



ITC-Asia 2018



Aug. 17, 2018
Session 3B_1
Analog Test

Low-Distortion One-Tone and Two-Tone Signal Generation Using AWG Over Full Nyquist Region

Tomonori Yanagida, Shohei Shibuya, Kosuke Machida

Koji Asami, Haruo Kobayashi



Gunma University



Research Objectives

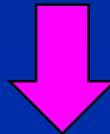
Objective

For ADC testing

- Low-distortion signal generation
 - Low cost AWG
- Full Nyquist Region

Our Approach

- Phase-Switching-Method



- Only AWG program change
- No need for AWG nonlinearity identification

Outline

- Research Background
- Phase-Switching Method
- Low & High-Frequency Signal Generation
- Mid-Frequency Signal Generation
- Experimental Results
- Conclusions

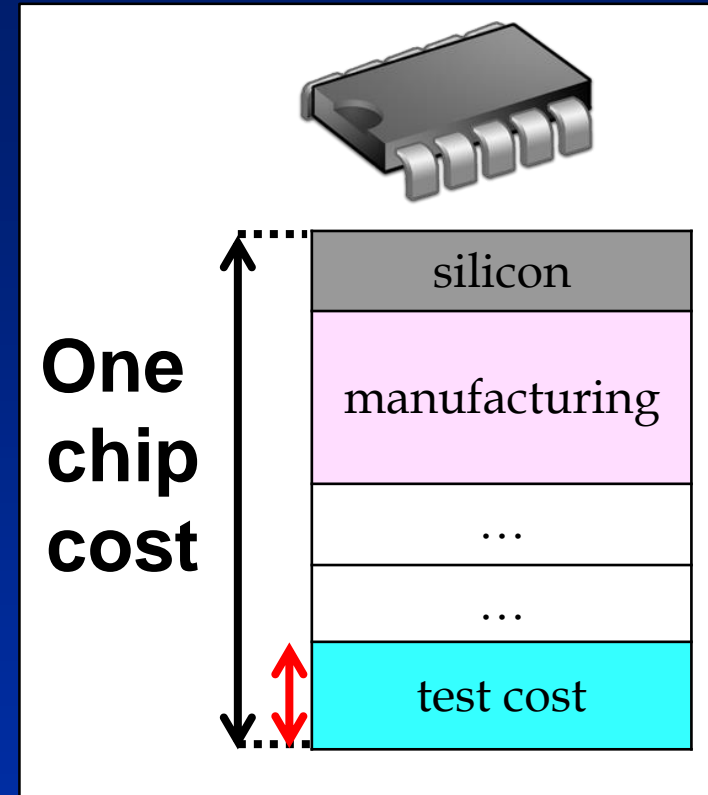
Outline

- Research Background
- Phase-Switching Method
- Low & High-Frequency Signal Generation
- Mid-Frequency Signal Generation
- Experimental Results
- Conclusions

Research Background

Silicon cost per transistor → **decreasing**

Test cost → **increasing**



Low cost test

→ **Low cost LSI production**

ADC Test Cost Using AWG

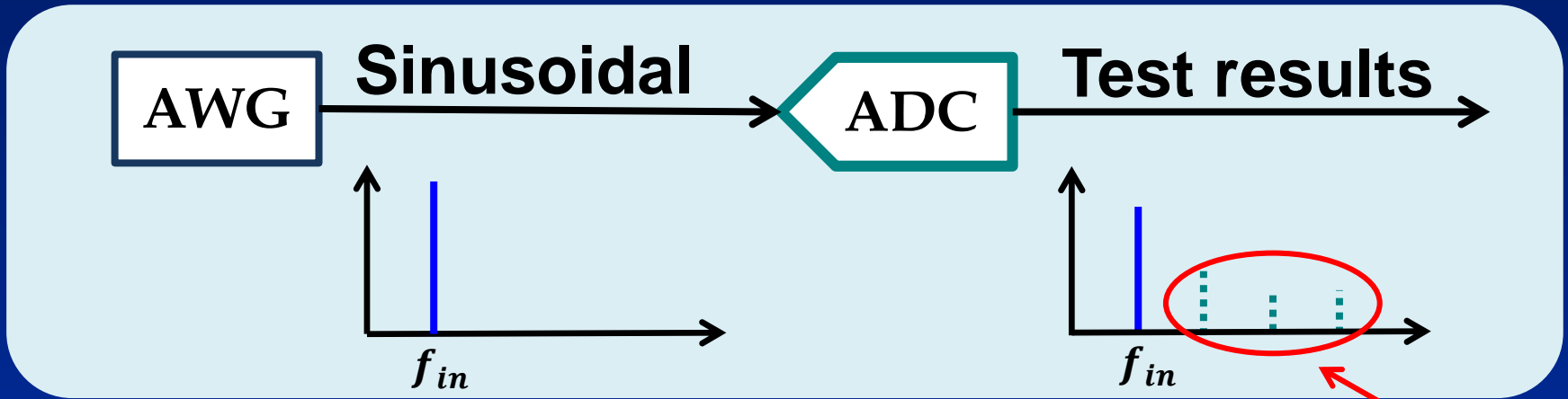


AWG : High Precision
Arbitrary Waveform Generator
Expensive

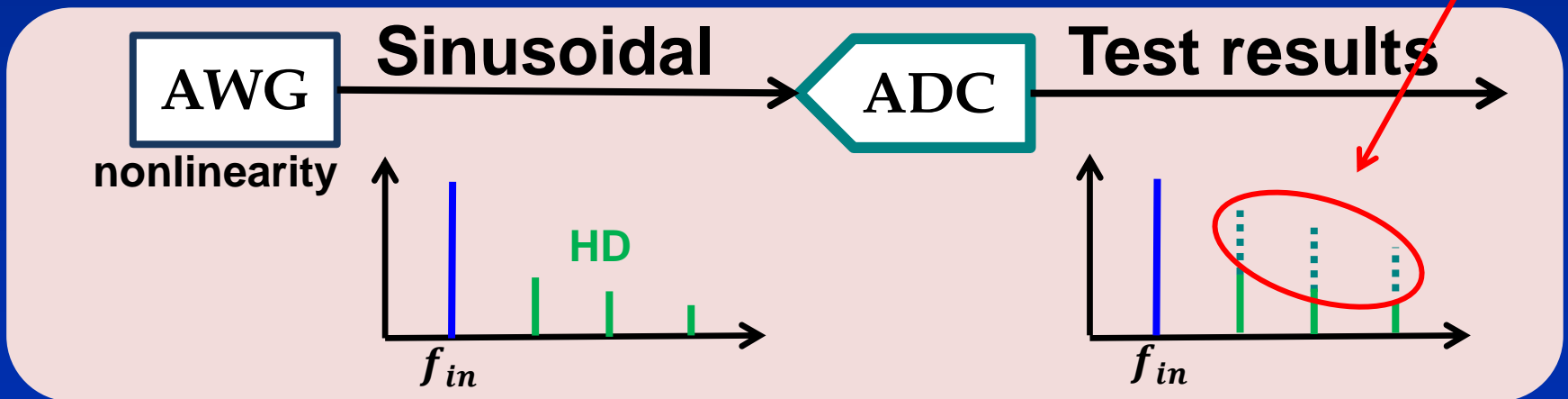
| | Cost | Quality |
|---------------------------------------|-------------|-------------|
| Expensive AWG | bad | good |
| Low-price AWG | good | bad |
| Low-price AWG + Proposed method | good | good |

Ideal and Real Signal

The ideal

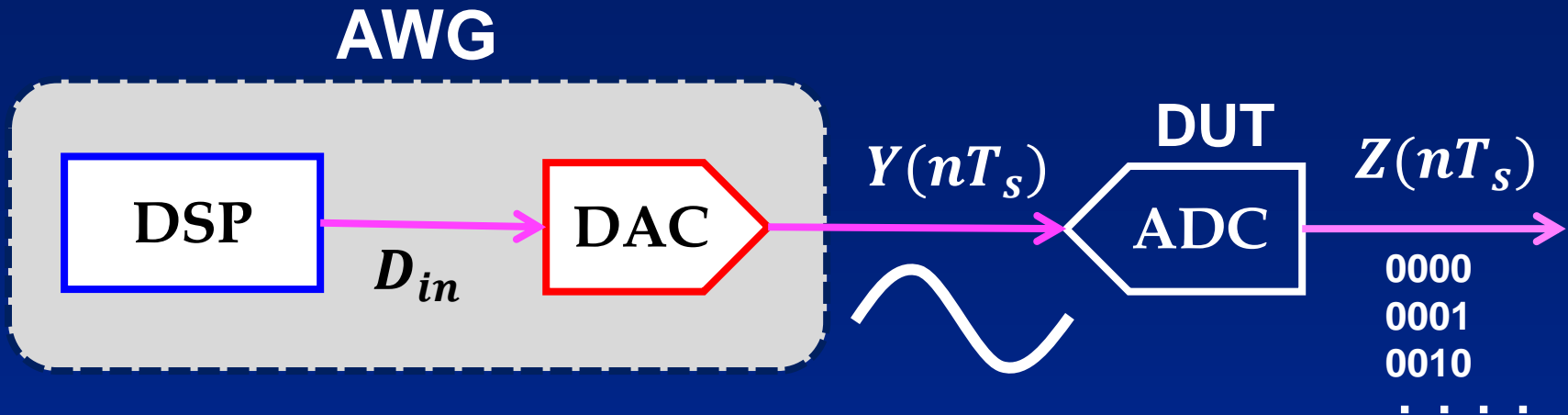


The real



HD: Harmonic Distortion

Arbitrary Waveform Generator



- **DAC** output

$$Y(nT_s) = a_0 + a_1 D_{in} + a_2 D_{in}^2 + a_3 D_{in}^3 + \dots$$

DAC nonlinearity \longrightarrow harmonic distortion

Low-distortion signal generation
Only DSP program change

DSP : Digital Signal Processor

Outline

- Research Background
- Phase-Switching Method
- Low & High-Frequency Signal Generation
- Mid-Frequency Signal Generation
- Experimental Results
- Conclusions

