



Overshoot Cancellation Based on Balanced Charge-Discharge Time Condition for Buck Converter in Mobile Applications

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Outline

1. Research Background

- **Applications of Switching Power Supply**
- **Basic Switching Converter Architecture**

2. Analysis of Step-down Switching Converter

- **Conventional Classical Technique**
- **Superposition Principle**

3. Proposed Design of Buck Converter

- **Overshoot Improvement with Parallel RLC Network**
- **Experimental Results**

4. Conclusions

1. Research Background

Research Objective & Approach

Objective

Development of switching power supply with

- Fast response & high efficiency
- Low EMI noise
- Small output ripple

Approach

- Analysis of buck converter system based on **classical technique** and **superposition principle**
- Overshoot reduction using **parallel RLC network**

1. Research Background

Design Achievements of This Work

Condition for overshoot cancelation

Balanced charge-discharge time

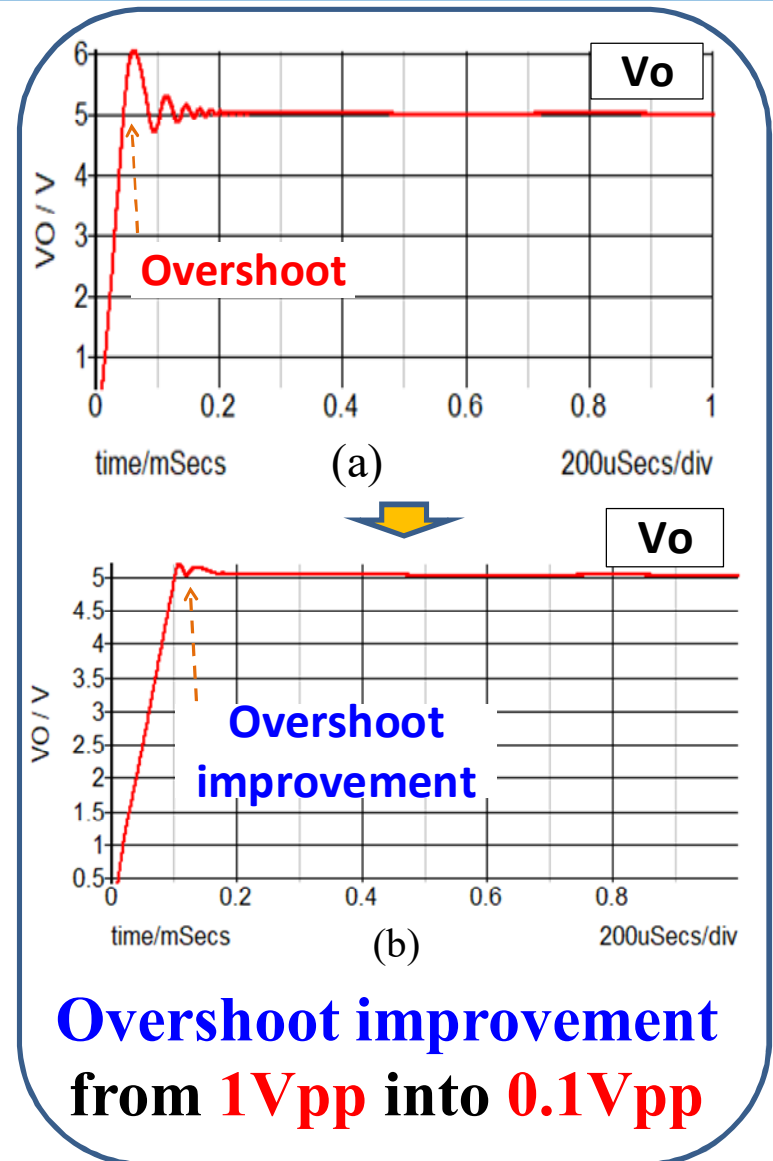
$$|Z_L| = |Z_C| = 2R \Rightarrow \omega L = \frac{1}{\omega C} = 2R$$

$$\text{Here, } \omega = \frac{1}{\sqrt{LC}} = \frac{1}{2RC}$$

Imbalance of charge-discharge time

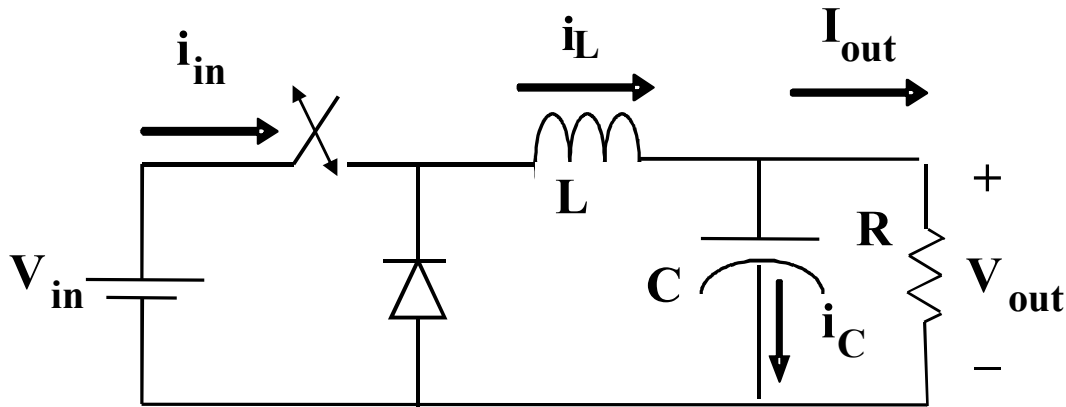


Overshoot improvement
with parallel RLC



1. Research Background

Basic Switching Converter Architecture



Basic Switching Converter

Merits

- Downsizing
- Light Weight
- High Efficiency



High Efficiency Switching



- ➔ Reduce energy consumption
- ➔ Extend battery operating time
- ➔ Minimize costs of systems

