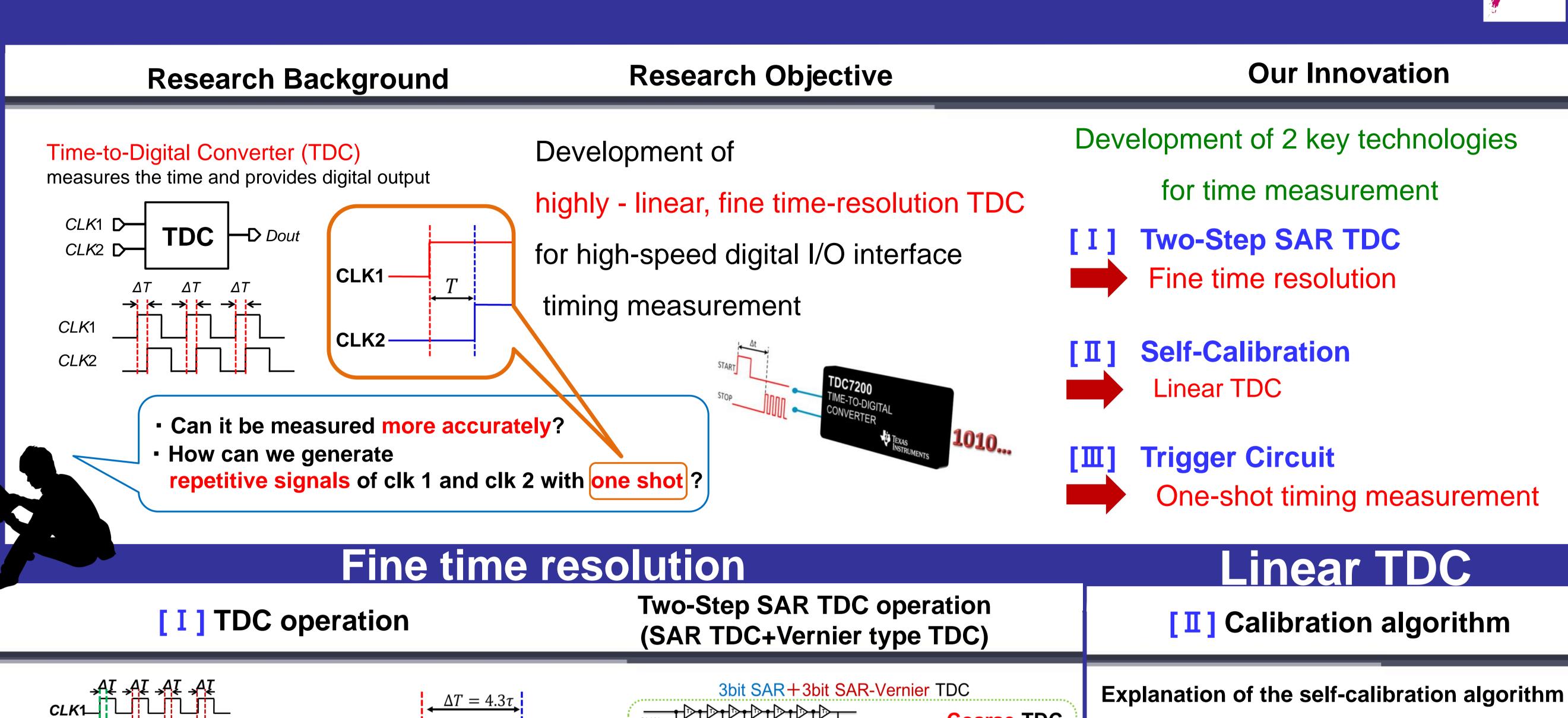
Introduction

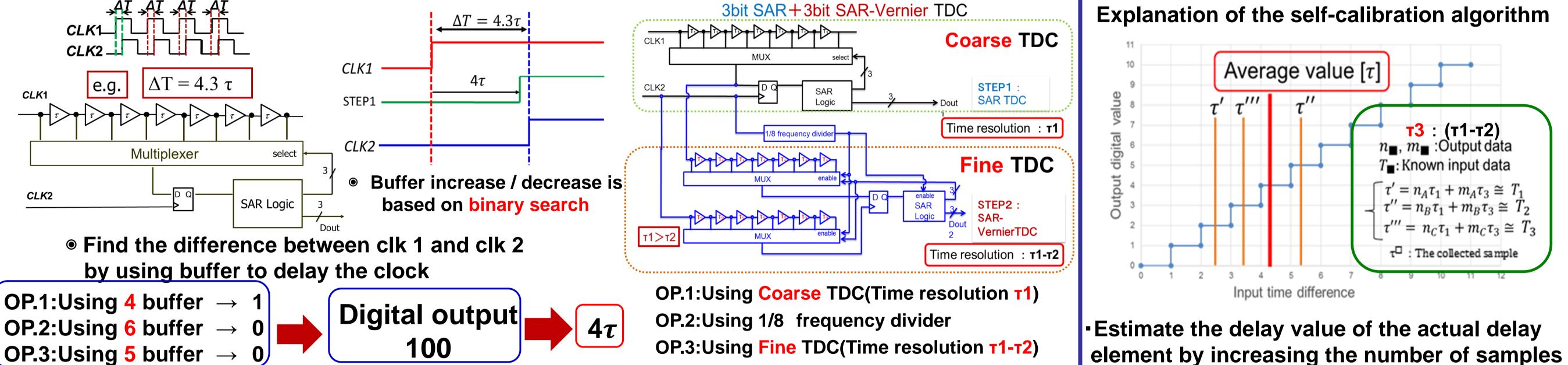


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