

Derivation of Loop Gain and Phase from Output Impedances in Analog Circuit with Negative Feedback

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Outline

- Research Background
- Purpose of This Work
- Derivation of Proposed Method
- Simulation and Measurement Result
- Summary

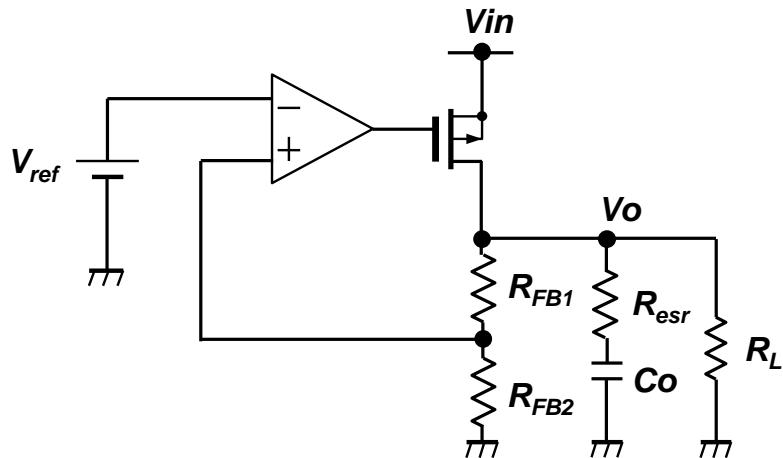
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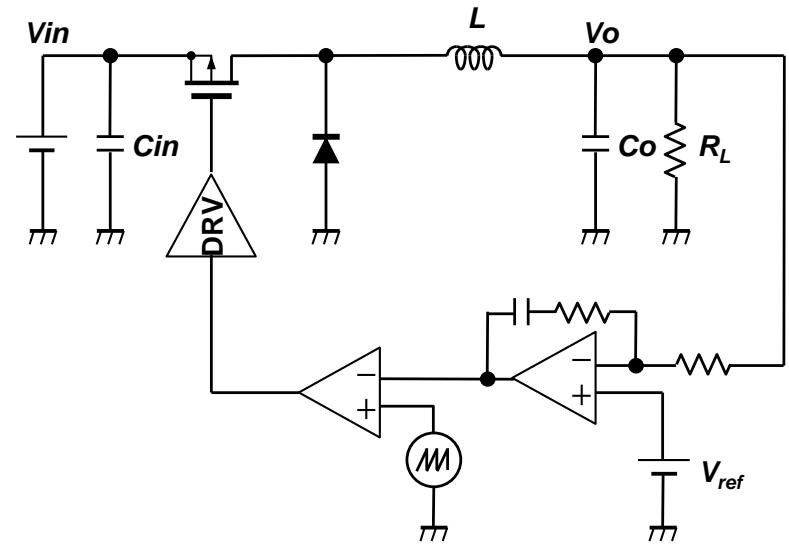
Research Background(1)

- There are a lot of applications using negative feedback systems.

Low Drop Out Regulator



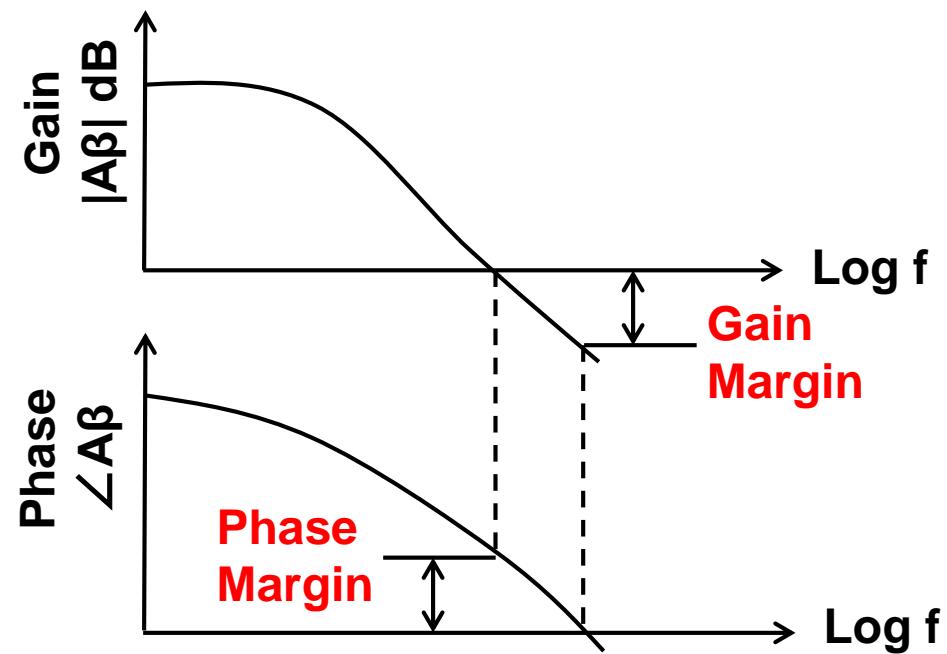
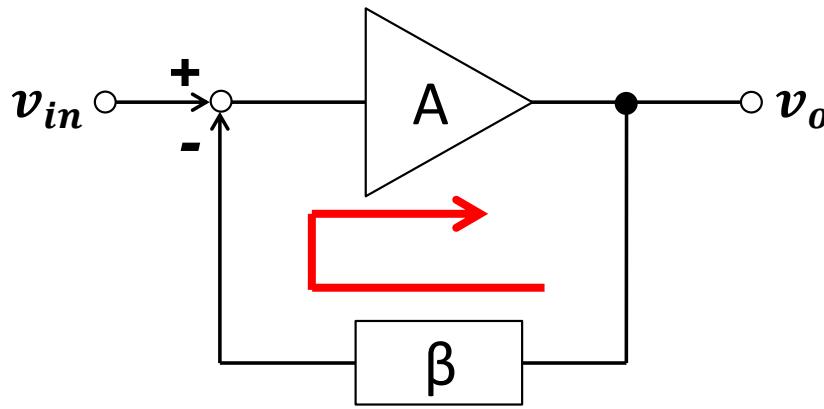
Switching Regulator



Research Background(2)