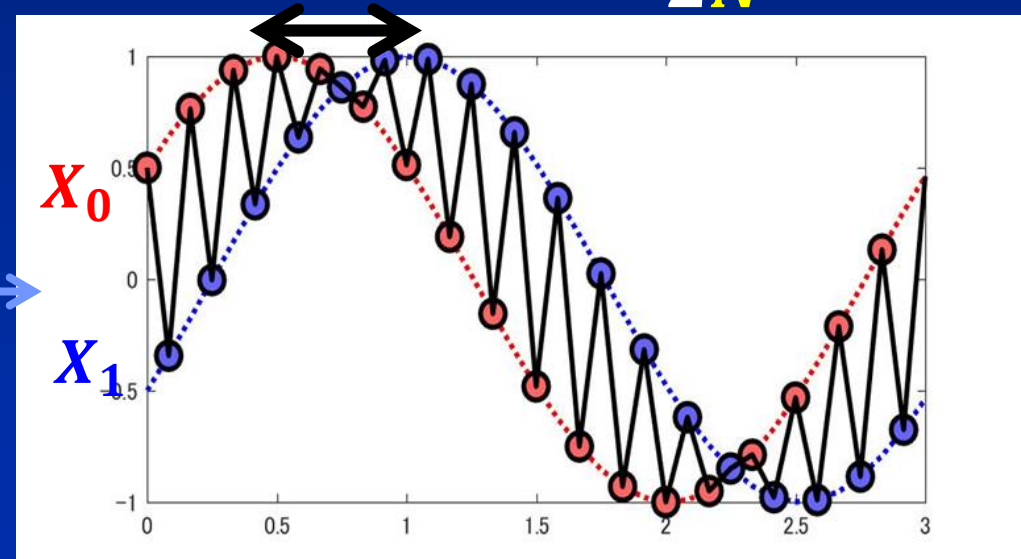
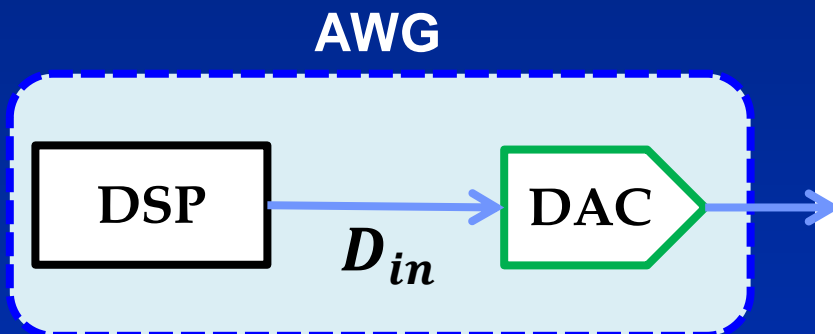
Phase Switching Algorithm

Phase Switching Algorithm

- step 1. φ_0, φ_1 phase shift
- step 2. Choose alternately

Nth harmonic cancelled

$$\varphi_0 = \varphi_1 = \frac{\pi}{2N}$$



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} n T_s + \varphi_0) & n: \text{even} \\ X_1 = A \sin(2\pi f_{in} n T_s - \varphi_1) & n: \text{odd} \end{cases}$$

Phase Switching Algorithm

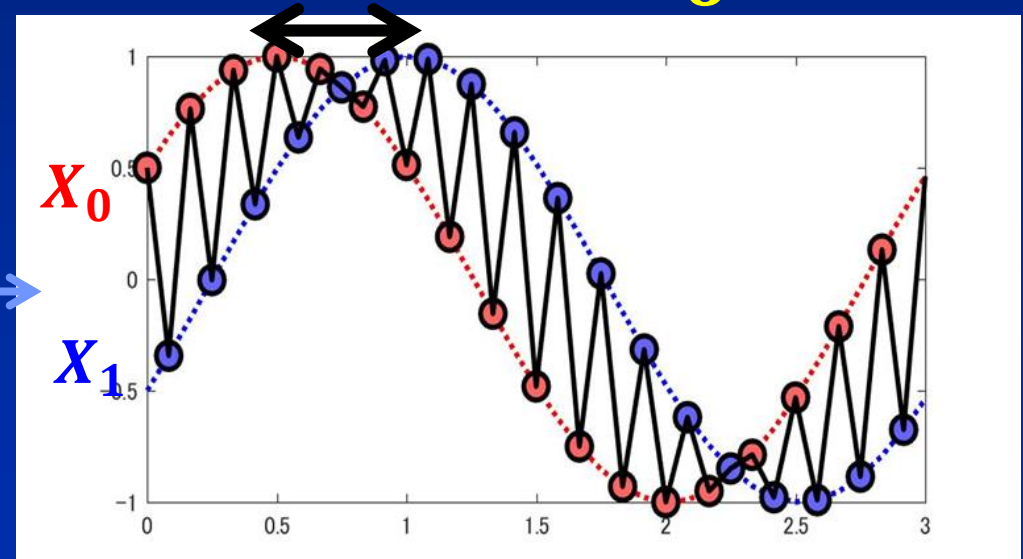
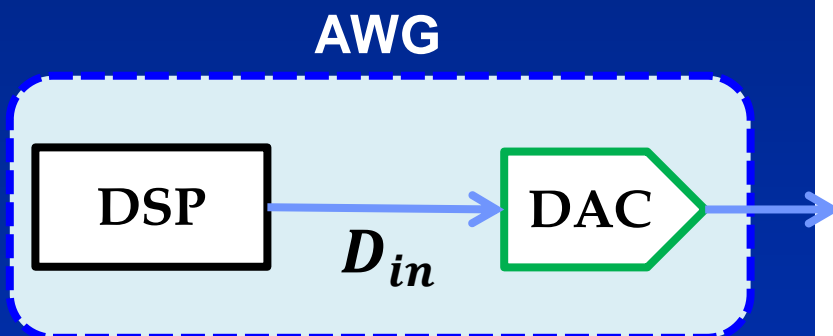
Phase Switching Algorithm

step 1. φ_0, φ_1 phase shift

step 2. Choose alternately

3rd harmonic suppression

$$\varphi_0 = \varphi_1 = \frac{\pi}{6}$$



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} nT_s + \pi/6) & n: \text{even} \\ X_1 = A \sin(2\pi f_{in} nT_s - \pi/6) & n: \text{odd} \end{cases}$$

Phase Switching Signal Equation

$$Y(nT_s) = \left(\frac{1}{2} + \cos\left(2\pi \frac{f_s}{2} nT_s\right) \right) (a_1 X_0 + a_3 X_0^3) + \left(\frac{1}{2} - \cos\left(2\pi \frac{f_s}{2} nT_s\right) \right) (a_1 X_1 + a_3 X_1^3)$$

$$= \frac{4a_1A + 3a_3A^3}{4} (e^{j\varphi_0} + e^{-j\varphi_0}) \sin(2\pi f_{in} nT_s)$$

$$- \frac{a_3A^3}{8} (e^{j3\varphi_0} + e^{-j3\varphi_0}) \sin(2\pi 3f_{in} nT_s)$$

$$- \frac{4a_1A + 3a_3A^3}{4} (e^{j\varphi_0} - e^{-j\varphi_0}) \sin\left(2\pi \left(\frac{f_s}{2} - f_{in}\right) nT_s\right)$$

$$+ \frac{a_3A^3}{8} (e^{j3\varphi_0} - e^{-j3\varphi_0}) \sin\left(2\pi \left(\frac{f_s}{2} - 3f_{in}\right) nT_s\right)$$

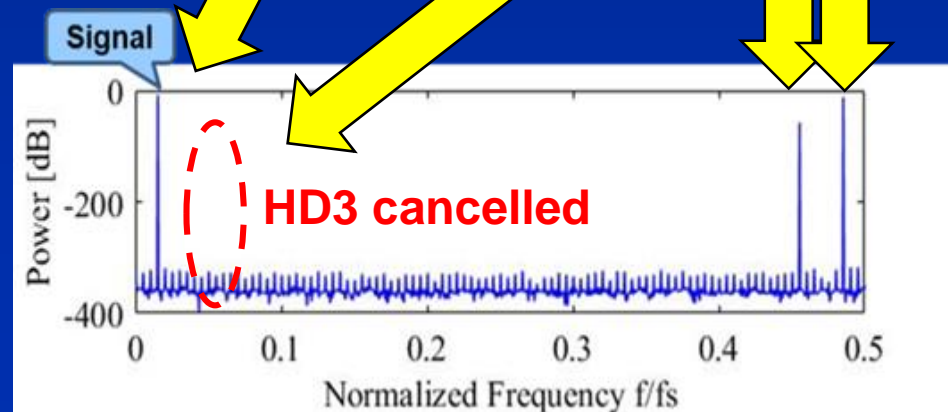
In case $\varphi_0 = \frac{\pi}{6}$
 $(e^{j3\varphi_0} + e^{-j3\varphi_0}) = 0$

Fundamental wave

HD3

HD3 image

Fundamental image

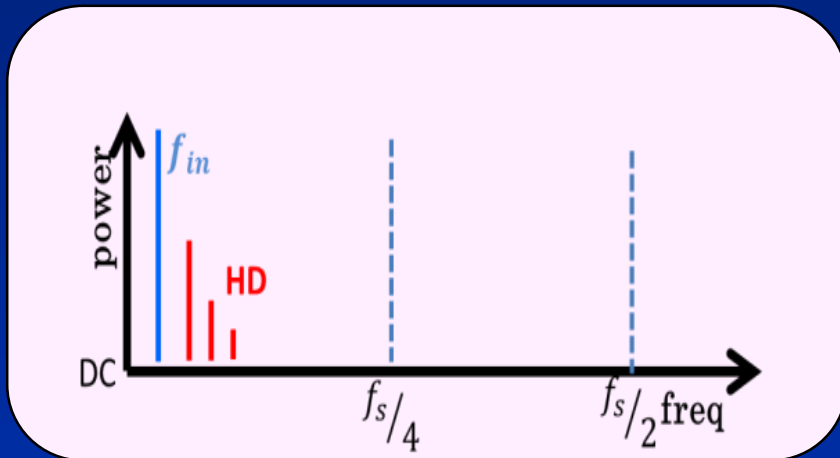


Outline

- Research Background
- Phase-Switching Method
- Low & High-Frequency Signal Generation
- Mid-Frequency Signal Generation
- Experimental Results
- Conclusions

