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## Purpose of Research & Background

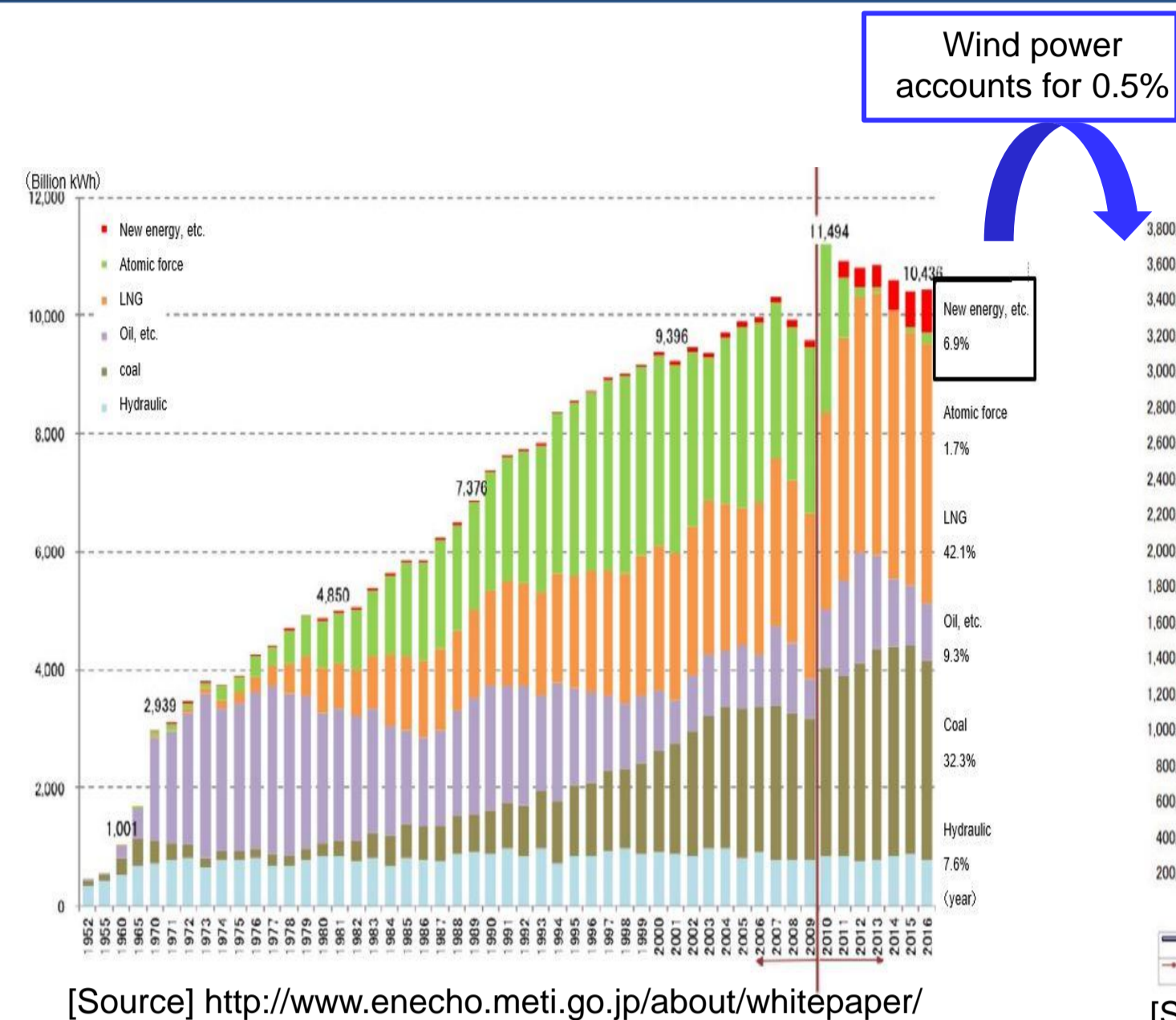
### Research Background

Global warming is a global problem. Reduction of greenhouse gases is necessary.