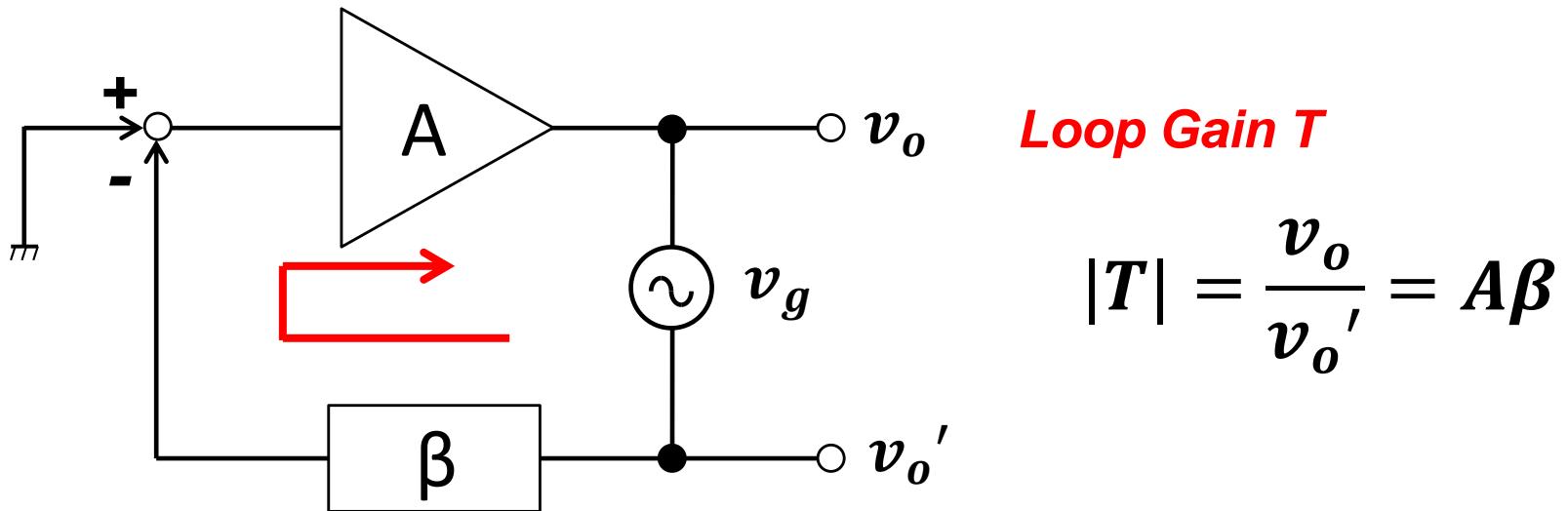
- Measurement of the loop gain is important to evaluate the stability of the negative feedback system.

$$\text{Loop Gain } T = A\beta$$



Research Background(3)

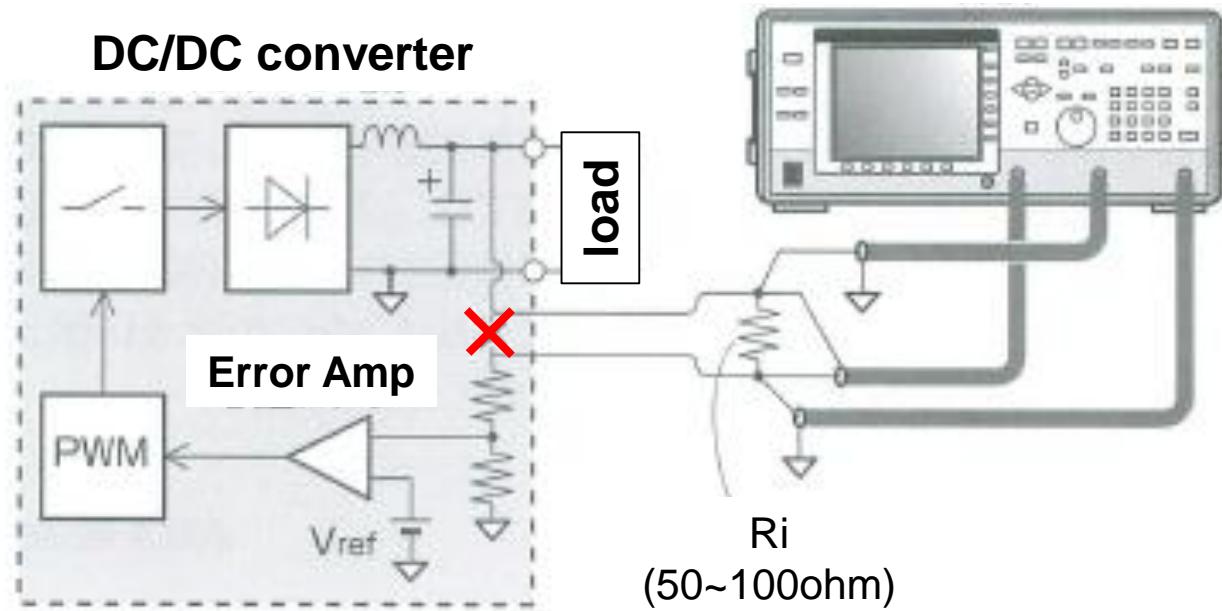
- Conventional loop gain measurement method



Disadvantage of Conventional Method

- It is necessary to inject a voltage signal into the feedback loop by breaking the loop.
- If the control circuits are implemented on an IC, this method is NOT applicable.

FRA (Frequency Response Analyzer)



Outline

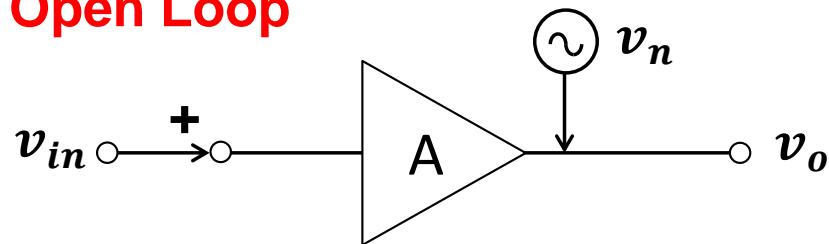
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Purpose of This Work

- To measure the loop gain
without breaking the feedback loop.
- To develop a new method
to derive the loop gain from output impedances
in dc-dc buck converter.
- To demonstrate the proposed method
by simulation and experimental evaluations.