Linear TDC

Measurement error of estimated value $[\tau_3]$



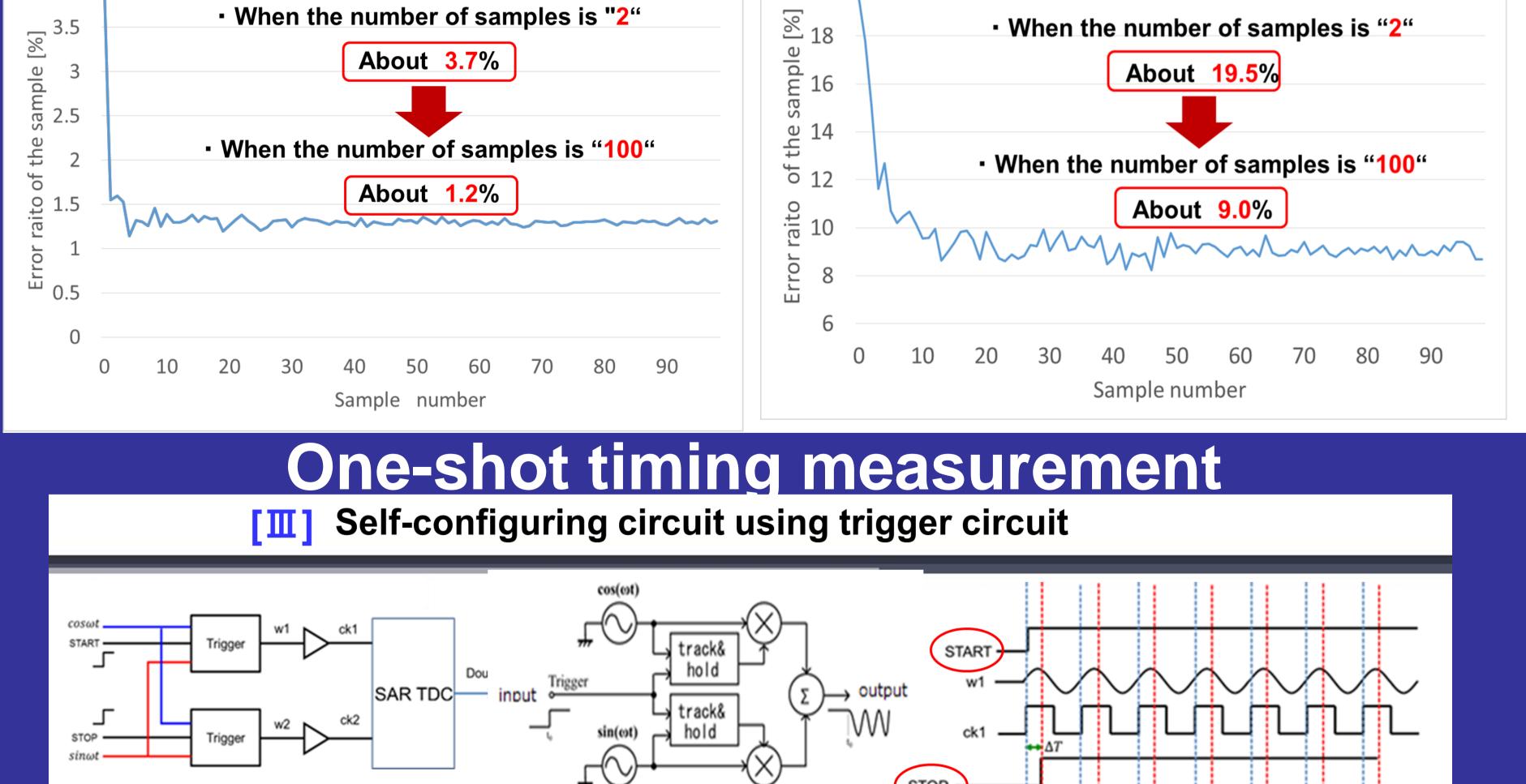
STEP (1)