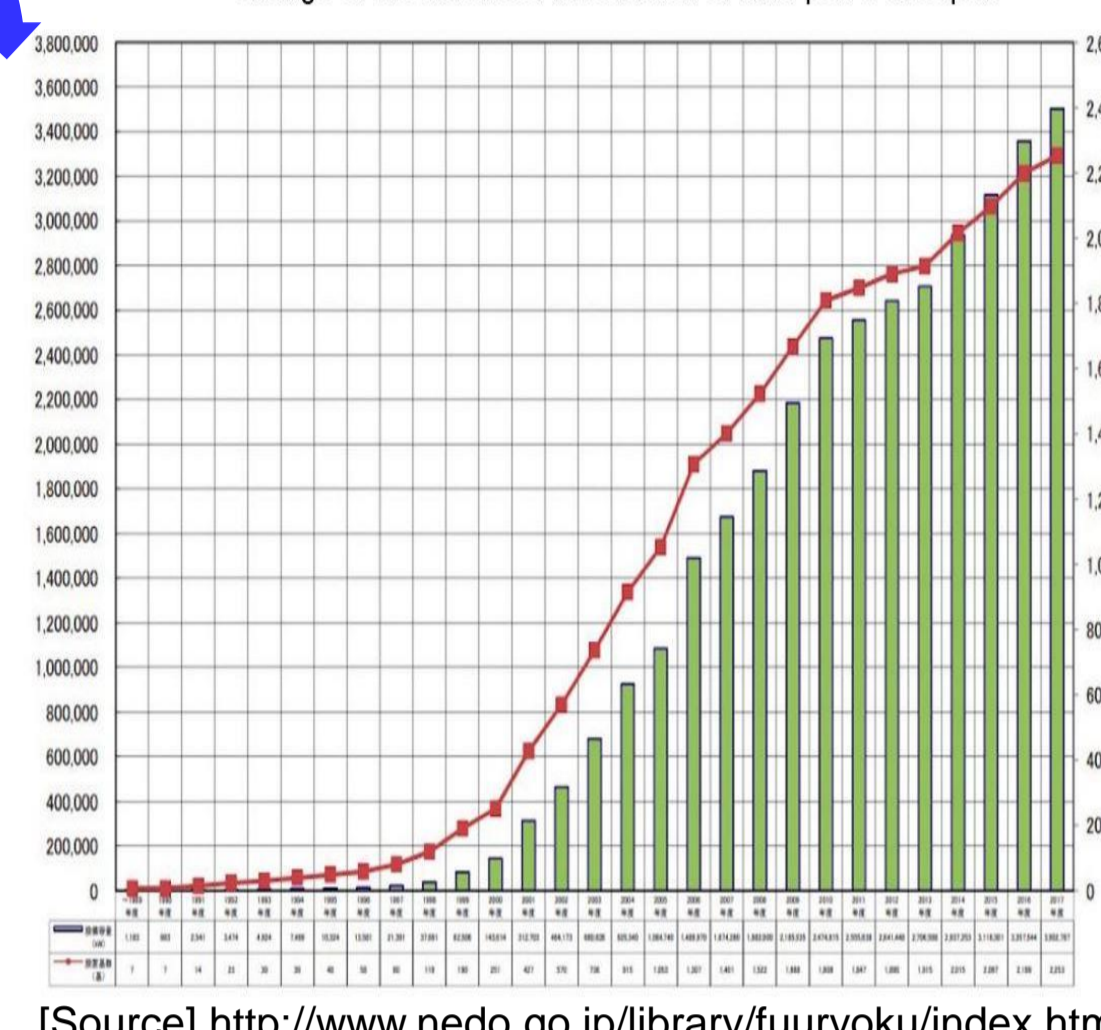
The use of renewable energy and decentralized power generation is effective.