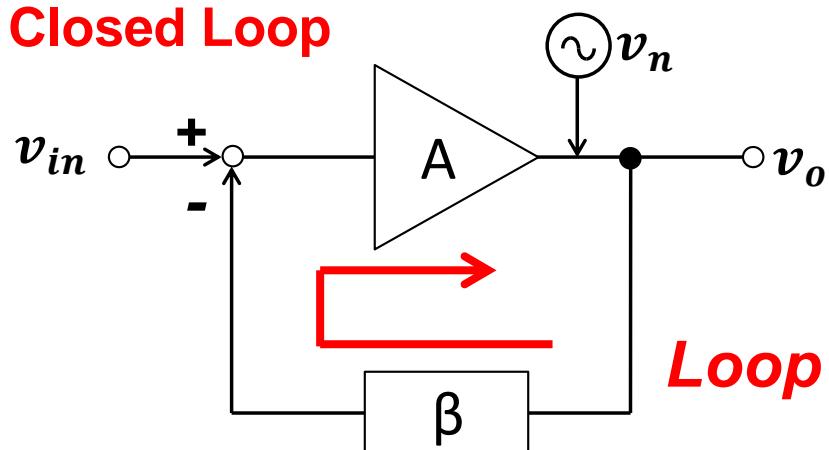
Keypoint of Proposed Method

Open Loop



$$v_o = A v_{in} + \boxed{v_n}$$

Closed Loop



$$v_o = \frac{1}{\beta} \cdot \frac{T}{1+T} v_{in} + \boxed{\frac{v_n}{1+T}}$$

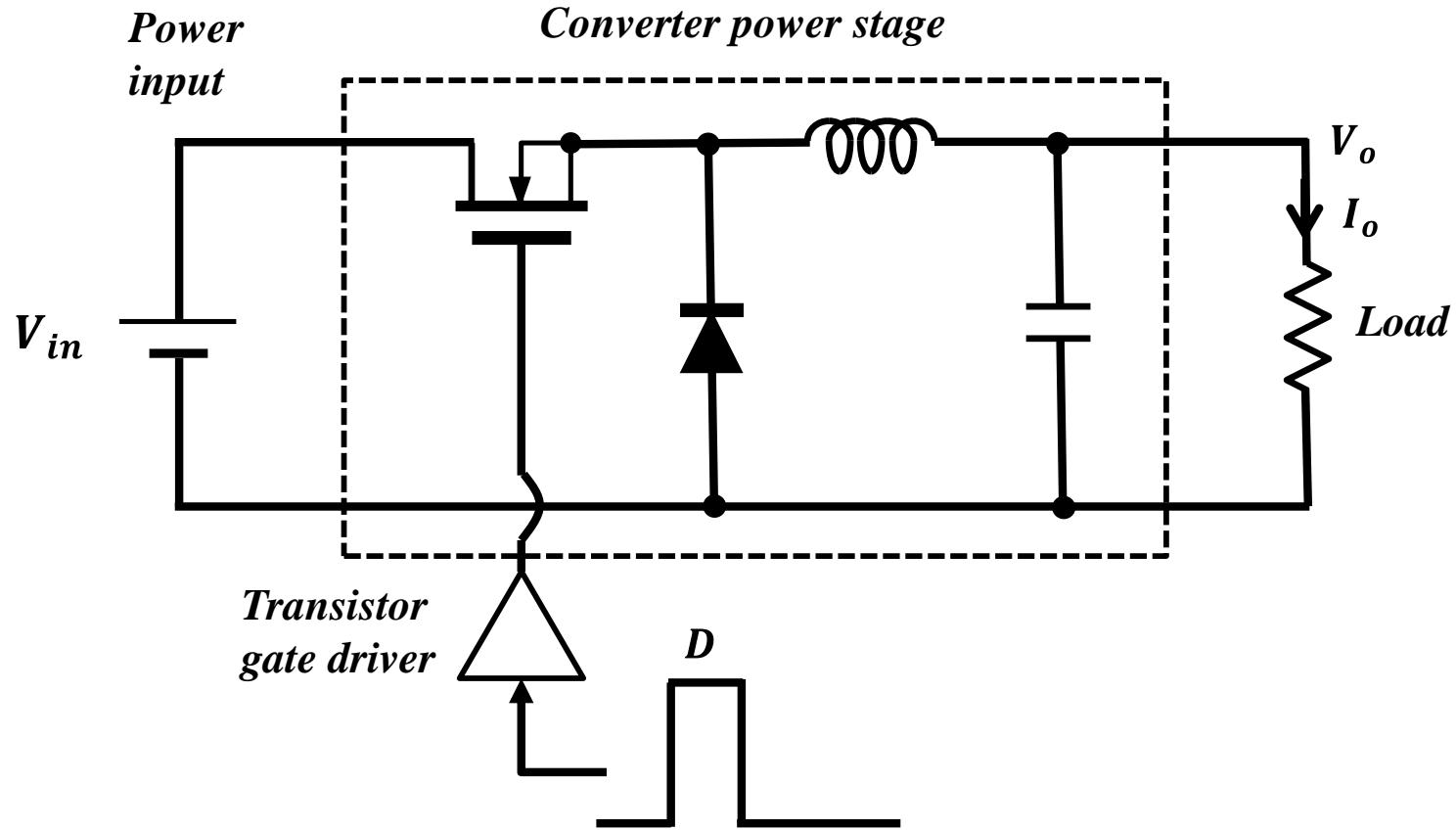
Loop Gain $T = A\beta$

Negative feedback reduces the noise by a factor of $1/(1+T)$.
This theory can be applied to loop gain measurement .

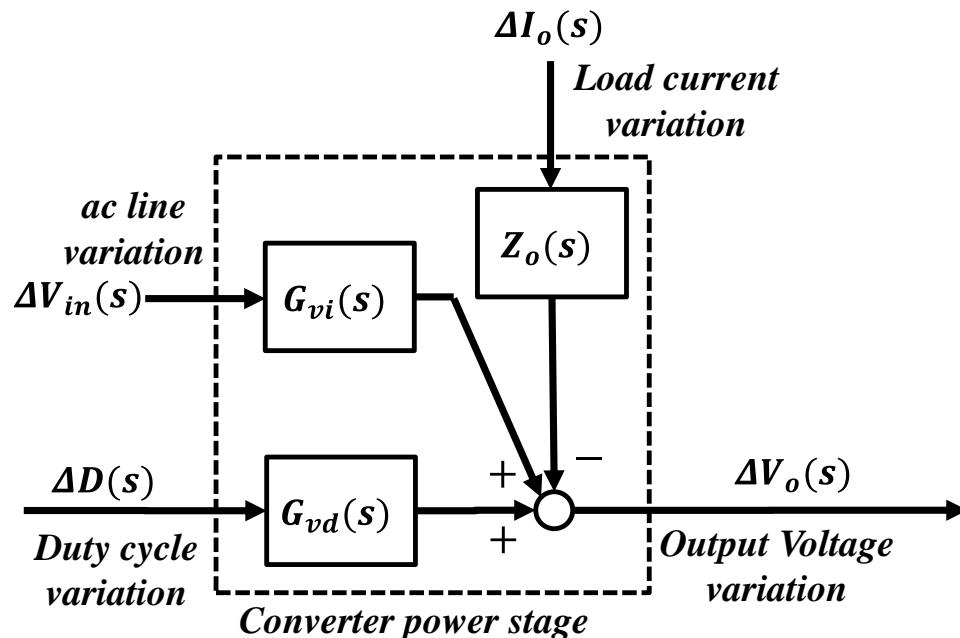
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DC-DC Buck Converter Circuit in Open Loop