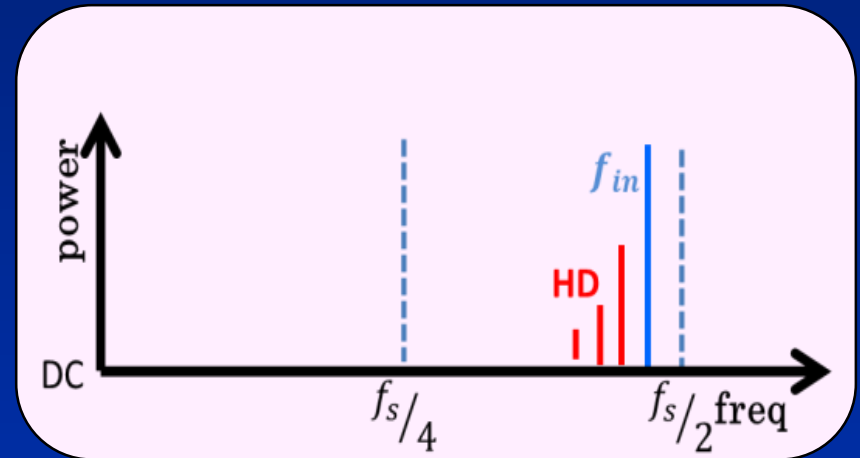
Low & High-Frequency Signals

Low-Frequency Signal



Near **DC**

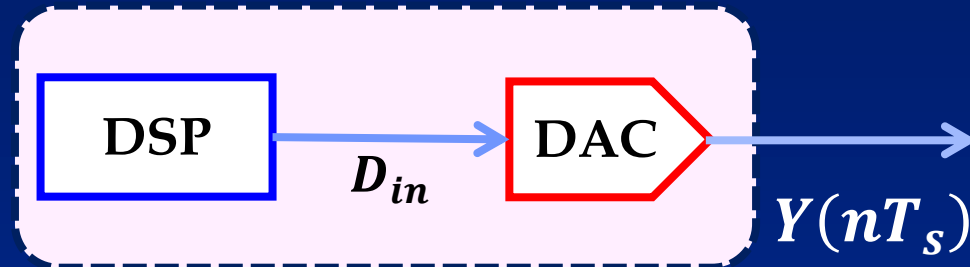
High-Frequency Signal



Near **Nyquist frequency**

Low Freq. Single-Tone Signal Generation

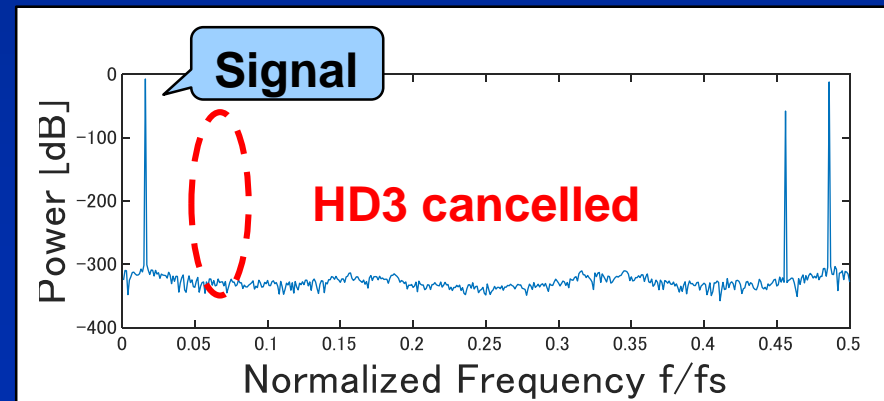
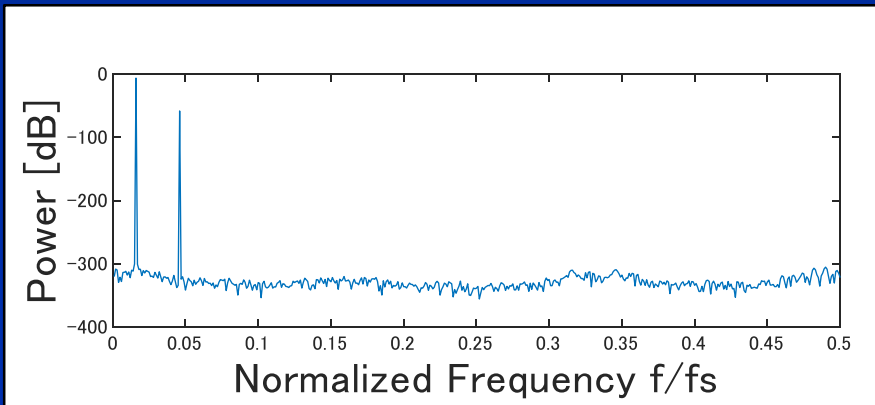
AWG



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} nT_s + \varphi_0) & n: \text{even} \\ X_1 = A \sin(2\pi f_{in} nT_s - \varphi_1) & n: \text{odd} \end{cases}$$

$$\varphi_0 = \varphi_1 = \frac{\pi}{2N}$$

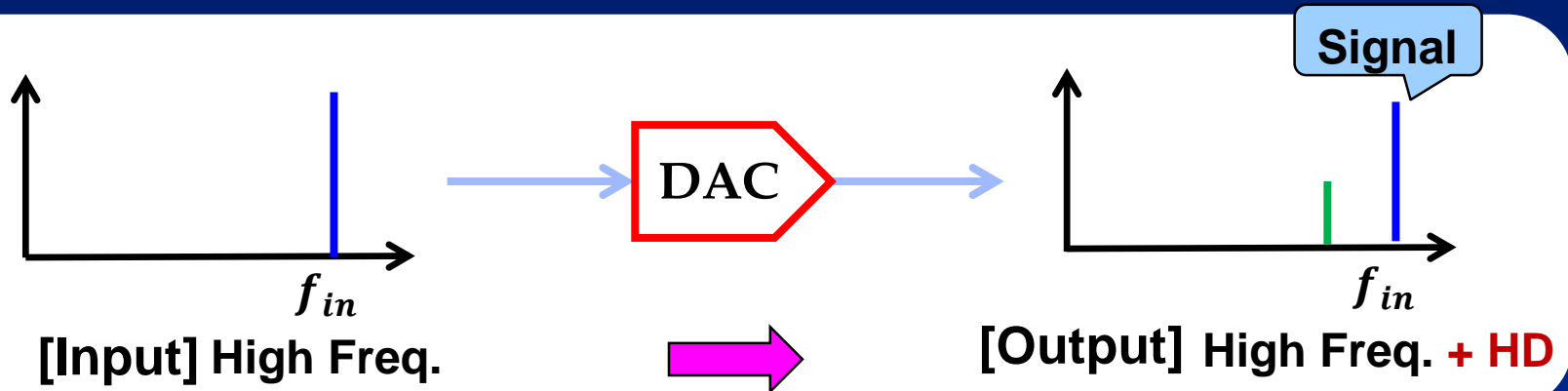
Nth order
is cancelled



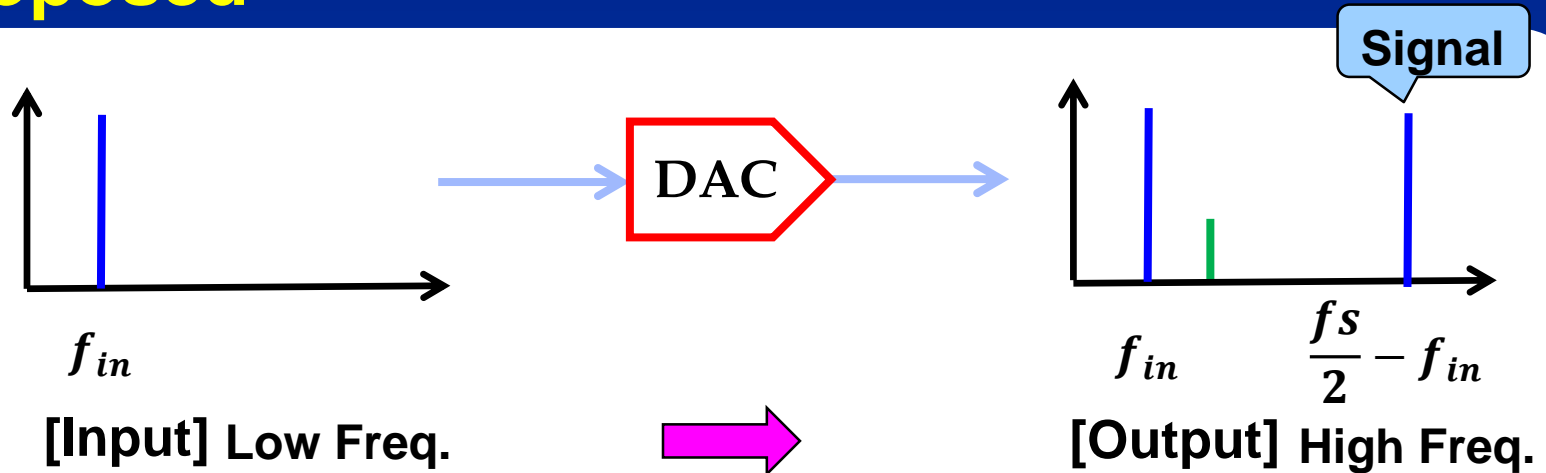
$$f_1/f_s = 3/200$$

High Freq. Signal Generation

Conventional



Proposed



$f_s/2 - f_{in}$ deal with high-freq. signal

Phase Switching Signal Equation

$$Y(nT_s) = \left(\frac{1}{2} + \cos\left(2\pi \frac{f_s}{2} nT_s\right) \right) (a_1 X_0 + a_3 X_0^3) + \left(\frac{1}{2} - \cos\left(2\pi \frac{f_s}{2} nT_s\right) \right) (a_1 X_1 + a_3 X_1^3)$$

$$= \frac{4a_1A + 3a_3A^3}{4} (e^{j\varphi_0} + e^{-j\varphi_0}) \sin(2\pi f_{in} nT_s)$$

Fundamental wave

$$- \frac{a_3A^3}{8} (e^{j3\varphi_0} + e^{-j3\varphi_0}) \sin(2\pi 3f_{in} nT_s)$$

HD3

$$- \frac{4a_1A + 3a_3A^3}{4} (e^{j\varphi_0} - e^{-j\varphi_0}) \sin\left(2\pi \left(\frac{f_s}{2} - f_{in}\right) nT_s\right)$$