Wind power generation is one of a effective solution.

### Japan's Energy Distribution



Change of the amount of introduction of wind power in Japan



Offshore wind power generation is attracting attention as a new energy source in Japan.



[Source] <https://www.mugendai-web.jp/archives/933>

## Scope of This Research

### Ford Types of Wind Turbine

	Lift Type	Drag Type
Vertical Axis Type		
Horizontal Axis Type		

Can be placed on the bottom of the wind turbine such as a generator  
→Stable

It is necessary to follow the change of the wind direction

Rotate quickly.  
→Power generation

High torque  
→Ventilation, Pumping, For startup.

### Characteristics of VAWT

#### Advantages of Vertical axis type

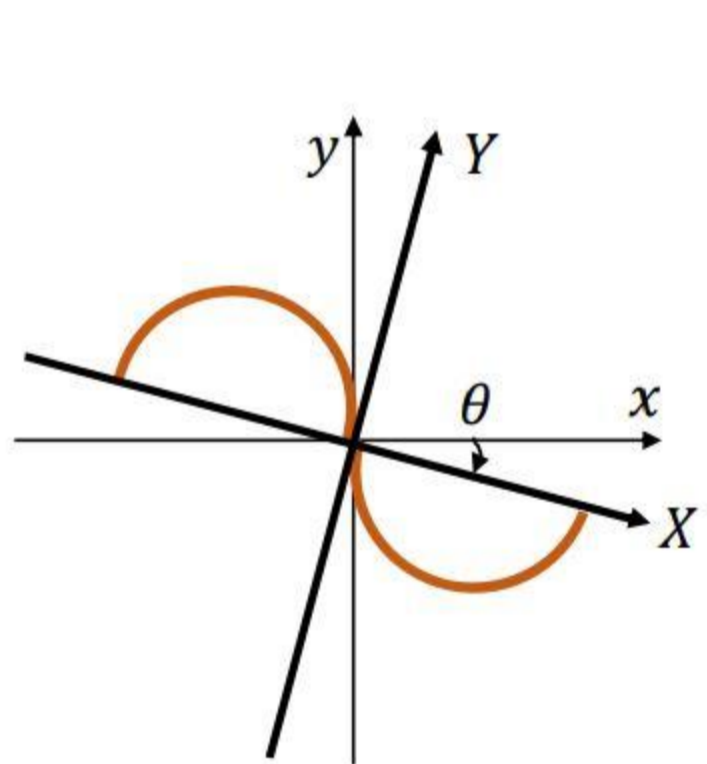
- Simple construction with low cost
- Wind acceptance from any direction for the operation
- Low noise and angular velocity in operation
- Reduced wear on moving parts
- Various rotor configuration options
- High static and dynamic moment

#### Purpose of This Work

The optimum shape of a 2-stage Savonius wind turbine (one of a VAWT) is examined using a simulation technique for fluid phenomena.

## Numerical Method

### Wind Turbine Calculation Formula



$$\frac{\partial U}{\partial X} + \frac{\partial V}{\partial Y} + \frac{\partial W}{\partial Z} = 0$$