Functional Block Diagram in Open Loop

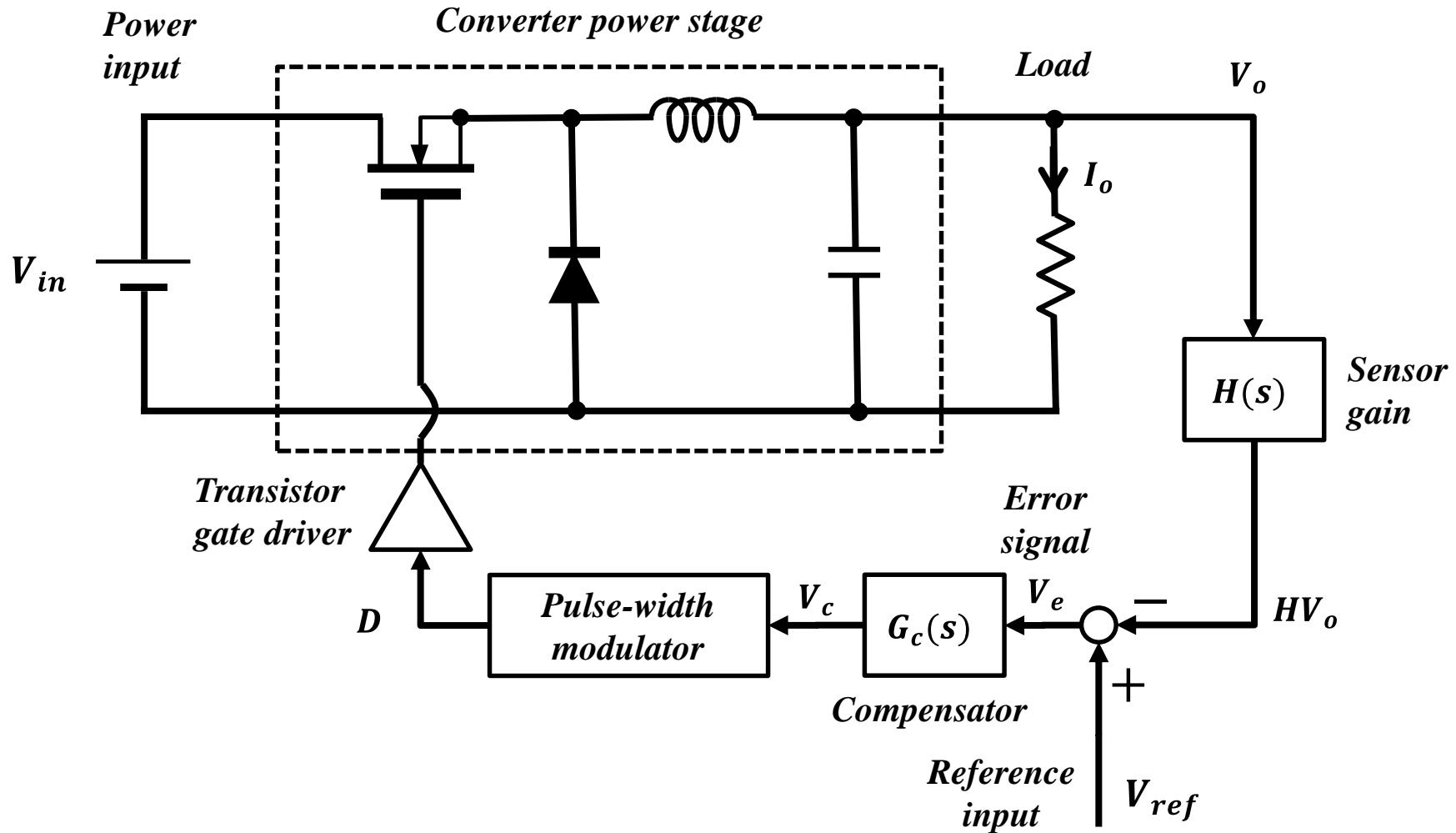


$$\Delta V_o = G_{vd}\Delta D + G_{vi}\Delta V_{in} - Z_o\Delta I_o$$

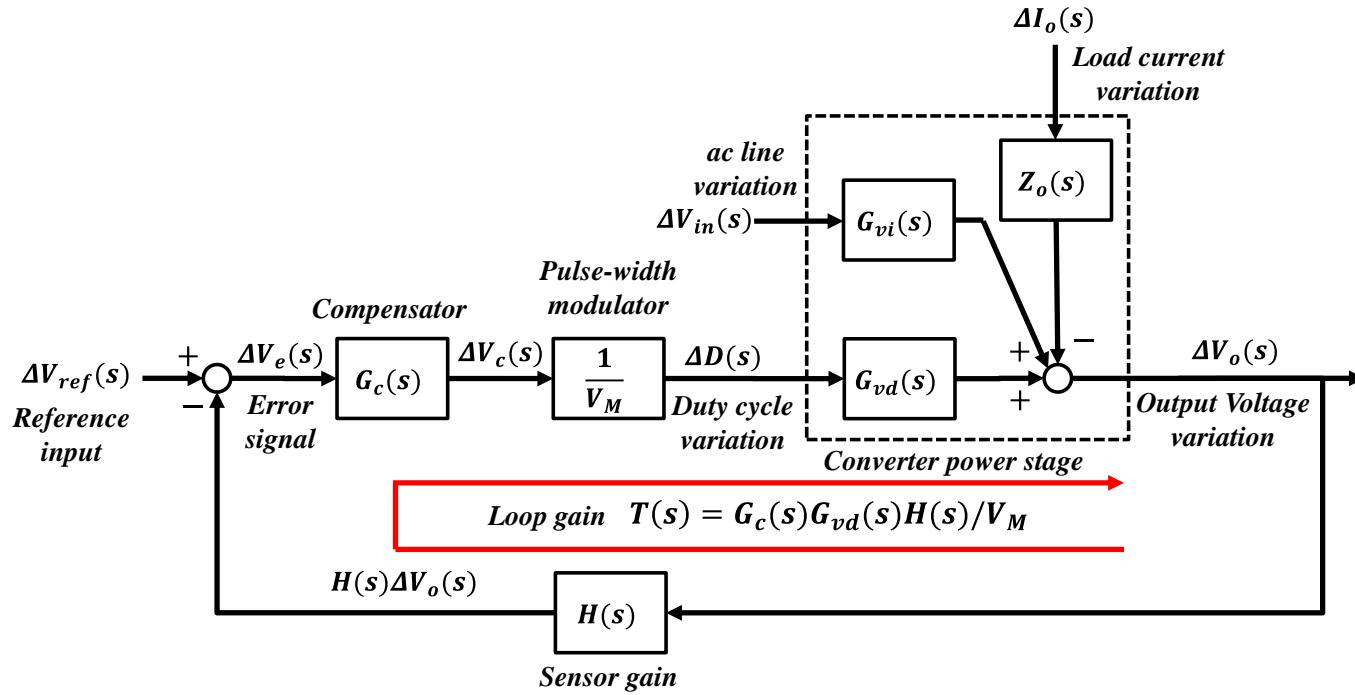
$$Z_o \equiv - \left. \frac{\Delta V_o}{\Delta I_o} \right|_{\Delta D=0, \Delta V_{in}=0}$$