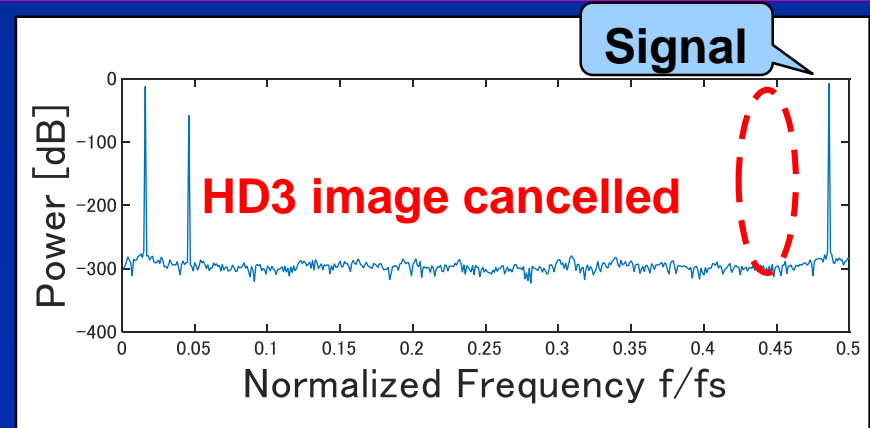
HD3 image

$$+ \frac{a_3A^3}{8} (e^{j3\varphi_0} - e^{-j3\varphi_0}) \sin\left(2\pi \left(\frac{f_s}{2} - 3f_{in}\right) nT_s\right)$$

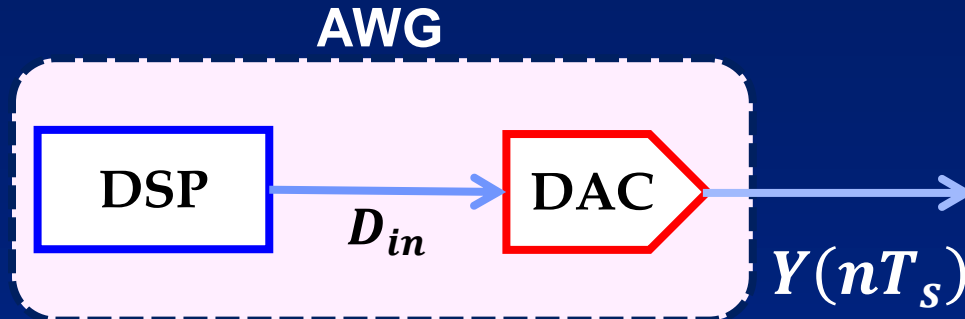
Fundamental image

In case $\varphi_0 = \frac{\pi}{3}$

$$(e^{j\varphi_0} - e^{-j\varphi_0}) = 0$$



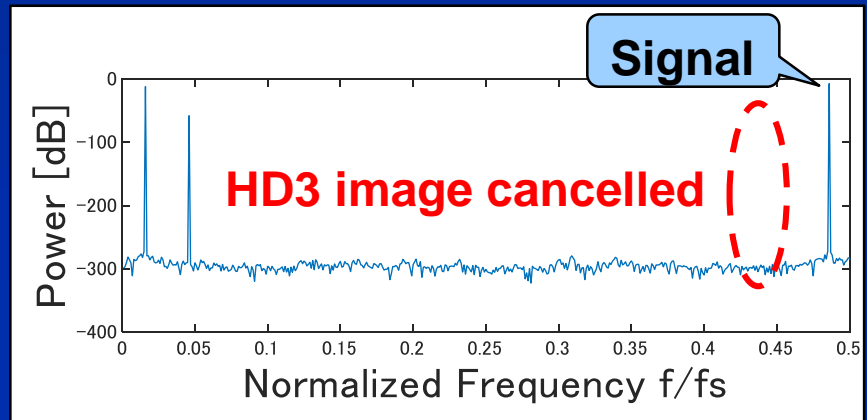
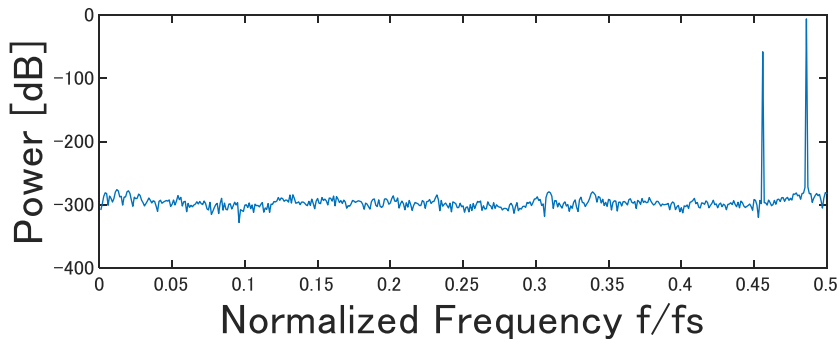
High Freq. Single-Tone Signal Generation



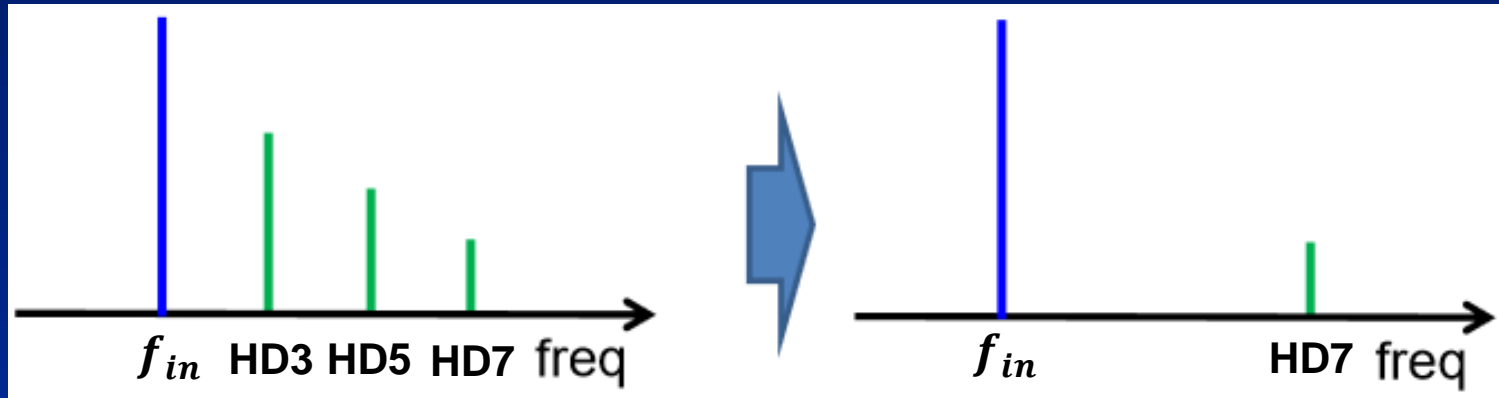
$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} nT_s + \varphi_0) & n: \text{even} \\ X_1 = A \sin(2\pi f_{in} nT_s - \varphi_1) & n: \text{odd} \end{cases}$$

$$\varphi_0 = \varphi_1 = \frac{\pi}{N}$$

Nth order image
is cancelled



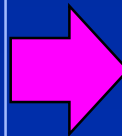
Multiple Harmonics Suppression



Example : 3rd & 5th cancel at once

Single

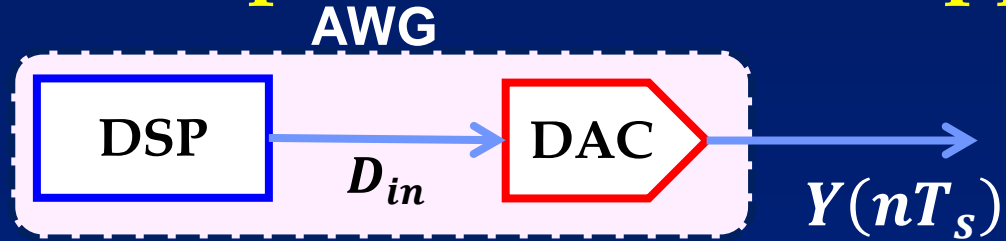
1 shift parameter ($\varphi_0 (= \varphi_1)$)
2-phase switching (X_0, X_1)



Multiple

2 shift parameters (φ_a, φ_b)
4-phase switching (X_0, X_1, X_2, X_3)

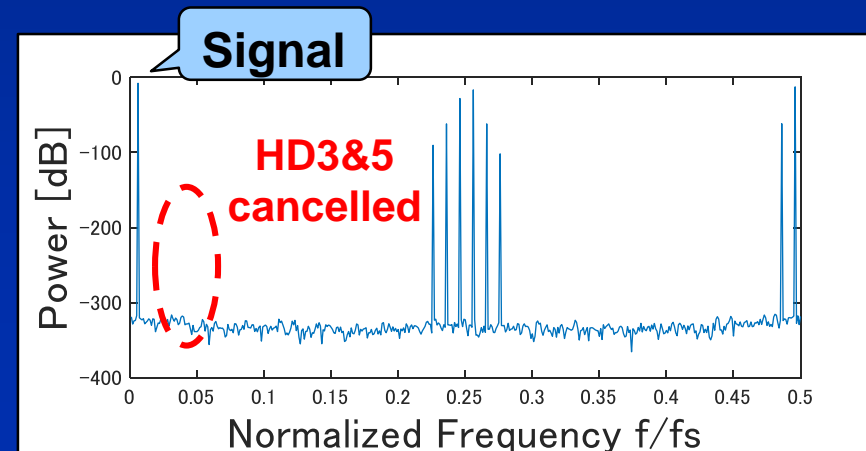
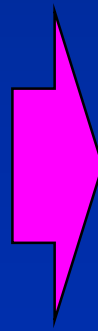
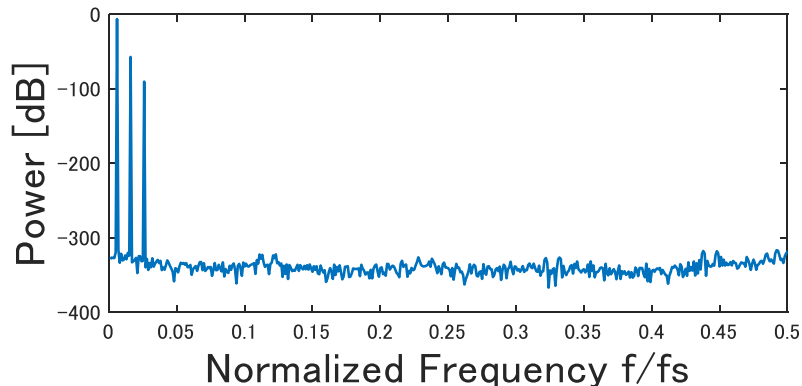
Low Freq. Multiple Harmonics Suppression