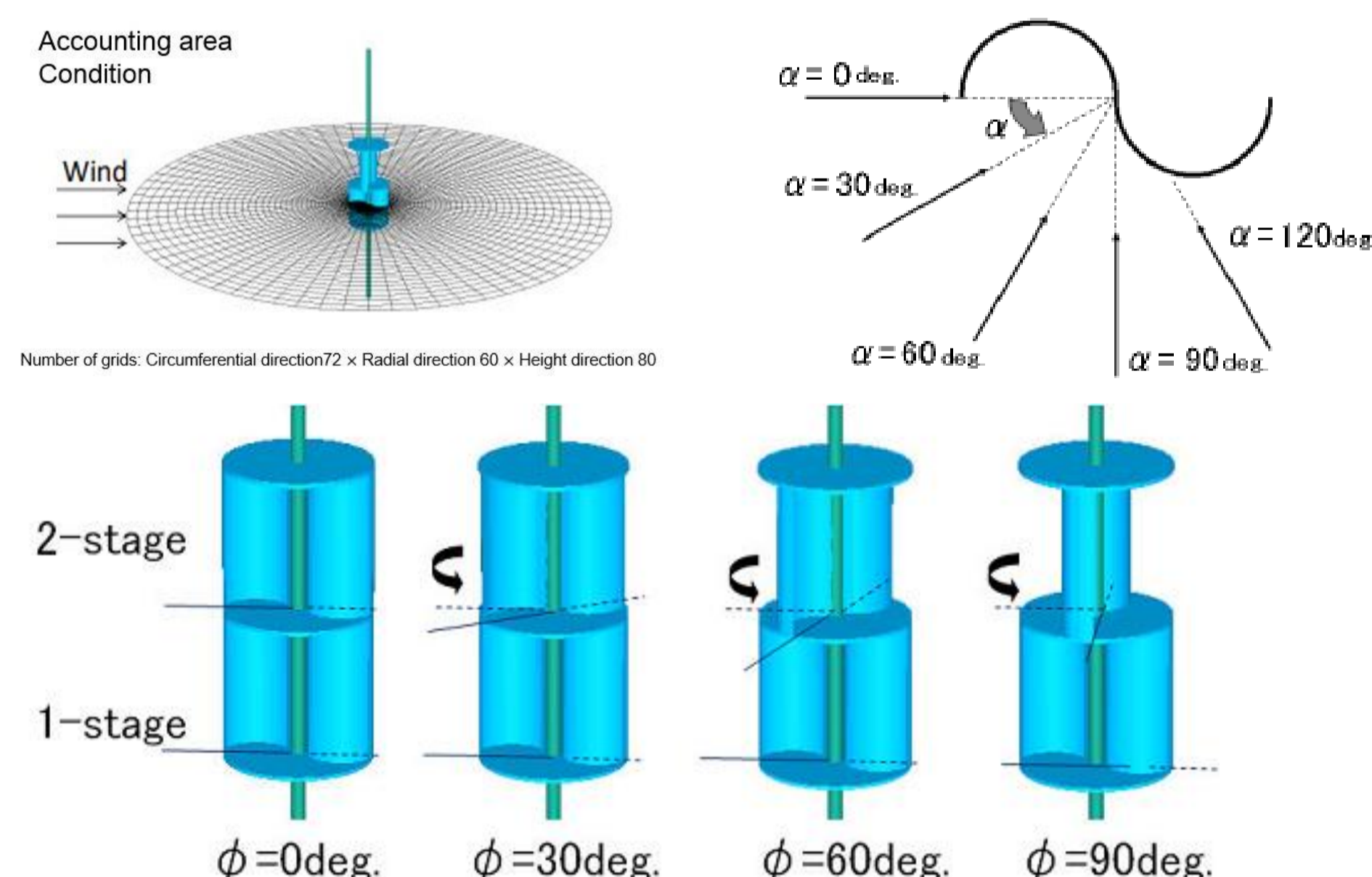
$$\frac{\partial U}{\partial t} + U \frac{\partial U}{\partial X} + V \frac{\partial U}{\partial Y} + W \frac{\partial U}{\partial Z} - \omega^2 X + 2\omega V = -\frac{\partial p}{\partial X} + \frac{1}{Re} \left( \frac{\partial^2 U}{\partial X^2} + \frac{\partial^2 U}{\partial Y^2} + \frac{\partial^2 U}{\partial Z^2} \right)$$