converter output impedance
in open loop

DC-DC Buck Converter Circuit in Closed Loop



Functional Block Diagram in Closed Loop



$$\Delta V_o = \frac{1}{H} \frac{T}{1+T} \Delta V_{ref} + \frac{G_{vi}}{1+T} \Delta V_{in} - \frac{Z_o}{1+T} \Delta I_o$$

$$Z_{oc} \equiv -\left. \frac{\Delta V_o}{\Delta I_o} \right|_{\Delta V_{ref}=0, \Delta V_{in}=0} = \frac{Z_o}{1+T}$$

converter output impedance
in closed loop

Derivation of Proposed Method

$$Z_{oc}(s) = \frac{Z_o(s)}{1 + T(s)} \quad \rightarrow \quad T(s) = \frac{Z_o(s) - Z_{oc}(s)}{Z_{oc}(s)}$$

Magnitude of Loop Gain

$$20 \log_{10} |T| = 20 \log_{10} \left[\frac{|Z_o - Z_{oc}|}{|Z_{oc}|} \right]$$

Phase of Loop Gain

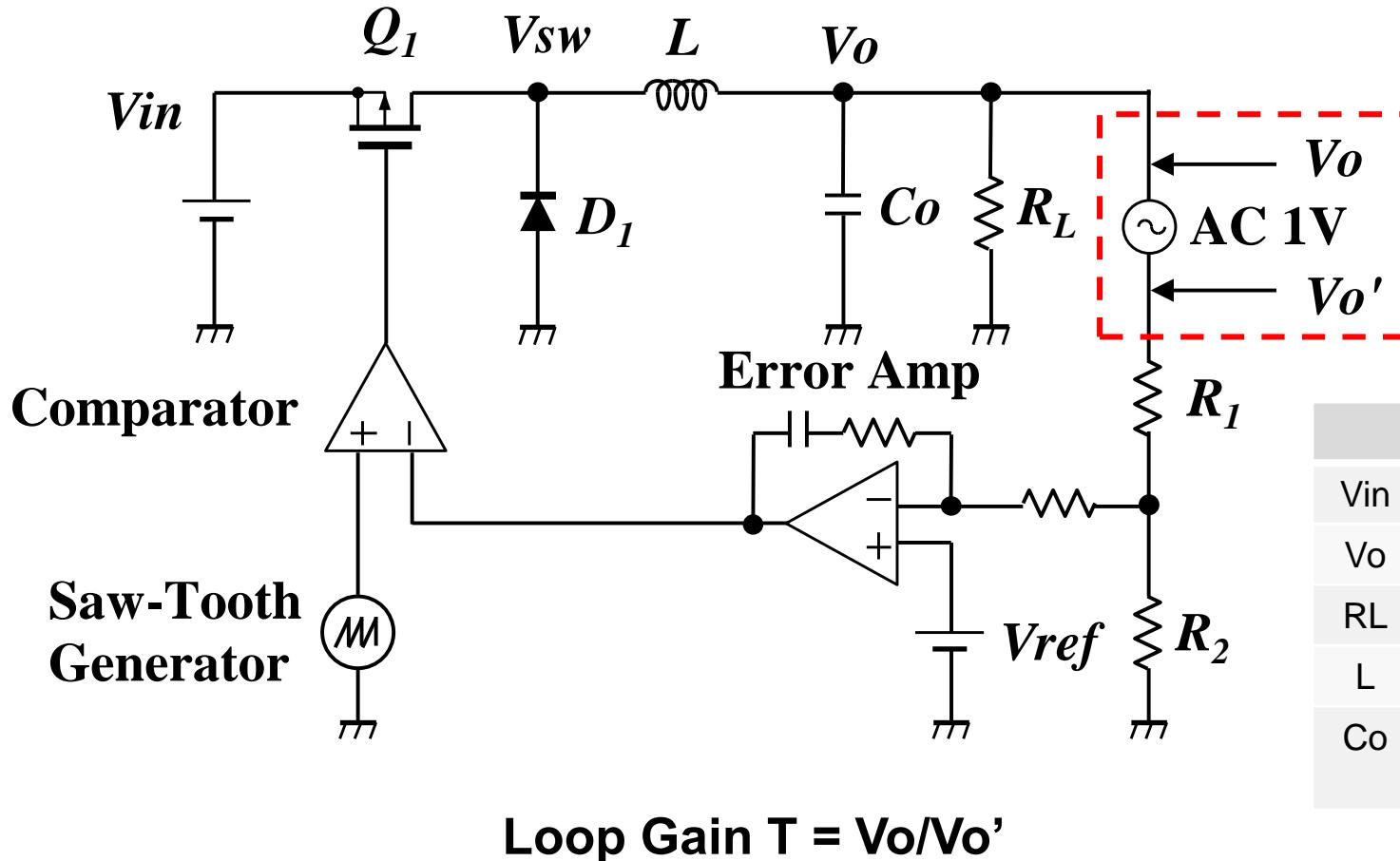
$$\arg(T) = \arg(Z_o - Z_{oc}) - \arg(Z_{oc})$$