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} n T_s - \varphi_a - \varphi_b) & n = 4k \\ X_1 = A \sin(2\pi f_{in} n T_s - \varphi_a + \varphi_b) & n = 4k + 1 \\ X_2 = A \sin(2\pi f_{in} n T_s + \varphi_a - \varphi_b) & n = 4k + 2 \\ X_3 = A \sin(2\pi f_{in} n T_s + \varphi_a + \varphi_b) & n = 4k + 3 \end{cases}$$

$$\varphi_a = \frac{\pi}{2M} \quad \varphi_b = \frac{\pi}{2N}$$

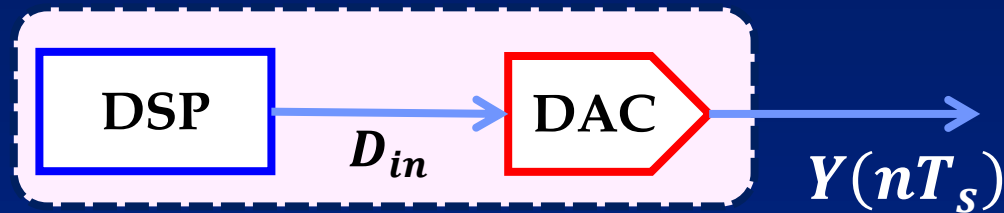
**M & Nth orders
are cancelled**



$$f_1/f_s = 1/200$$

High Freq. Multiple Harmonics Suppression

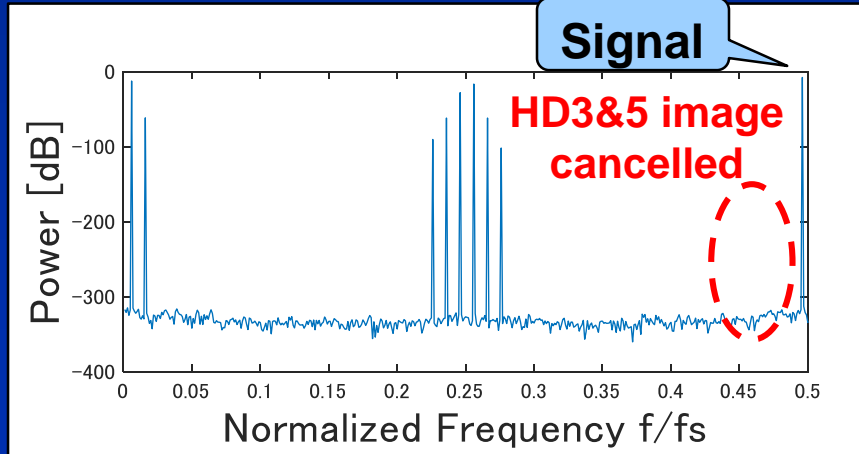
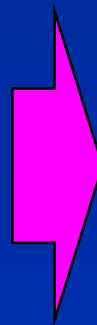
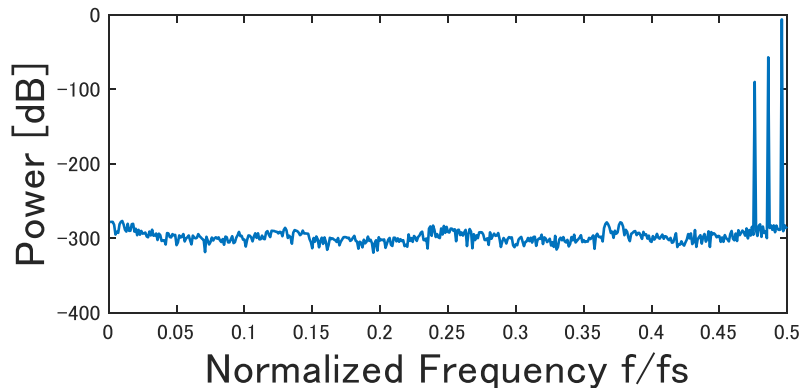
AWG



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} nT_s - \varphi_a - \varphi_b) & n = 4k \\ X_1 = A \sin(2\pi f_{in} nT_s - \varphi_a + \varphi_b) & n = 4k + 1 \\ X_2 = A \sin(2\pi f_{in} nT_s + \varphi_a - \varphi_b) & n = 4k + 2 \\ X_3 = A \sin(2\pi f_{in} nT_s + \varphi_a + \varphi_b) & n = 4k + 3 \end{cases}$$

$$\varphi_a = \frac{\pi}{M} \quad \varphi_b = \frac{\pi}{N}$$

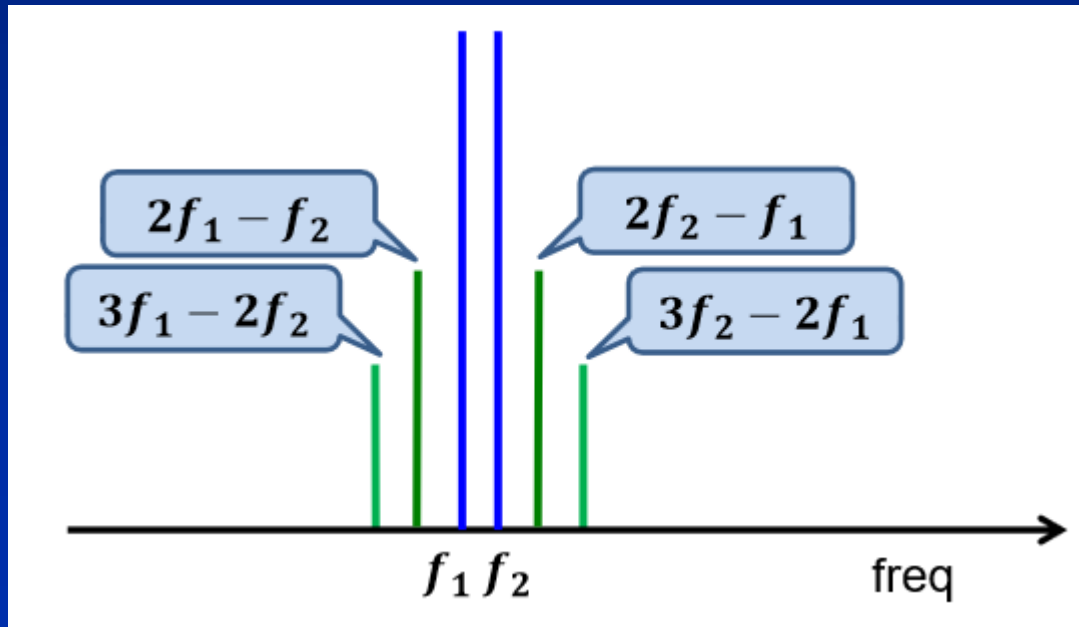
M & Nth order images are cancelled



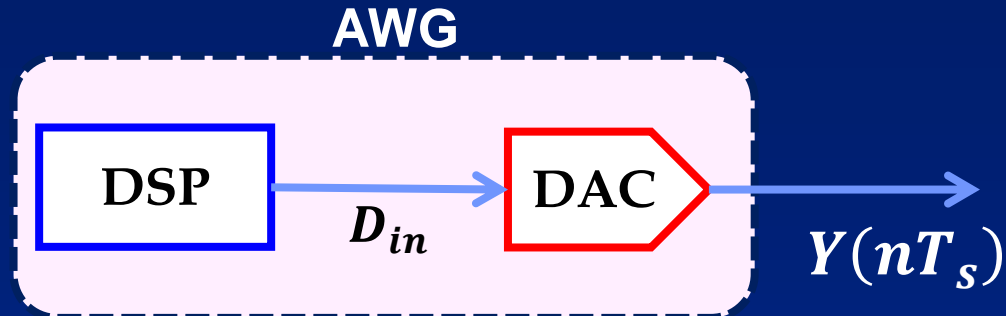
Two-Tone Signal Generation

$$D_{in} = A \sin(2\pi f_1 nT_s) + B \sin(2\pi f_2 nT_s)$$

- Inter Modulation Distortion (IMD)



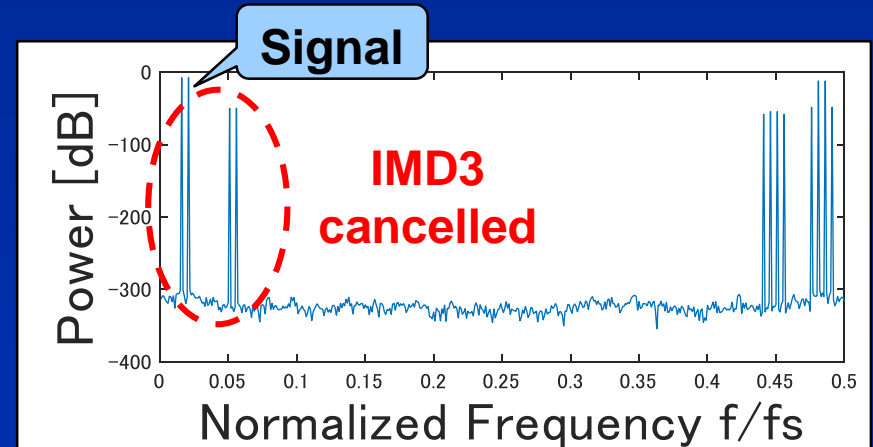
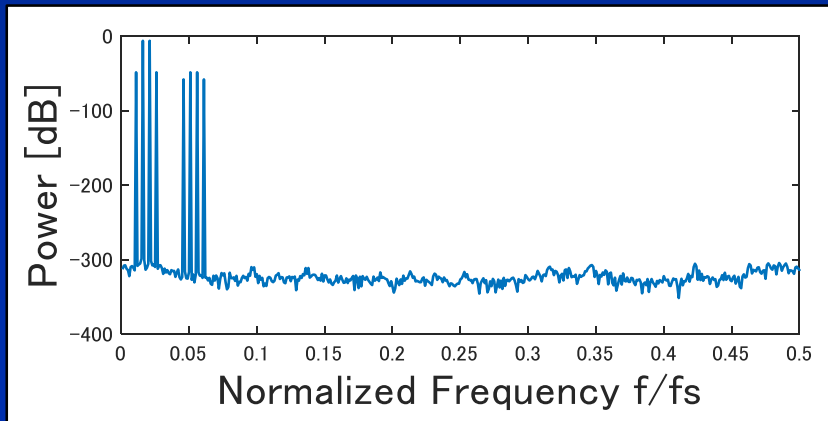
Low Freq. Two-Tone Signal Generation