$$\frac{\partial V}{\partial t} + U \frac{\partial V}{\partial X} + V \frac{\partial V}{\partial Y} + W \frac{\partial V}{\partial Z} - \omega^2 Y - 2\omega U = -\frac{\partial p}{\partial Y} + \frac{1}{Re} \left( \frac{\partial^2 V}{\partial X^2} + \frac{\partial^2 V}{\partial Y^2} + \frac{\partial^2 V}{\partial Z^2} \right)$$

$$\frac{\partial W}{\partial t} + U \frac{\partial W}{\partial X} + V \frac{\partial W}{\partial Y} + W \frac{\partial W}{\partial Z} = -\frac{\partial p}{\partial Z} + \frac{1}{Re} \left( \frac{\partial^2 W}{\partial X^2} + \frac{\partial^2 W}{\partial Y^2} + \frac{\partial^2 W}{\partial Z^2} \right)$$

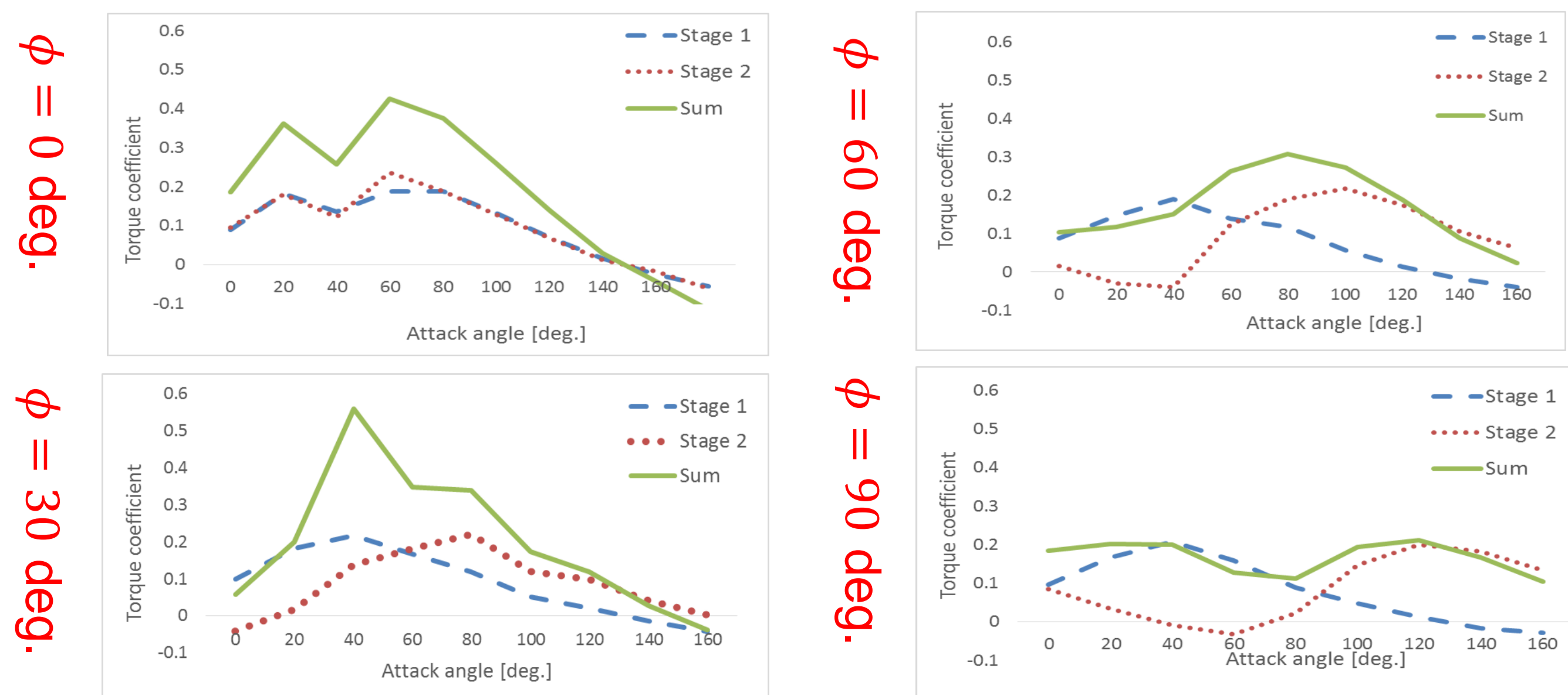
(X, Y, Z) : Position component in rotational coordinate system  
 (U, V, W) : Velocity component in rotational coordinate system  
 p : Pressure t : Time ω : Angular velocity of wind turbine  
 Re : Reynolds number based on wind turbine radius and uniform flow (= 10<sup>5</sup>)