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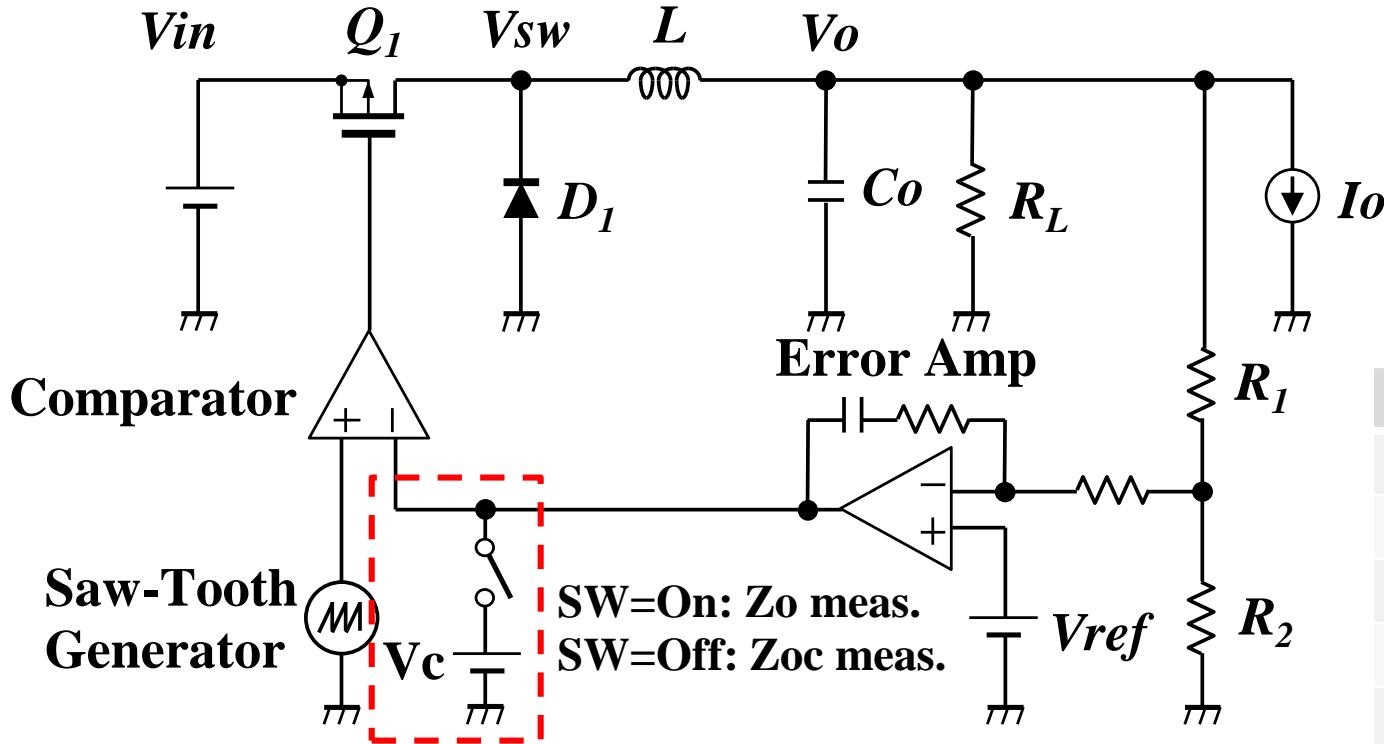
Simulation Circuits