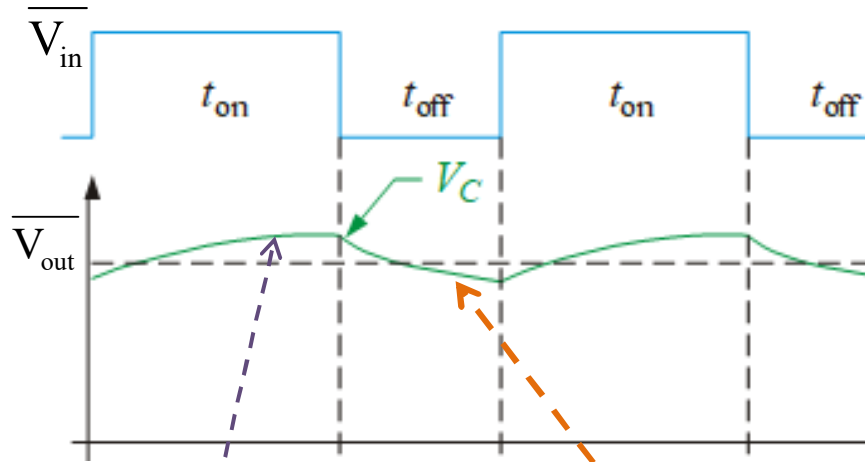
Demerits



- Output Ripple
- Switching noise
- Harmonic noise

1. Research Background

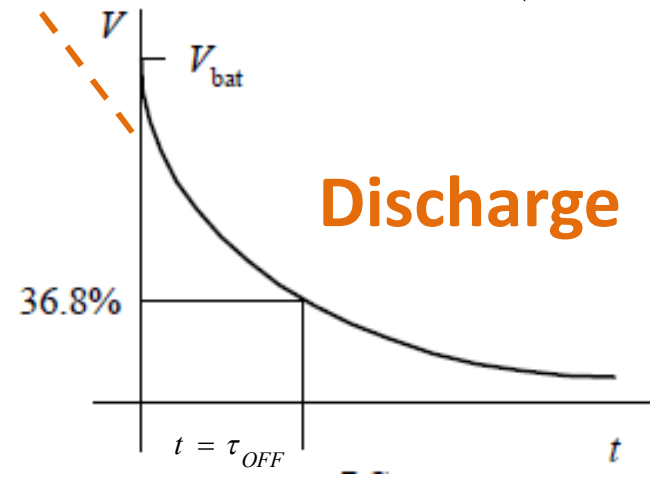
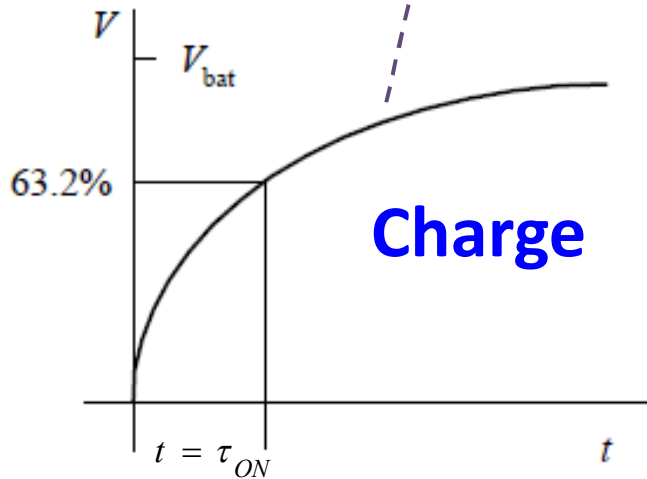
Switching Regulator



**Independence of
PWM Frequency**



$$\overline{V}_{out} = \frac{T_{ON}}{(T_{ON} + T_{OFF})} \overline{V}_{in}$$



$$V_{Charge}(t_i) = \overline{V}_{discharge}(t_{i-1}) \left(1 - e^{\frac{-t}{\tau_{ON}}} \right)$$

$$V_{discharge}(t_i) = \overline{V}_{charge}(t_i) e^{\frac{-t}{\tau_{OFF}}}$$

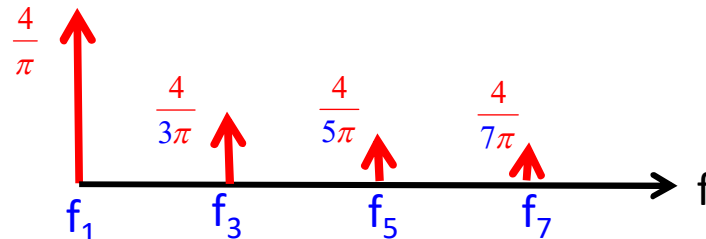
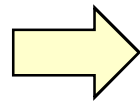
1. Research Background

Harmonics of PWM Signals

50% Duty Cycle



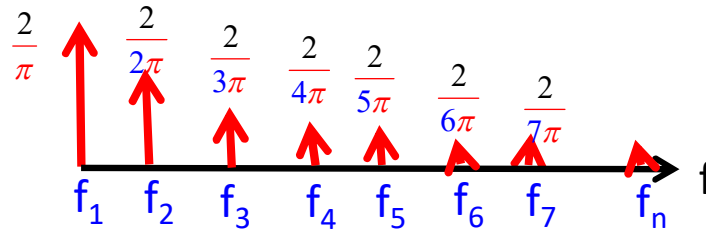
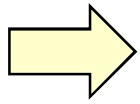
$$S_{PWM}(t) = \frac{4}{\pi} \left(\sin(2\pi ft) + \frac{1}{3} \sin(3 \cdot 2\pi ft) + \frac{1}{5} \sin(5 \cdot 2\pi ft) + \dots \right)$$



75% Duty Cycle



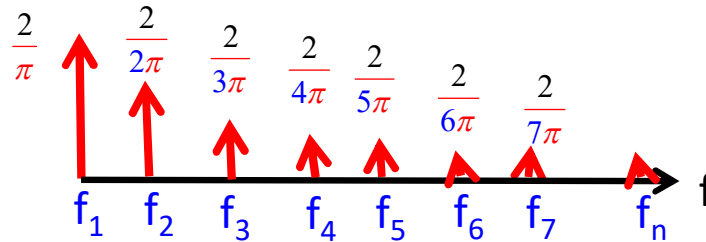
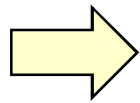
$$S_{PWM}(t) = \frac{4}{\pi} \left(\sin(2\pi ft) + \frac{1}{2} \sin(2 \cdot 2\pi ft) + \frac{1}{3} \sin(3 \cdot 2\pi ft) + \frac{1}{4} \sin(4 \cdot 2\pi ft) + \frac{1}{5} \sin(5 \cdot 2\pi ft) + \dots \right)$$



25% Duty Cycle




$$S_{PWM}(t) = \frac{4}{\pi} \left(\sin(2\pi ft) - \frac{1}{2} \sin(2 \cdot 2\pi ft) + \frac{1}{3} \sin(3 \cdot 2\pi ft) - \frac{1}{4} \sin(4 \cdot 2\pi ft) + \frac{1}{5} \sin(5 \cdot 2\pi ft) + \dots \right)$$



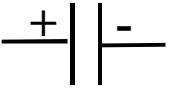
2. Analysis of Step-down Switching Converter

Conventional Classical Technique

Inductor L $\xrightarrow{i(t)}$ 

Magnetic energy

$$i(t) = \frac{1}{L} \int_{-\infty}^{t_0} v(\tau) d\tau + \frac{1}{L} \int_{t_0}^t v(\tau) d\tau$$
$$= i(t_0^-) + \frac{1}{L} \int_{t_0}^t v(\tau) d\tau$$

Capacitor C $\begin{matrix} v(t) \\ + | | - \end{matrix}$ 

Electric energy

$$v(t) = \frac{1}{C} \int_{-\infty}^{t_0} i(\tau) d\tau + \frac{1}{C} \int_{t_0}^t i(\tau) d\tau$$
$$= v(t_0^-) + \frac{1}{C} \int_{t_0}^t i(\tau) d\tau$$