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_1 nT_s + \varphi_0) + B \sin(2\pi f_2 nT_s - \varphi_0) & n: \text{even} \\ X_1 = A \sin(2\pi f_1 nT_s - \varphi_0) + B \sin(2\pi f_2 nT_s + \varphi_0) & n: \text{odd} \end{cases}$$

$$\varphi_0 = \frac{\pi}{2N}$$

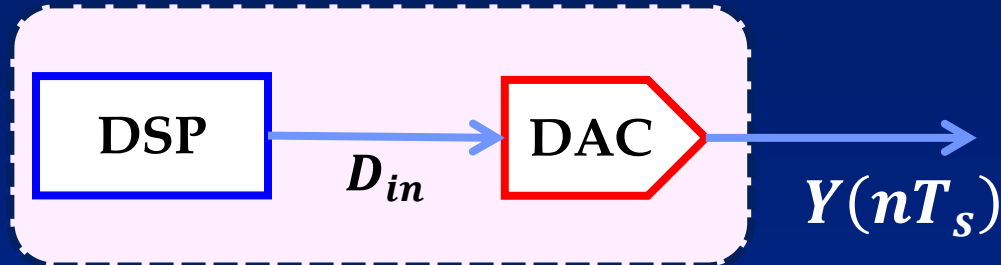
Nth order IMD
is cancelled



$$f_1/f_2/f_s = 3/4/200$$

High Freq. Two-Tone Signal Generation

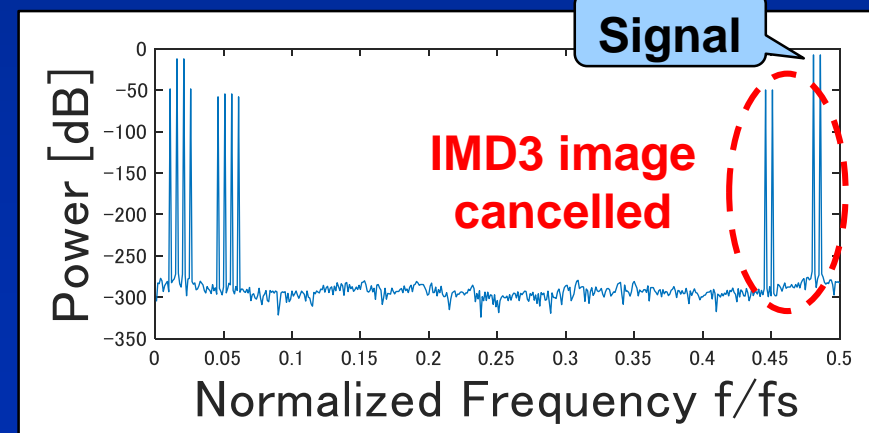
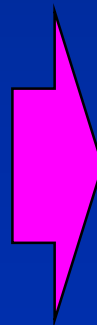
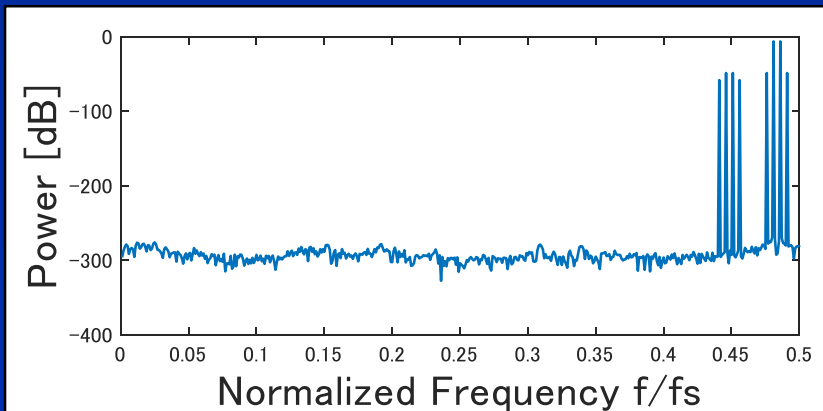
AWG



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_1 nT_s + \varphi_0) + B \sin(2\pi f_2 nT_s - \varphi_0) & n: \text{even} \\ X_1 = A \sin(2\pi f_1 nT_s - \varphi_0) + B \sin(2\pi f_2 nT_s + \varphi_0) & n: \text{odd} \end{cases}$$

$$\varphi_0 = \frac{\pi}{N}$$

Nth order IMD image is cancelled

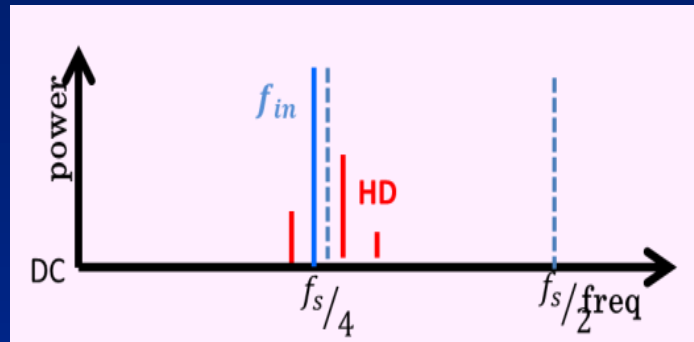


Outline

- Research Background
- Phase-Switching Method
- Low & High-Frequency Signal Generation
- Mid-Frequency Signal Generation
- Experimental Results
- Conclusions

Mid Freq. Harmonics Suppression

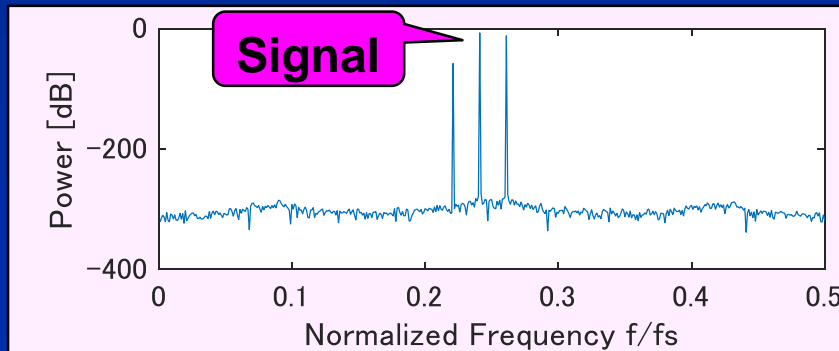
Mid Freq.



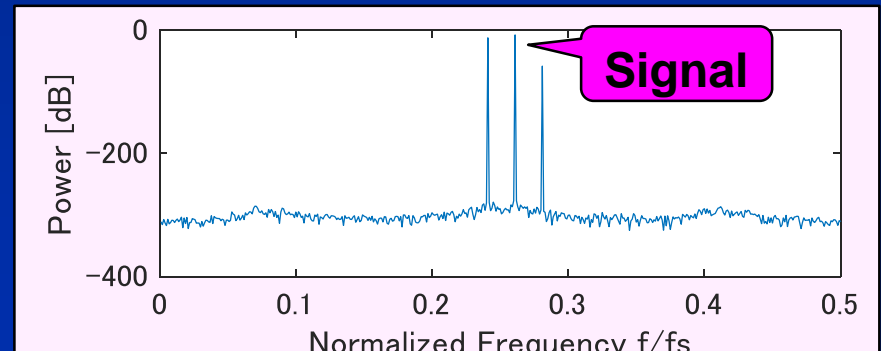
Frontier

phase switching

Low Freq. Generation



High Freq. Generation



HD or HD image near signal
is not suppressed

New Phase Switching Algorithm

Low Freq. High Freq.

Choose alternately

$$X_0 \rightarrow X_1 \rightarrow X_0 \rightarrow X_1$$

smart idea



Mid Freq.

2-point interleaving

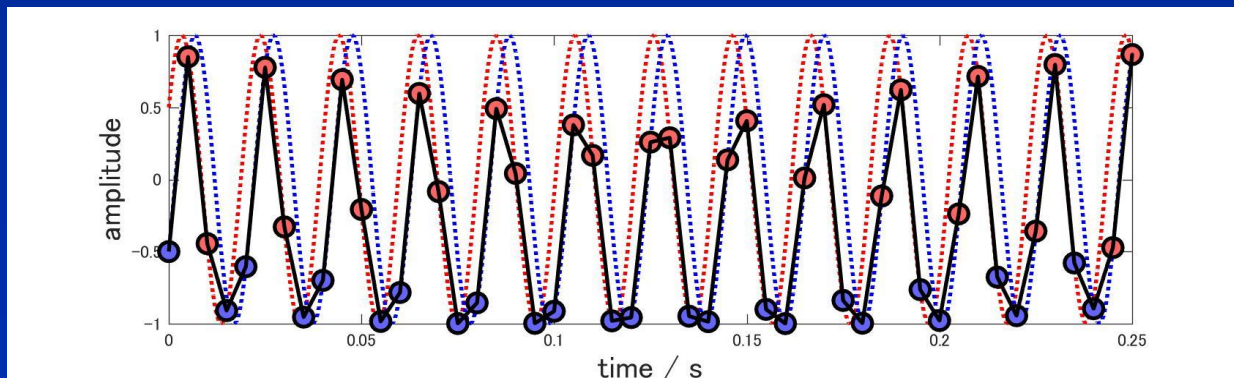
$$X_0 \rightarrow X_0 \rightarrow X_1 \rightarrow X_1$$