Conventional



Simulation Circuits

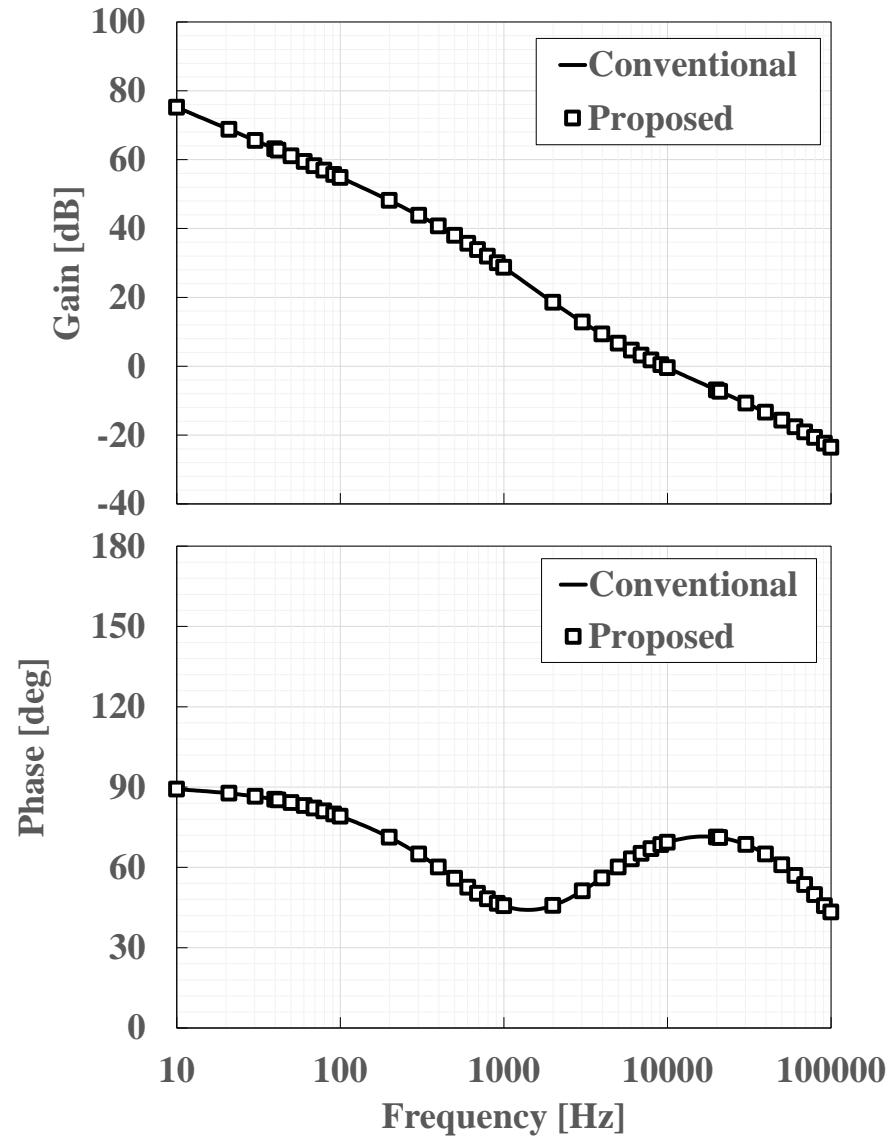
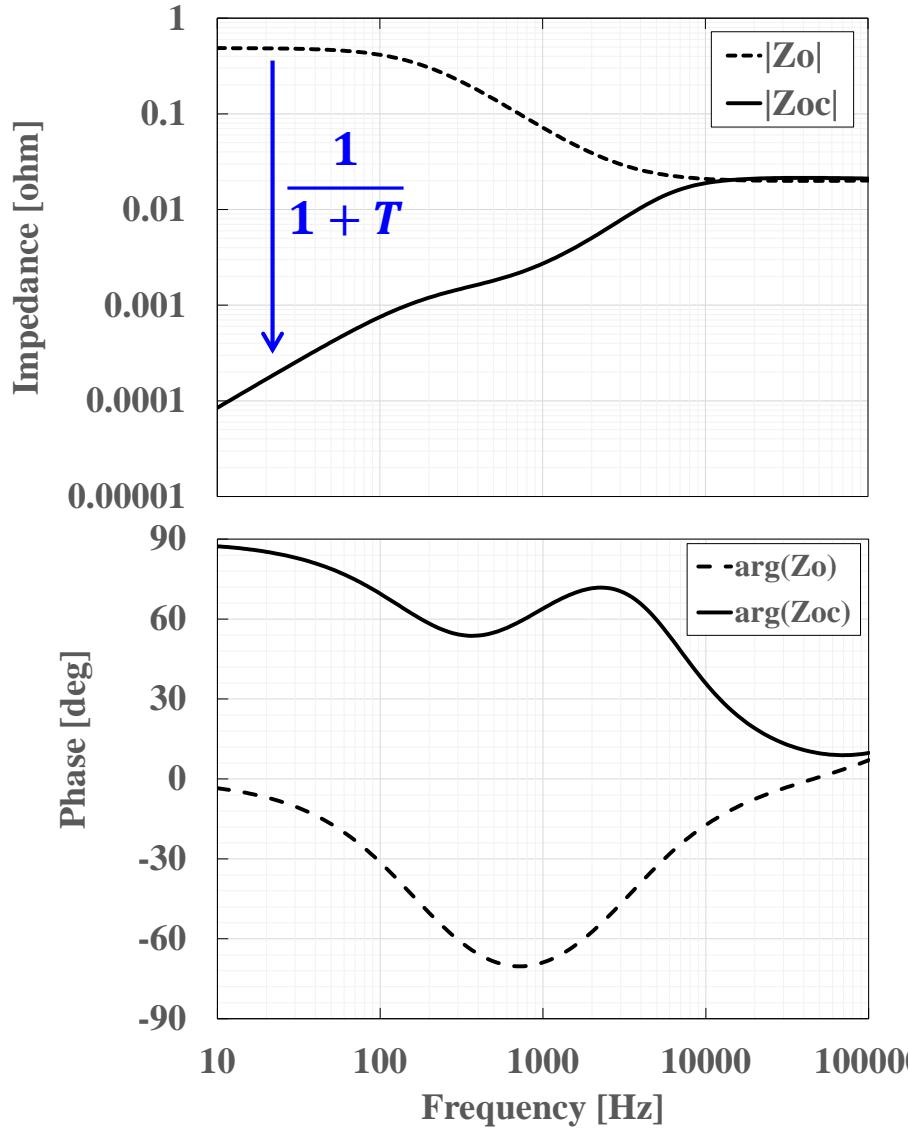
Proposed



Parameter	
V_{in}	12V
V_o	5V
R_L	5Ω
L	$120\mu H$
C_o	$1.2mF \times 2$ (ESR=40mΩ)

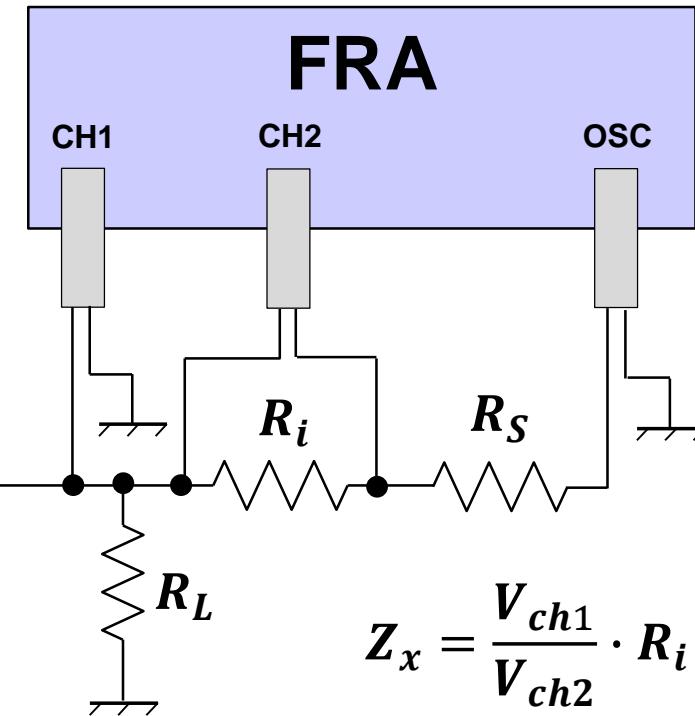
$$\text{Loop Gain } T = (Z_o - Z_{oc})/Z_{oc}$$