- **Advantages**

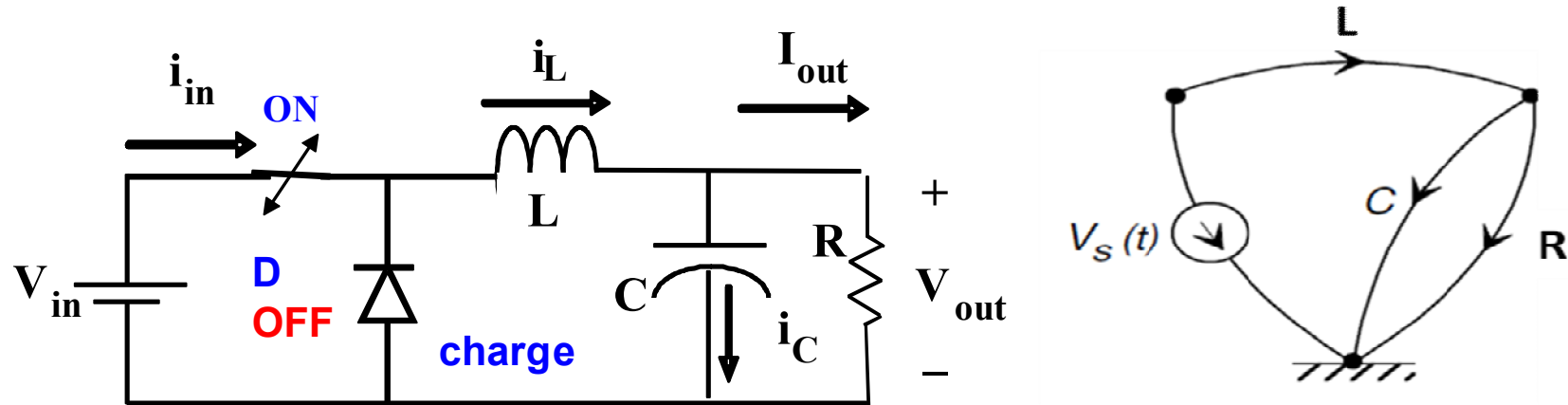
- Converts differential equation into algebraic equation.
- Rapidly provides stability & transient response.

- **Disadvantages**

- Applicable only to **Linear, Time-Invariant (LTI)** systems

2. Analysis of Step-down Switching Converter

Linear Graph of Buck Converter (Switch ON)



$$\begin{bmatrix} \dot{i}_L(t) \\ \dot{v}_C(t) \end{bmatrix} = \begin{bmatrix} 0 & -\frac{1}{L} \\ \frac{1}{C} & -\frac{1}{RC} \end{bmatrix} \begin{bmatrix} i_L(t) \\ v_C(t) \end{bmatrix} + \begin{bmatrix} \frac{1}{L} \\ 0 \end{bmatrix} v_i(t) \quad y(t) = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} i_L(t) \\ v_C(t) \end{bmatrix} + \begin{bmatrix} 0 \end{bmatrix} v_i(t)$$

$$\begin{cases} \frac{1}{L} V_C(s) + sC \left(s + \frac{1}{RC} \right) V_C(s) = \frac{1}{L} V_i(s) \\ I_L(s) = C \left(s + \frac{1}{RC} \right) V_C(s) \end{cases}$$

2. Analysis of Step-down Switching Converter

Analysis of Buck Converter (Switch ON)

$$V_C(s) = \frac{\frac{1}{LC}}{\left(s^2 + \frac{s}{RC} + \frac{1}{LC}\right)} V_i(s)$$

$$s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0$$

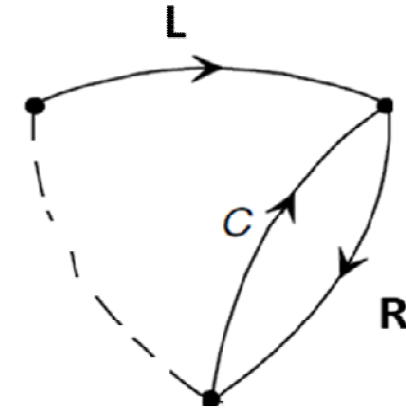
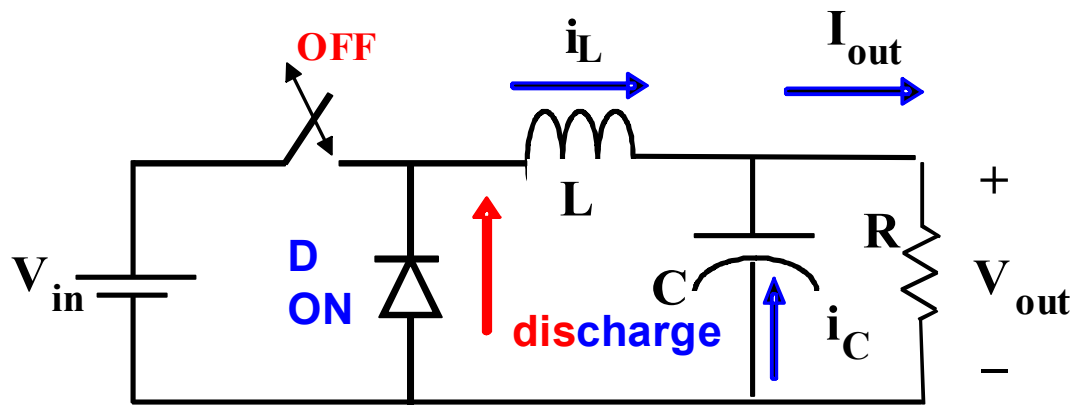
$$s_1 = -\frac{1}{2RC} + \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}} \quad \vee \quad s_2 = -\frac{1}{2RC} - \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}}$$

$$\omega_{2RC} = \frac{1}{2RC}; \omega_{LC} = \frac{1}{\sqrt{LC}};$$

$$V_{charge}(t) = A_{ch1} e^{\left(-\omega_{2RC} + \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2}\right)t} + A_{ch2} e^{\left(-\omega_{2RC} - \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2}\right)t}$$

2. Analysis of Step-down Switching Converter

Linear Graph of Buck Converter (Switch OFF)



$$\begin{bmatrix} \dot{i}_L(t) \\ \dot{v}_C(t) \end{bmatrix} = \begin{bmatrix} 0 & -\frac{1}{L} \\ -\frac{1}{C} & -\frac{1}{RC} \end{bmatrix} \begin{bmatrix} i_L(t) \\ v_C(t) \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix} v_i(t)$$

$$y(t) = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} i_L(t) \\ v_C(t) \end{bmatrix} + \begin{bmatrix} 0 \end{bmatrix} v_i(t)$$

$$\begin{cases} \frac{1}{L} V_C(s) - sC \left(s + \frac{1}{RC} \right) V_C(s) = 0 \\ I_L(s) = -C \left(s + \frac{1}{RC} \right) V_C(s) \end{cases}$$

2. Analysis of Step-down Switching Converter

Analysis of Buck Converter (Switch OFF)

$$\left(s^2 - \frac{s}{RC} + \frac{1}{LC} \right) V_C(s) = 0$$

$$s^2 - \frac{1}{RC}s + \frac{1}{LC} = 0$$

$$s_{dis1} = \frac{1}{2RC} + \sqrt{\left(\frac{1}{2RC} \right)^2 - \frac{1}{LC}} \quad \vee \quad s_{dis2} = \frac{1}{2RC} - \sqrt{\left(\frac{1}{2RC} \right)^2 - \frac{1}{LC}}$$

$$\omega_{2RC} = \frac{1}{2RC}; \omega_{LC} = \frac{1}{\sqrt{LC}};$$

$$V_{discharge}(t) = A_{dis1} e^{\left(\omega_{2RC} + \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2} \right) t} + A_{dis2} e^{\left(\omega_{2RC} - \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2} \right) t}$$