### Condition of Simulation

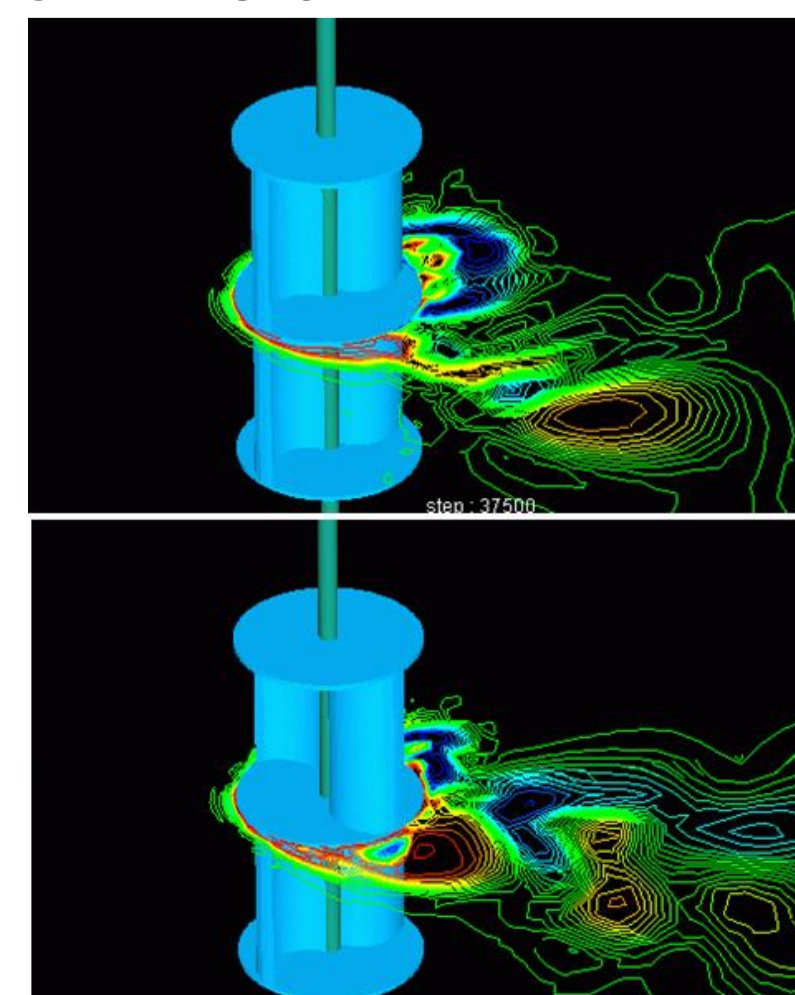


## Simulation Results

### Comparison of Simulation Results



### Flow Field



## Summary

The wind turbine has the highest torque coefficient compared to other wind turbines when φ is 30 degrees. When the torque coefficient is negative, the wind turbine can not be start to rotate. The torque coefficients of Stage 1 and Stage 2 are canceled, and the total torque does not become negative when φ is more than 60 degrees.

J.V. Akwa, H.A. Vielmo, A. Prisco "A review on the performance of Savonius wind turbines" Renewable and Sustainable Energy Reviews, 16 (5) (2012), pp. 3054-3064