Simulation Results



Experimental Setup

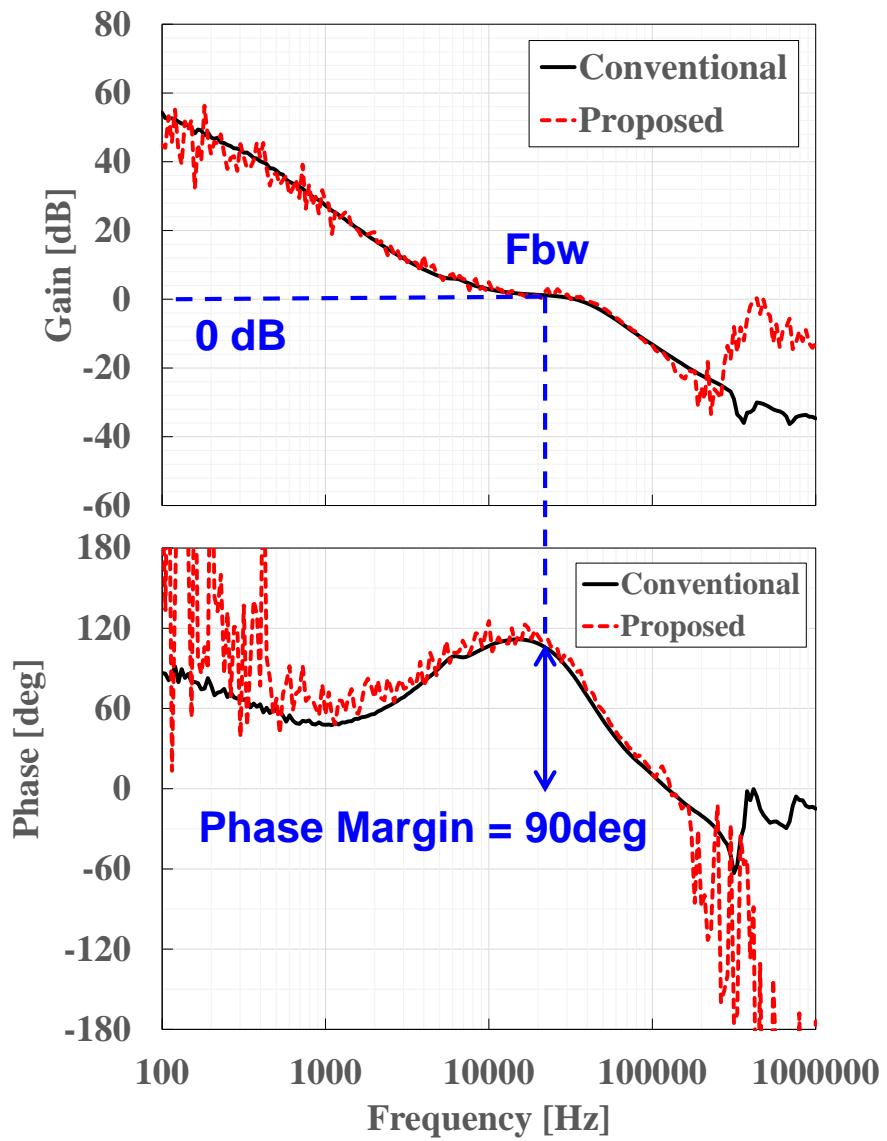
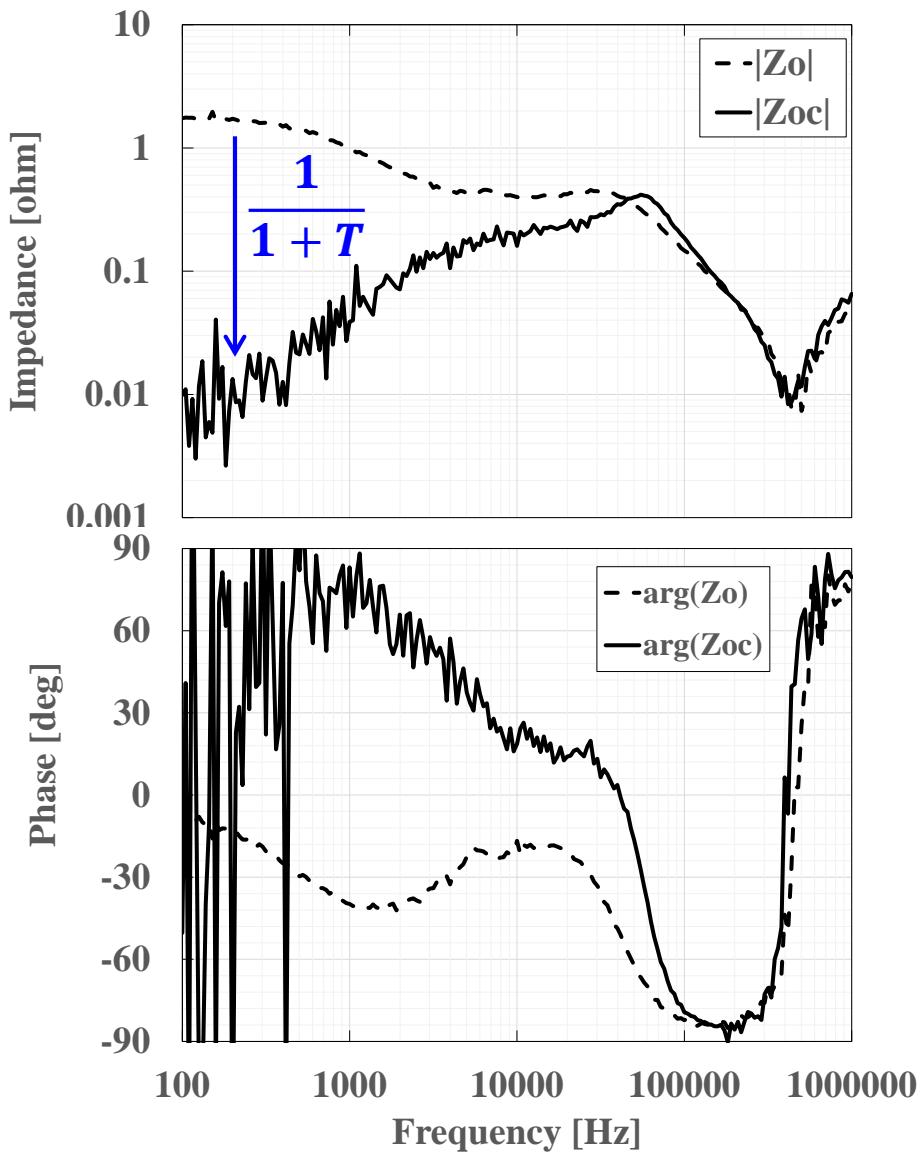
- IC:BD9329A (Rohm Semiconductor)
 - Synchronous buck converter with integrated FET
 - Switching frequency: 380kHz



Parameter	
Vin	12V
Vo	3.3V
RL	3Ω
L	10uH
Co	10uF x 2
Ri	1Ω
Rs	1kΩ

Evaluation board

Experimental Results



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Summary

- We have proposed a method to derive the loop gain from the output impedances in dc-dc buck converter.
- We showed effectiveness of the proposed method with simulations and experiments of dc-dc buck converter.
- We found out that sufficient evaluation of phase margin and gain margin is possible.

Thank you for listening !!