2. Analysis of Step-down Switching Converter

Balanced Charge-Discharge Time Condition

$$\overline{V}_{out} = \frac{1}{(T_{ON} + T_{OFF})} \left(\int_0^{T_{ON}} \left(A_{ch1} e^{\left(-\omega_{2RC} + \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2}\right)t} + A_{ch2} e^{\left(-\omega_{2RC} - \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2}\right)t} \right) dt + \int_{T_{ON}}^{T_{ON} + T_{OFF}} \left(A_{dis1} e^{\left(\omega_{2RC} + \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2}\right)t} + A_{dis2} e^{\left(\omega_{2RC} - \sqrt{(\omega_{2RC})^2 - \omega_{LC}^2}\right)t} \right) dt \right)$$

$$\omega_{2RC} = \omega_{LC} \Leftrightarrow \omega = \frac{1}{\sqrt{LC}} = \frac{1}{2RC}$$

$$\omega L = \frac{1}{\omega C} = 2R$$

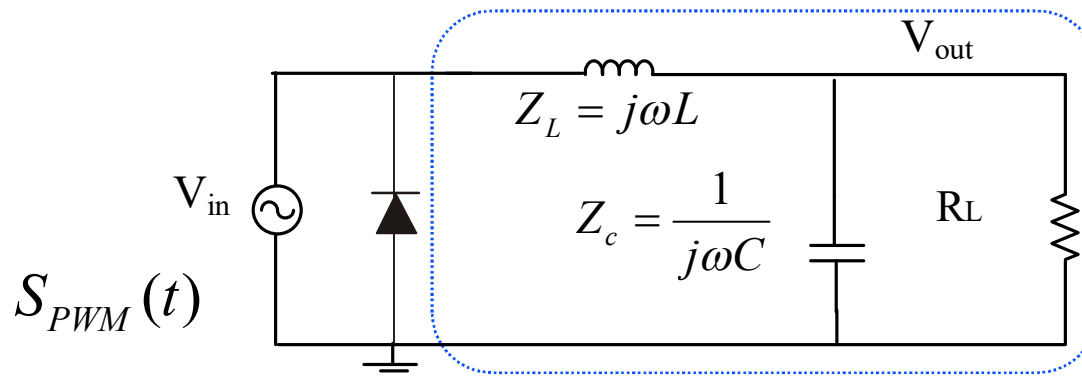
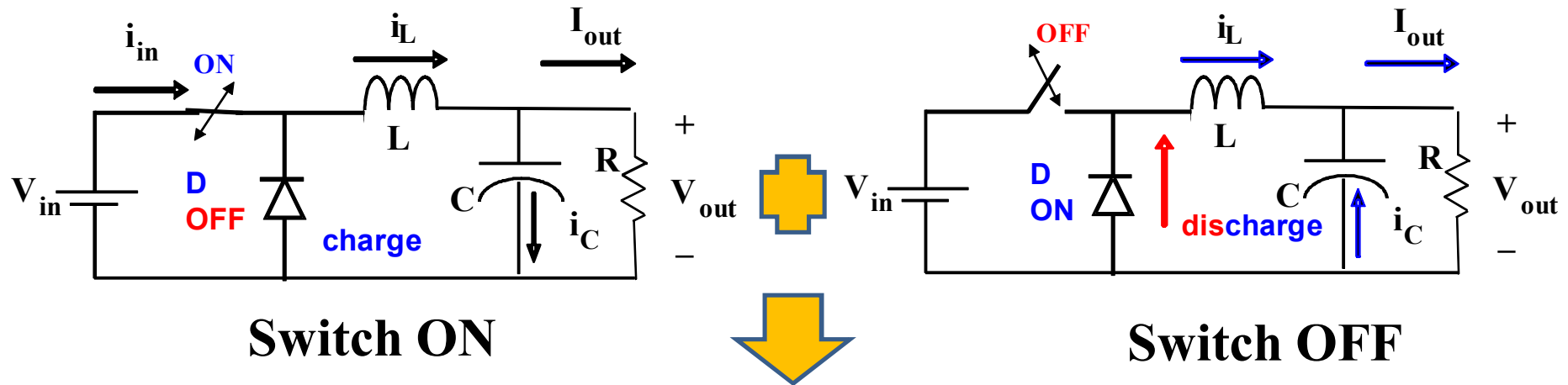
$$|Z_L| = |Z_C| = 2R$$

**Balanced Charge-Discharge
Time Condition**

$$\overline{V}_{out} = \frac{1}{(T_{ON} + T_{OFF})} \left(\int_0^{T_{ON}} A_{ch} e^{-\omega t} dt + \int_{T_{ON}}^{T_{ON} + T_{OFF}} A_{dis} e^{\omega t} dt \right)$$

2. Analysis of Step-down Switching Converter

Proposed Analysis Model of Buck Converter



Model of Buck Converter

2. Analysis of Step-down Switching Converter

Definition of Widened Superposition Principle

A superposition of energy at *one place* is proportional with **their input sources and resistance distances of transmission spaces.**

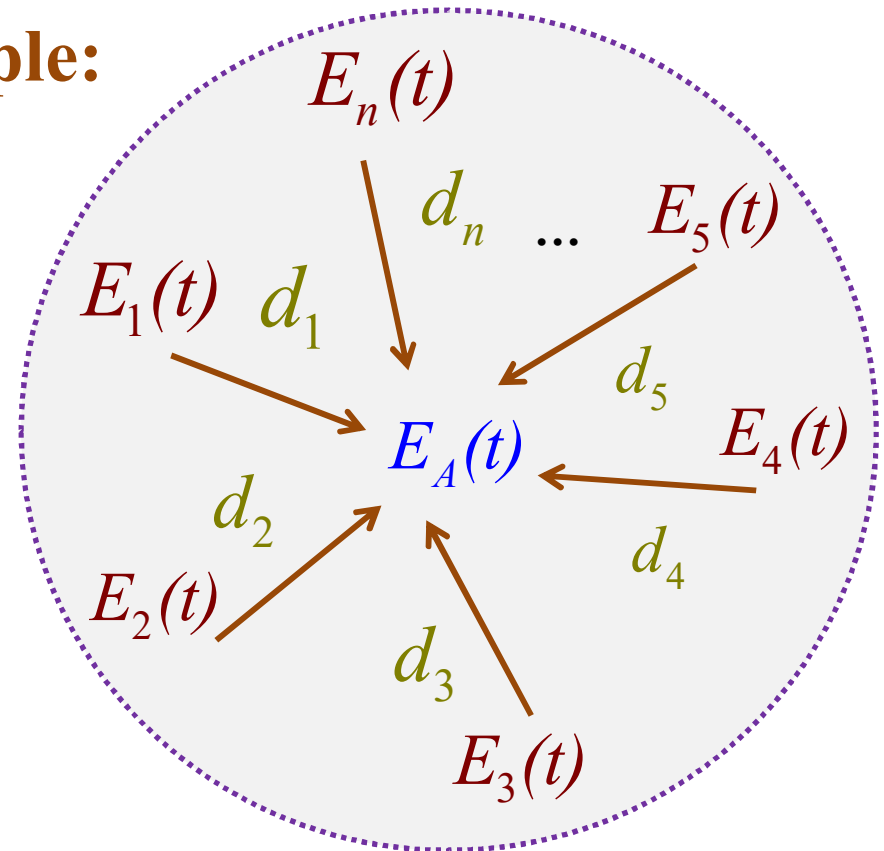
Widened Superposition Principle:

$$E_A(t) \sum_{i=1}^n \frac{1}{d_i} = \sum_{i=1}^n \frac{E_i(t)}{d_i}$$

$E_A(t)$: *energy at one place*

$E_i(t)$: *input sources*

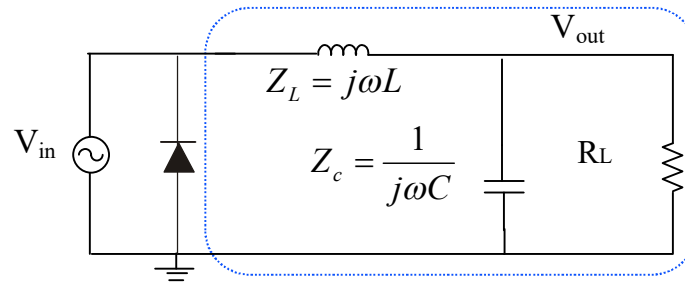
$d_i(t)$: *resistance distances*



2. Analysis of Step-down Switching Converter

Transfer Function of Proposed Analysis Model

Proposed analysis model



$$E_A(t) \sum_{i=1}^n \frac{1}{d_i} = \sum_{i=1}^n \frac{E_i(t)}{d_i}$$

Superposition principle

$$V_o \left(\frac{1}{Z_L} + \frac{1}{Z_C} + \frac{1}{R} \right) = \frac{V_{in}}{Z_L}$$

Output Voltage

$$V_o = V_{in} \frac{RZ_C}{R(Z_L + Z_C) + Z_L Z_C}$$

Transfer Function

$$H = \frac{V_o}{V_{in}} = \frac{RZ_C}{R(Z_L + Z_C) + Z_L Z_C}$$

$$H(j\omega) = \frac{1}{LC} \frac{1}{(j\omega)^2 + j\omega \frac{1}{RC} + \frac{1}{LC}}$$

2. Analysis of Step-down Switching Converter

Condition for Max Power Propagation

Transfer Function

$$H(j\omega) = \frac{\frac{1}{LC}}{(j\omega)^2 + j\omega \frac{1}{RC} + \frac{1}{LC}}$$
$$H(j2\pi f) = \frac{\frac{1}{(2\pi)^2 LC}}{(j * f)^2 + j * f \frac{1}{2\pi RC} + \frac{1}{(2\pi)^2 LC}}$$

$$|H(f)| = \frac{\frac{1}{(2\pi)^2 LC}}{\sqrt{\left(\frac{1}{(2\pi)^2 LC} - f^2\right)^2 + \left(\frac{f}{2\pi RC}\right)^2}}$$

$$|H(f)| = \frac{\frac{1}{(2\pi)^2 LC}}{\left(\frac{1}{4\pi RC}\right)^2 + f^2} \Rightarrow |H(f)| = \frac{1}{2}$$

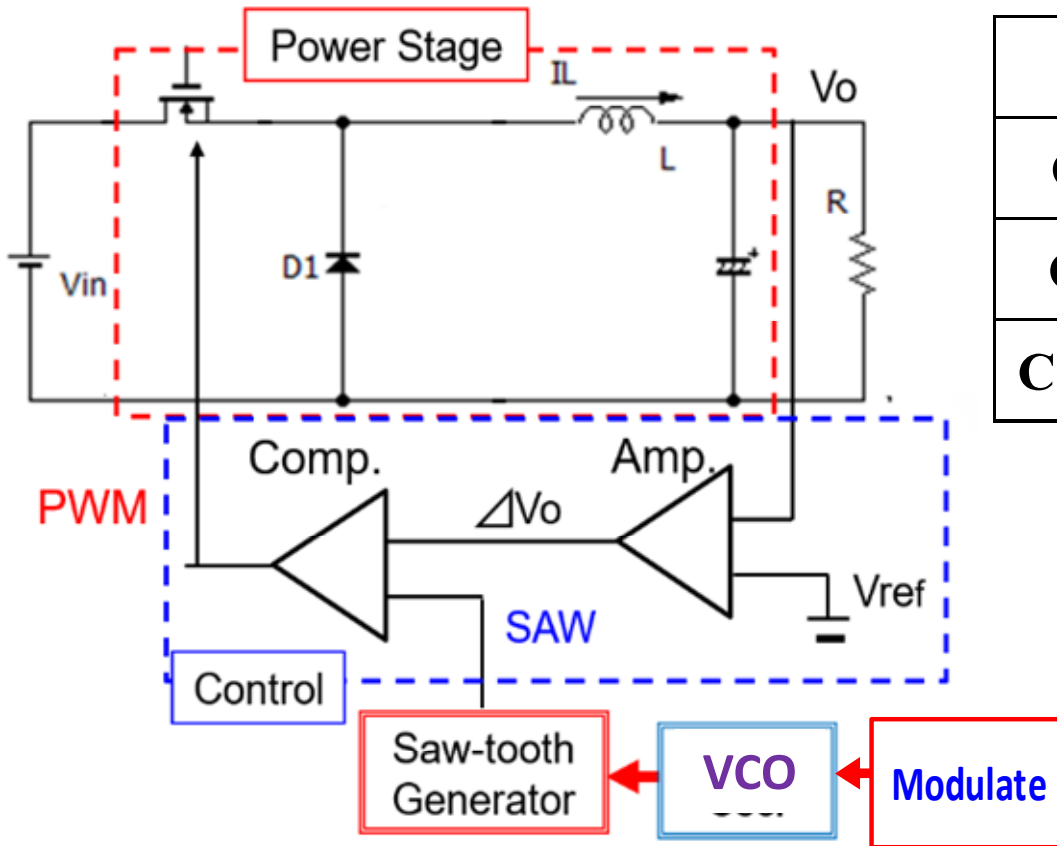
when $f = \frac{1}{4\pi RC} = \frac{1}{2\pi\sqrt{LC}}$

$$|Z_L| = |Z_C| = 2R$$

**Balanced Charge-Discharge
Time Condition**

3. Proposed Design of Buck Converter Conventional Step-down Switching Converter

VCO: Voltage Controlled Oscillator



Input Voltage (V_{in})	12V
Output Voltage (V_o)	5.0V
Output Current (I_o)	1.0A
Clock Frequency (F_{ck})	200kHz