$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} n T_s + \varphi_0) & n = 4k - 3, 4k - 2 \\ X_1 = A \sin(2\pi f_{in} n T_s - \varphi_0) & n = 4k - 1, 4k \end{cases}$$

$$\varphi_0 = \frac{\pi}{2N}$$

**Nth order
is cancelled**

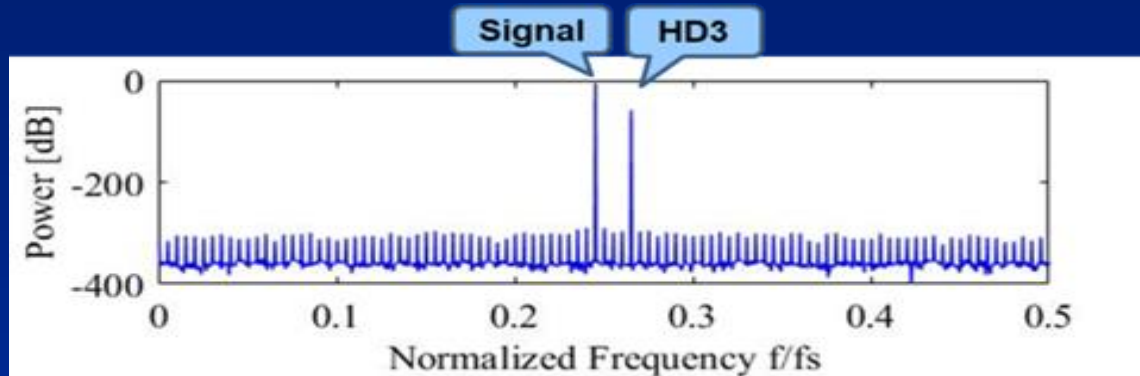


**Spurious components are split into
low and high frequency regions**

Mid Freq. HD3 Suppression

Conventional

$$D_{in} = A \sin(2\pi f_{in} n T_s)$$



$$Y(nT_s) = a_1 D_{in} + a_3 D_{in}^3$$

$$f_{in}/f_s = 49/200,$$

$$A = 1,$$

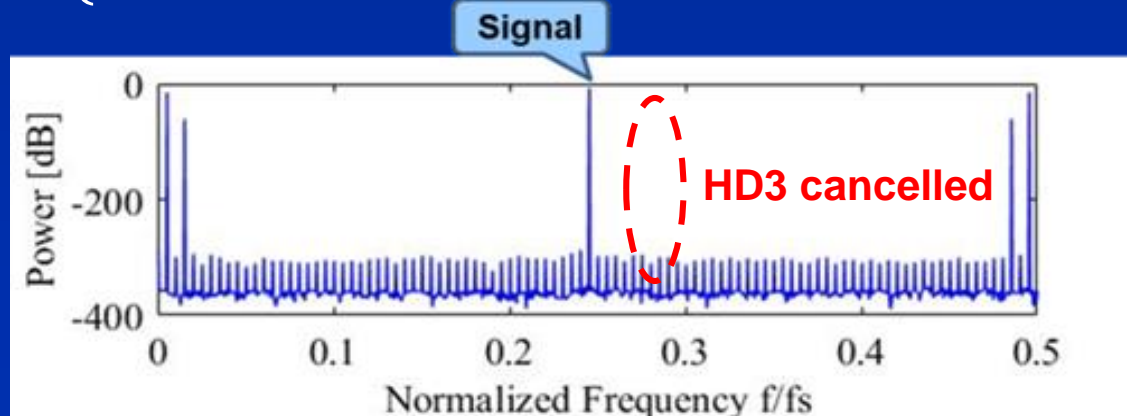
$$a_1 = 1,$$

$$a_3 = -0.01$$

$$\varphi_0 = \frac{\pi}{6}$$

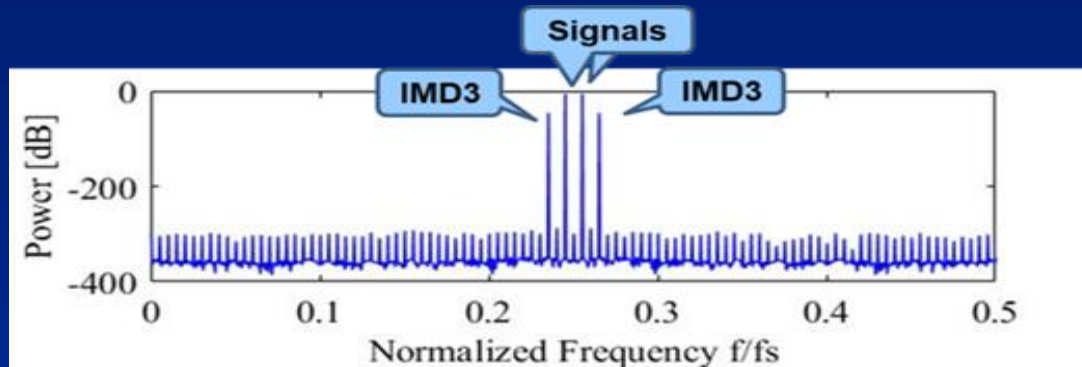
Proposed

$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} n T_s + \varphi_0) & n = 4k - 3, 4k - 2 \\ X_1 = A \sin(2\pi f_{in} n T_s - \varphi_0) & n = 4k - 1, 4k \end{cases}$$



Mid Freq. Two-Tone IMD3 Suppression

Conventional $D_{in} = A \sin(2\pi f_1 n T_s) + B \sin(2\pi f_2 n T_s)$



$$Y(nT_s) = a_1 D_{in} + a_3 D_{in}^3$$

$$f_1/f_s = 49/200,$$

$$f_2/f_s = 51/200$$

$$A = 1,$$

$$B = 1,$$

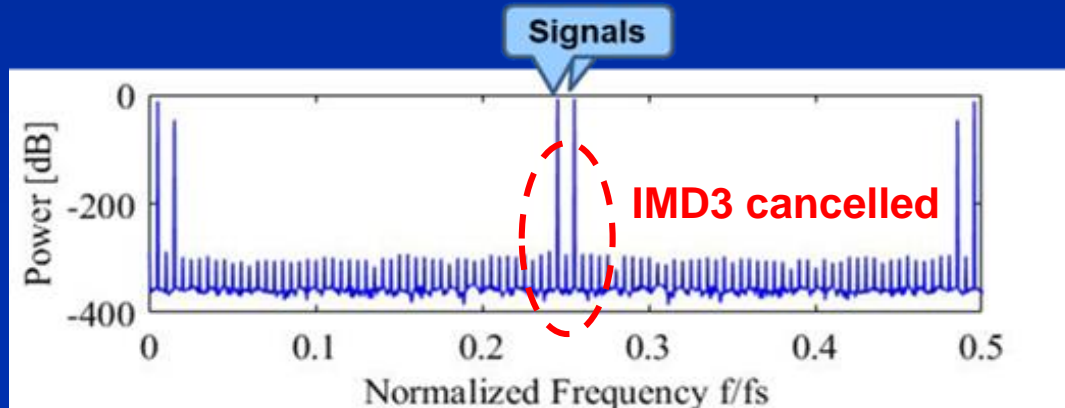
$$a_1 = 1,$$

$$a_3 = -0.01$$

$$\varphi_0 = \frac{\pi}{6}$$

Proposed

$$D_{in} = \begin{cases} X_0 = A \sin(2\pi f_{in} n T_s + \varphi_0) + B \sin(2\pi f_{in} n T_s - \varphi_0) & n = 4k - 3, 4k - 2 \\ X_1 = A \sin(2\pi f_{in} n T_s - \varphi_0) + B \sin(2\pi f_{in} n T_s + \varphi_0) & n = 4k - 1, 4k \end{cases}$$



Outline

- Research Background
- Phase-Switching Method
- Low & High-Frequency Signal Generation
- Mid-Frequency Signal Generation
- **Experimental Results**
- Conclusions

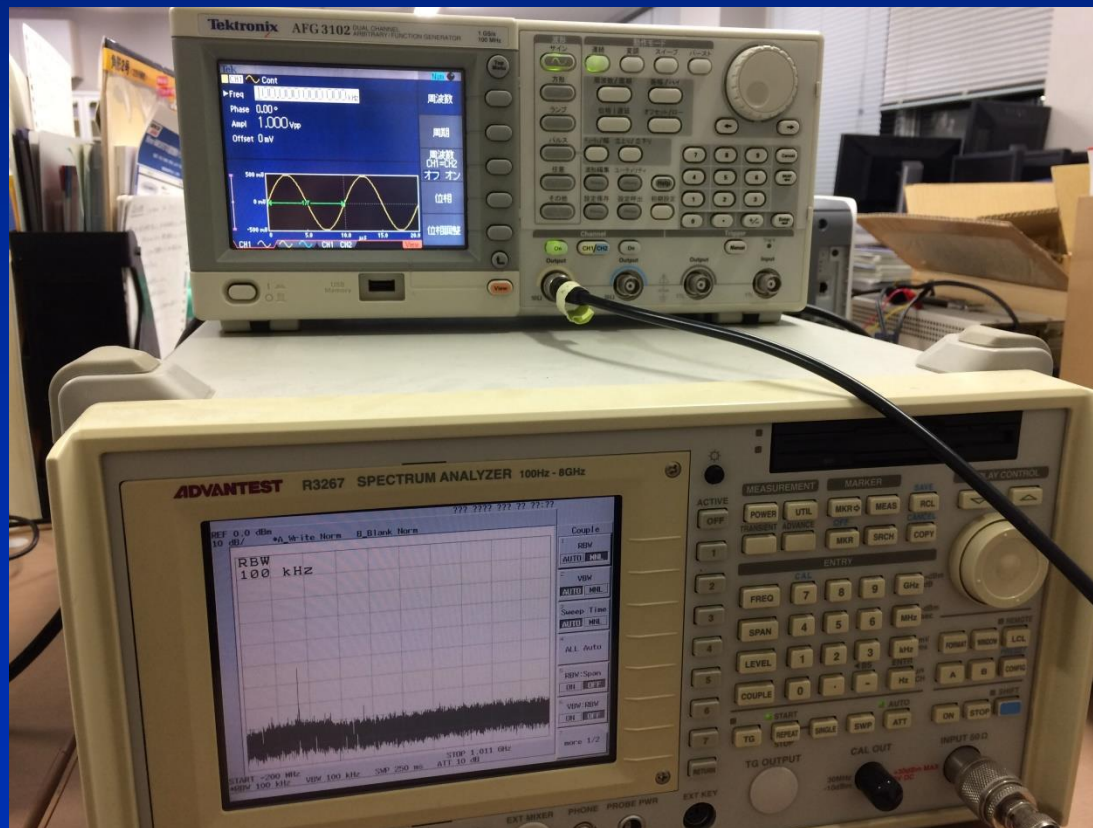
Experiment using AWG

AWG

(Tektronix TDS1001C-EDU, MAX 40MHz, 500Msample/s)