Multiple **STEP**s are required

for TDC self-calibration

Repetitive time difference signal is generated

by one shot of START signal and STOP signal



trigger circuit

Vout= $\cos(\omega t)\cos(\omega t)+\cos(\omega t+\pi/2)\cos(\omega t+\pi/2)$

Vout= $\cos(\omega t) \cos(\omega t_0) + \sin(\omega t) \sin(\omega t_0)$

track-and-hold

track mode

·hold mode

 $=\cos^2(\omega t)+\sin^2(\omega t)$

=1 (一定の値)

 $=\cos(\omega(t-t_0))$

***** trigger time:t₀

Hold

Track

T / H circuit

 $V_C = V_{out}$

Track

T / H circuit

 $V_{in} = V_{out}$

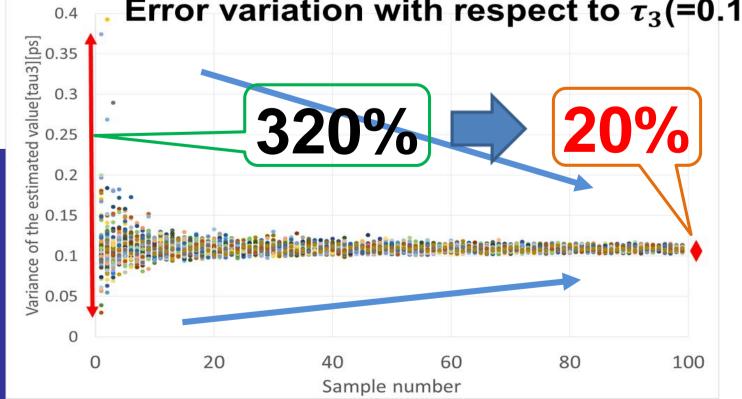
 τ_0

20

Measurement error of estimated value $[\tau_1]$

When the number of samples is "2"

Error variation with respect to τ_1 (=1.0) 36% Error variation with respect to τ_3 (=0.1)



 Increased reliability by increasing the number of samples Sufficient reliability!

References

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[3] Tektronics, Automatic RF Techniques Group 56th **Measurement Conference - Metrology and Test for RF** Telecommunications, Boulder, Colorado (Dec. 2000).