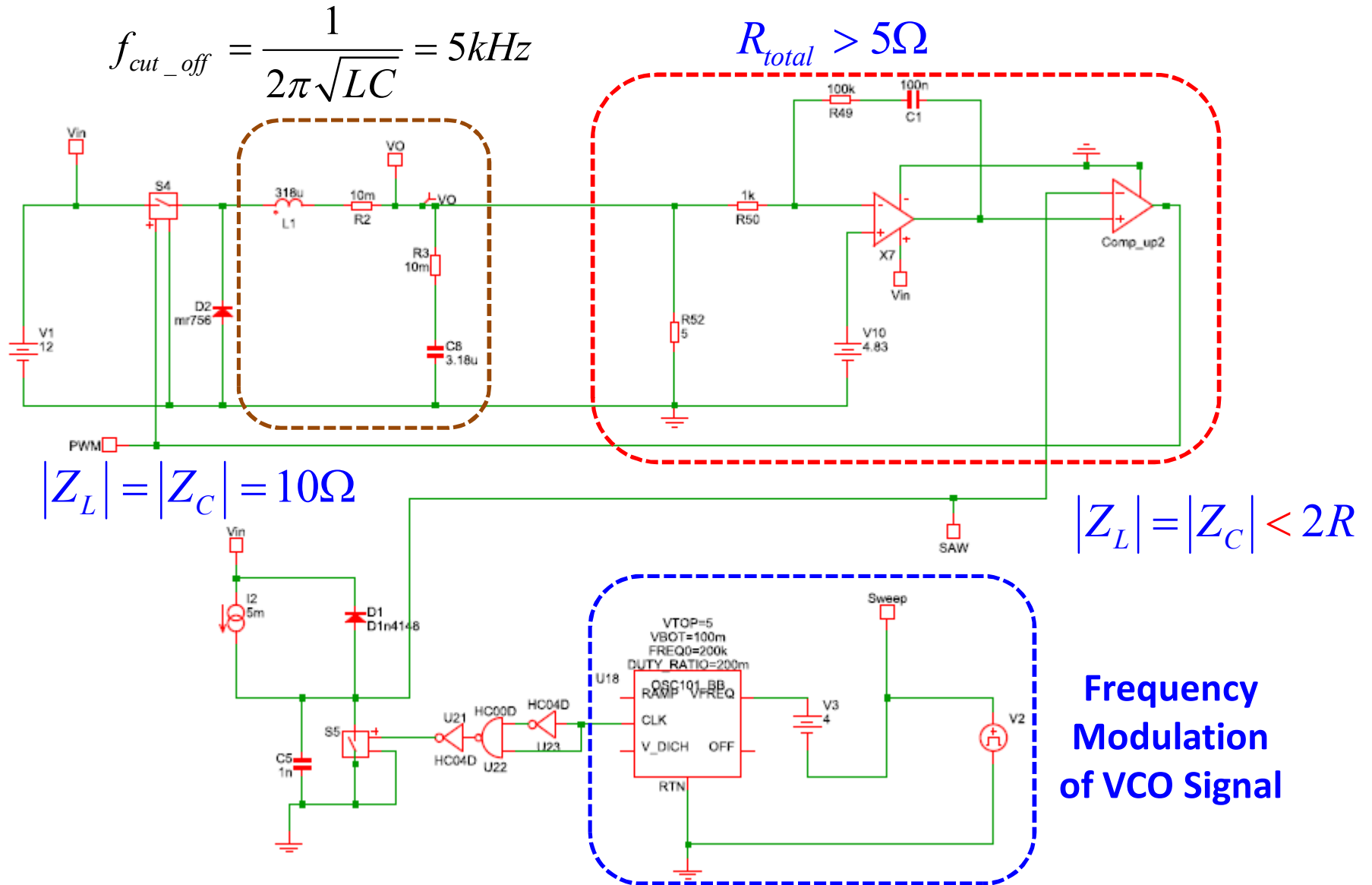
**EMI Reduction using
Spread Spectrum of VCO**