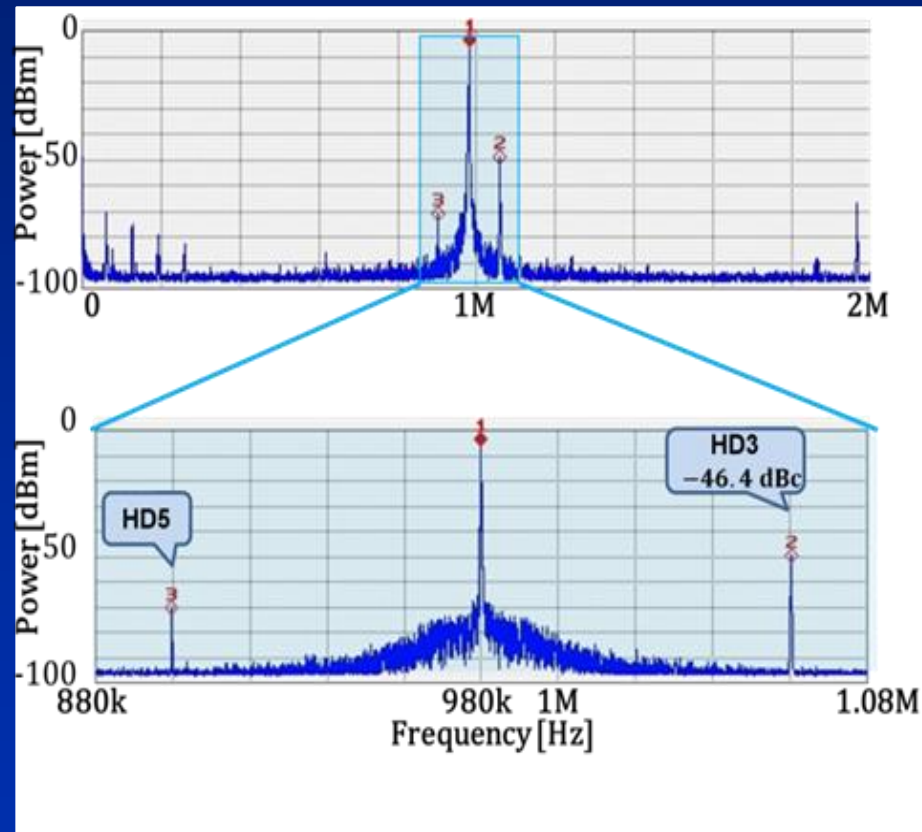
Spectrum analyzer

(Advantest R3267, Measurable band 100Hz – 8GHz)

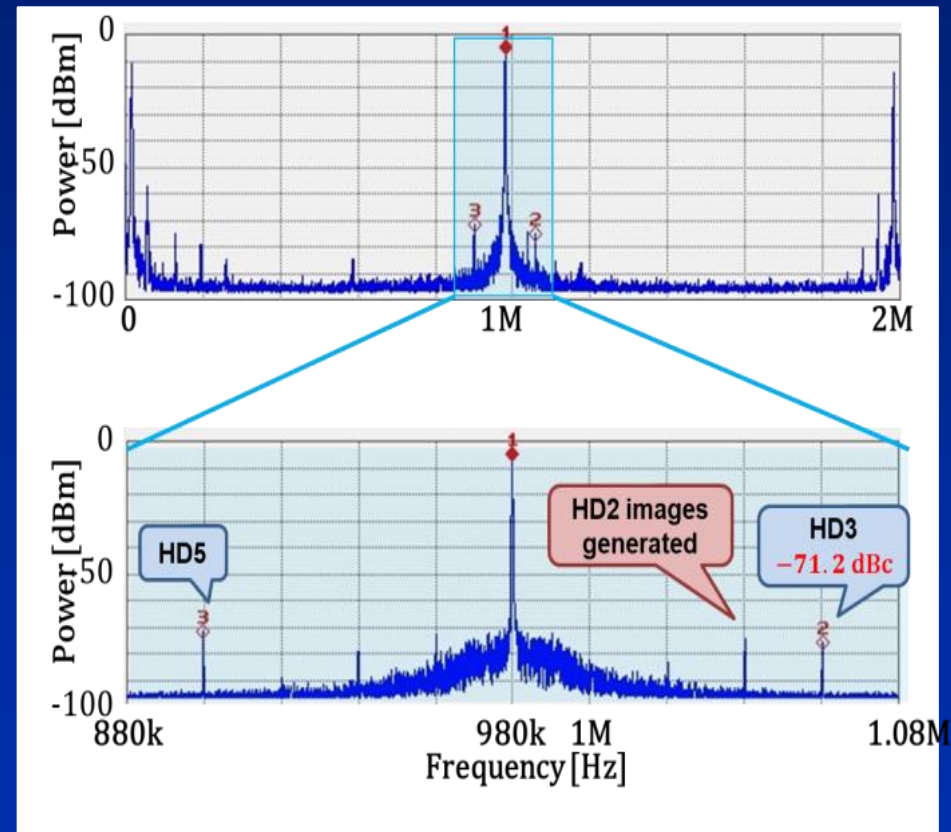


Mid Freq. HD3 Suppression

Conventional Method



Proposed Method

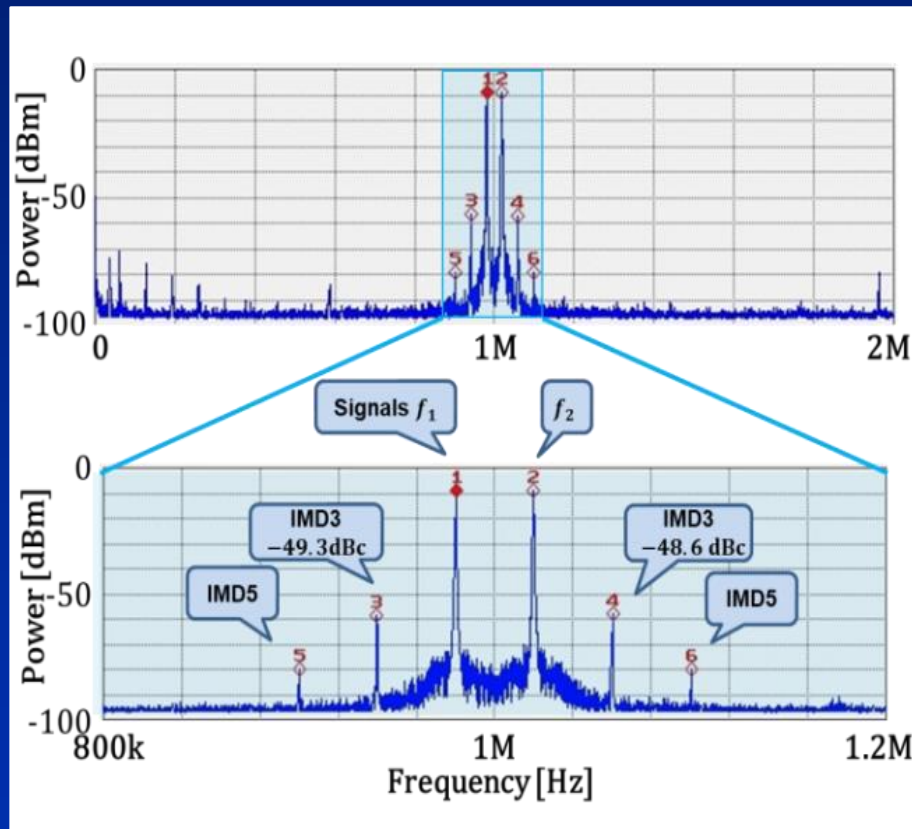


$$f_s = 4\text{MHz},$$

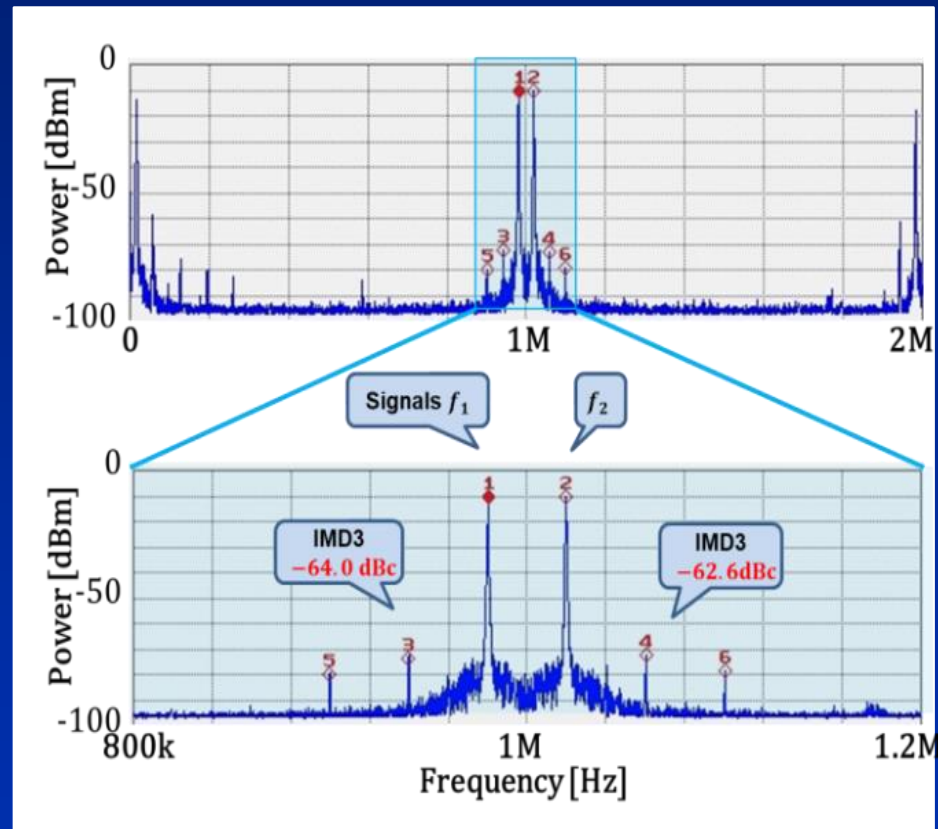
$$f_{in} = 980\text{kHz}$$

Mid Freq. Two-Tone IMD3 Suppression

Conventional Method



Proposed Method



$$f_s = 4\text{MHz}, \quad f_1 = 980\text{kHz}, \quad f_2 = 1020\text{kHz}$$

Outline

- Research Background
- Phase-Switching Method
- Low & High-Frequency Signal Generation
- Mid-Frequency Signal Generation
- Experimental Results
- Conclusions

Conclusions

- We have proposed **Mid-Freq.** single/two-tone signal generation algorithms
- Simulation/experimental verification shows their effectiveness
- In conjunction with previous research, we have completed **Full Nyquist Range** low-distortion signal generation method