Circuit with Frequency Modulation

3. Proposed Design of Buck Converter

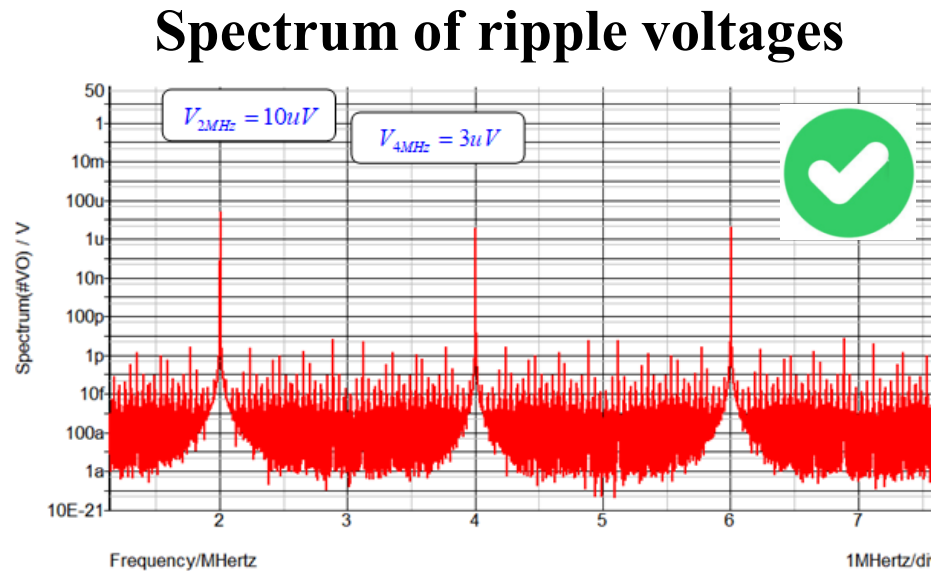
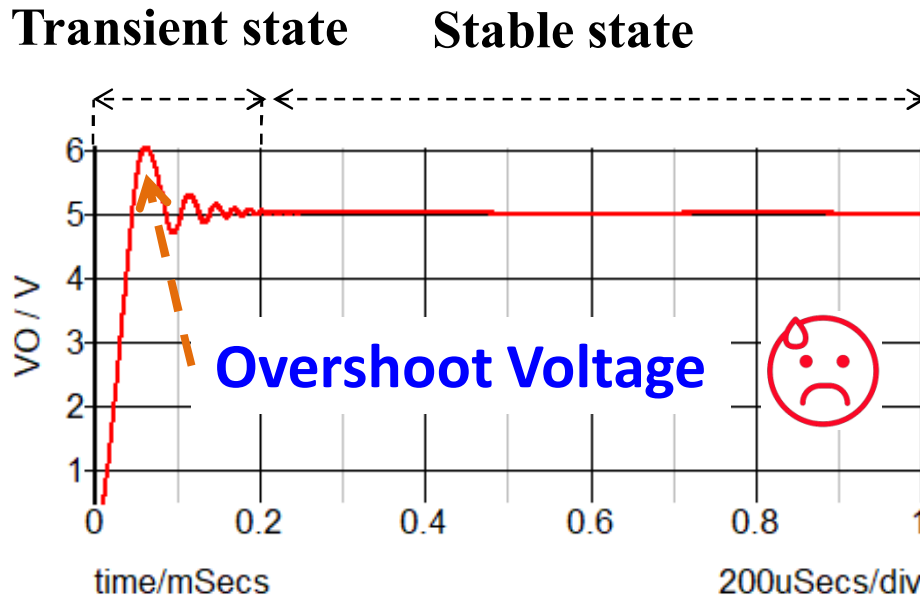
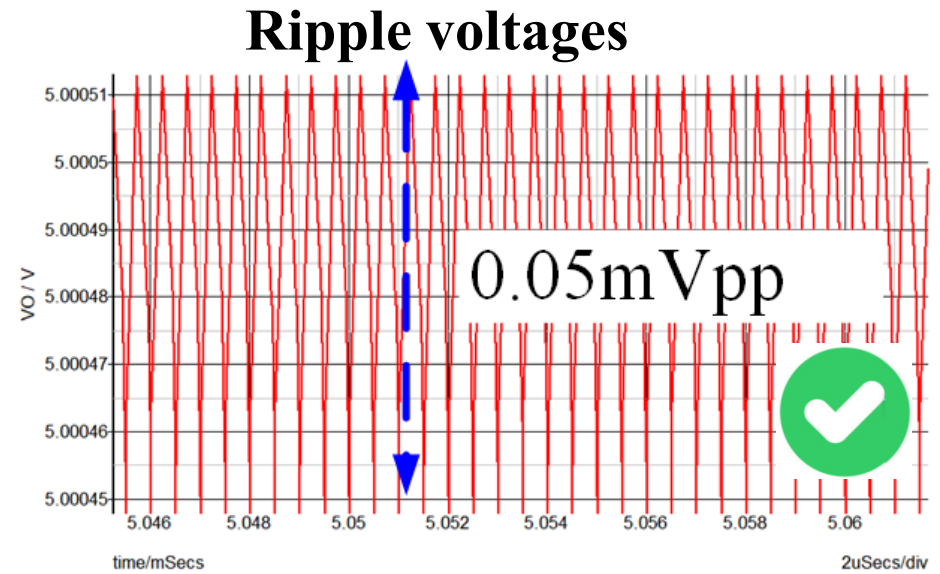
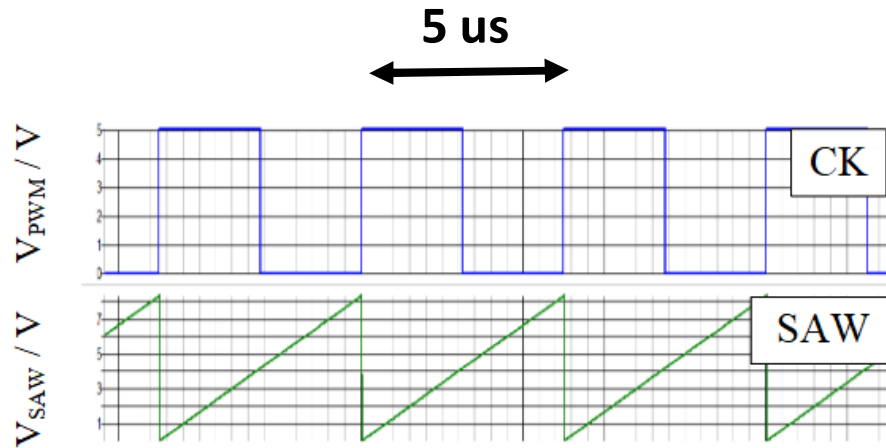
Simulation of Conventional Buck Converter

$$f_{cut_off} = \frac{1}{2\pi\sqrt{LC}} = 5kHz$$



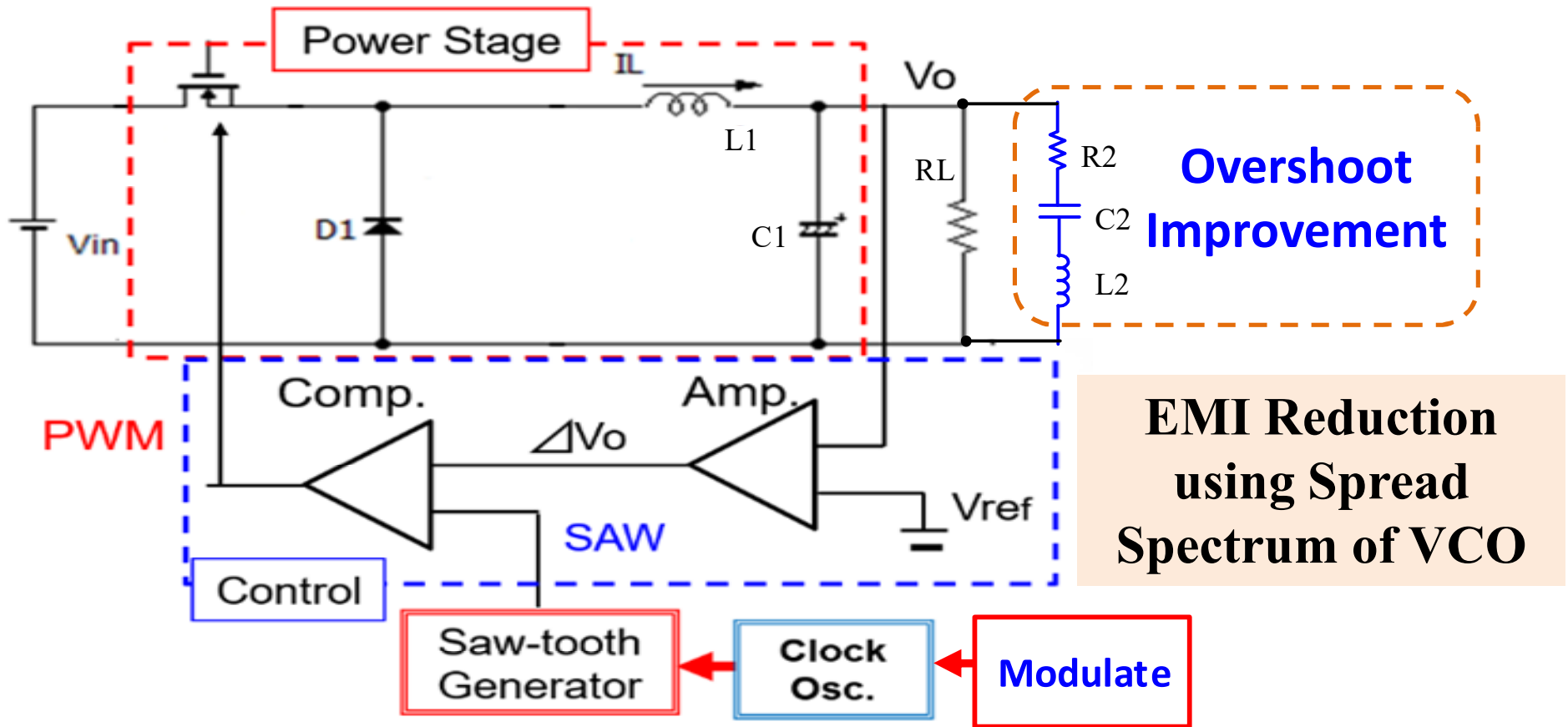
3. Proposed Design of Buck Converter

Waveforms of Conventional Buck Converter



3. Proposed Design of Buck Converter

Proposed Design of Step-down Switching Converter

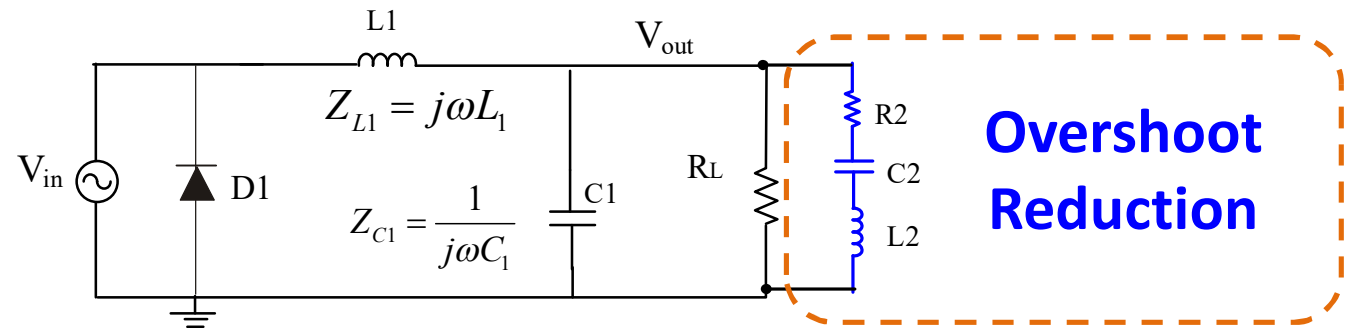


Overshoot improvement with parallel RLC

3. Proposed Design of Buck Converter

Overshoot Improvement with Parallel RLC Network

Proposed model



Superposition principle

$$V_o \left(\frac{1}{Z_{L1}} + \frac{1}{Z_{C1}} + \frac{1}{R_L} + \frac{1}{R_2 + Z_{L2} + Z_{C2}} \right) = \frac{V_{in}}{Z_{L1}}$$

Output Voltage

$$V_o = V_{in} \frac{(Z_{L2} + Z_{C2} + R_2) Z_{L1} R_L}{(Z_{L2} + Z_{C2} + R_2) [R_L (Z_{L1} + Z_{C1}) + Z_{L1} Z_{C1}] + Z_{L1} Z_{C1} R_L}$$

Transfer Function

$$H = \frac{V_o}{V_{in}} = \frac{(Z_{L2} + Z_{C2} + R_2) Z_{L1} R_L}{(Z_{L2} + Z_{C2} + R_2) [R_L (Z_{L1} + Z_{C1}) + Z_{L1} Z_{C1}] + Z_{L1} Z_{C1} R_L}$$

$$H(j\omega) = \frac{\frac{1}{L_1 C_1} \left((j\omega)^2 + j\omega \frac{R_2}{L_2} + \frac{1}{L_2 C_2} \right)}{\left((j\omega)^2 + j\omega \frac{R_2}{L_2} + \frac{1}{L_2 C_2} \right) \left((j\omega)^2 + j\omega \frac{1}{R_L C_1} + \frac{1}{L_1 C_1} \right) + \frac{(j\omega)^2}{L_2 C_1}}$$

3. Proposed Design of Buck Converter

Simulation of Parallel RLC Network

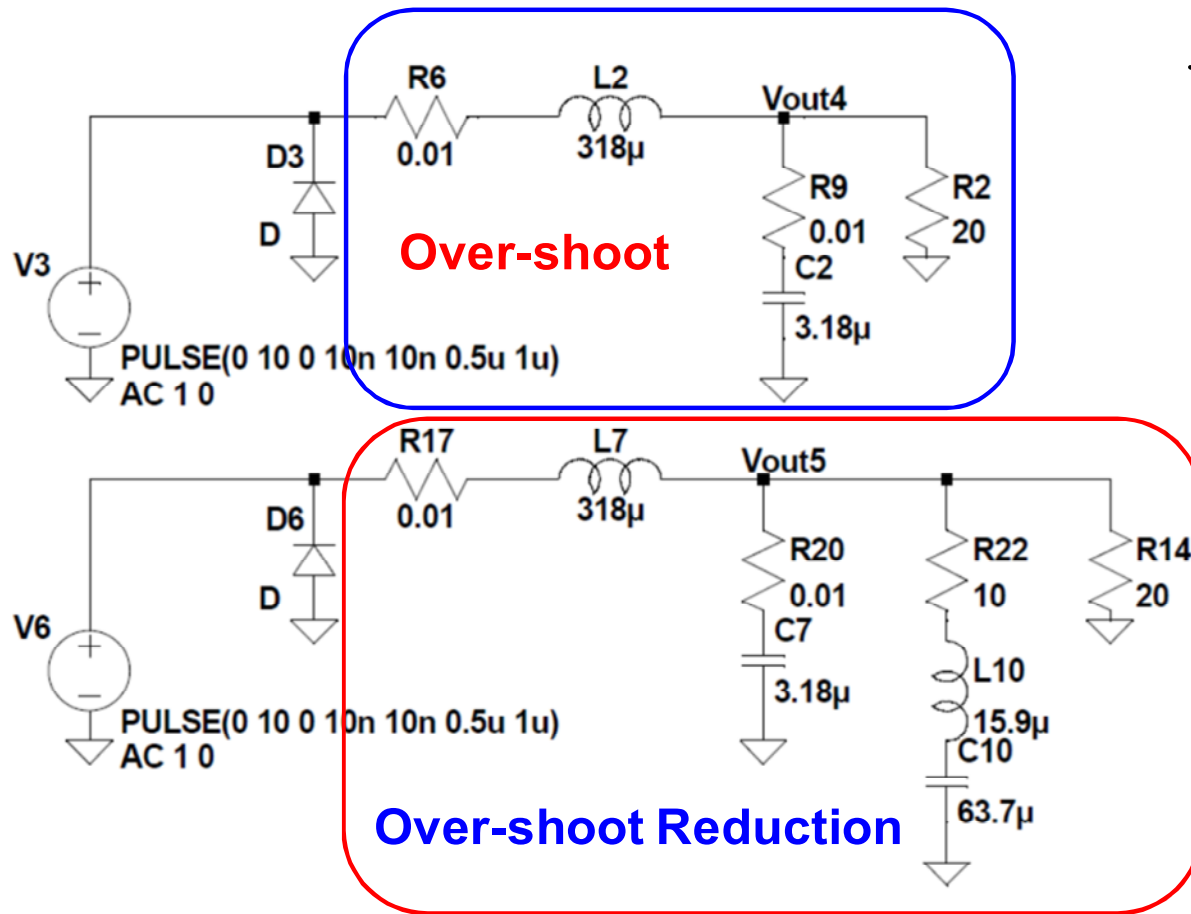
$$|Z_L| = |Z_C| = 10\Omega < 2R = 40\Omega$$

Cutoff frequency

$$f_{cut_off} = \frac{1}{2\pi\sqrt{LC}} = 5kHz$$

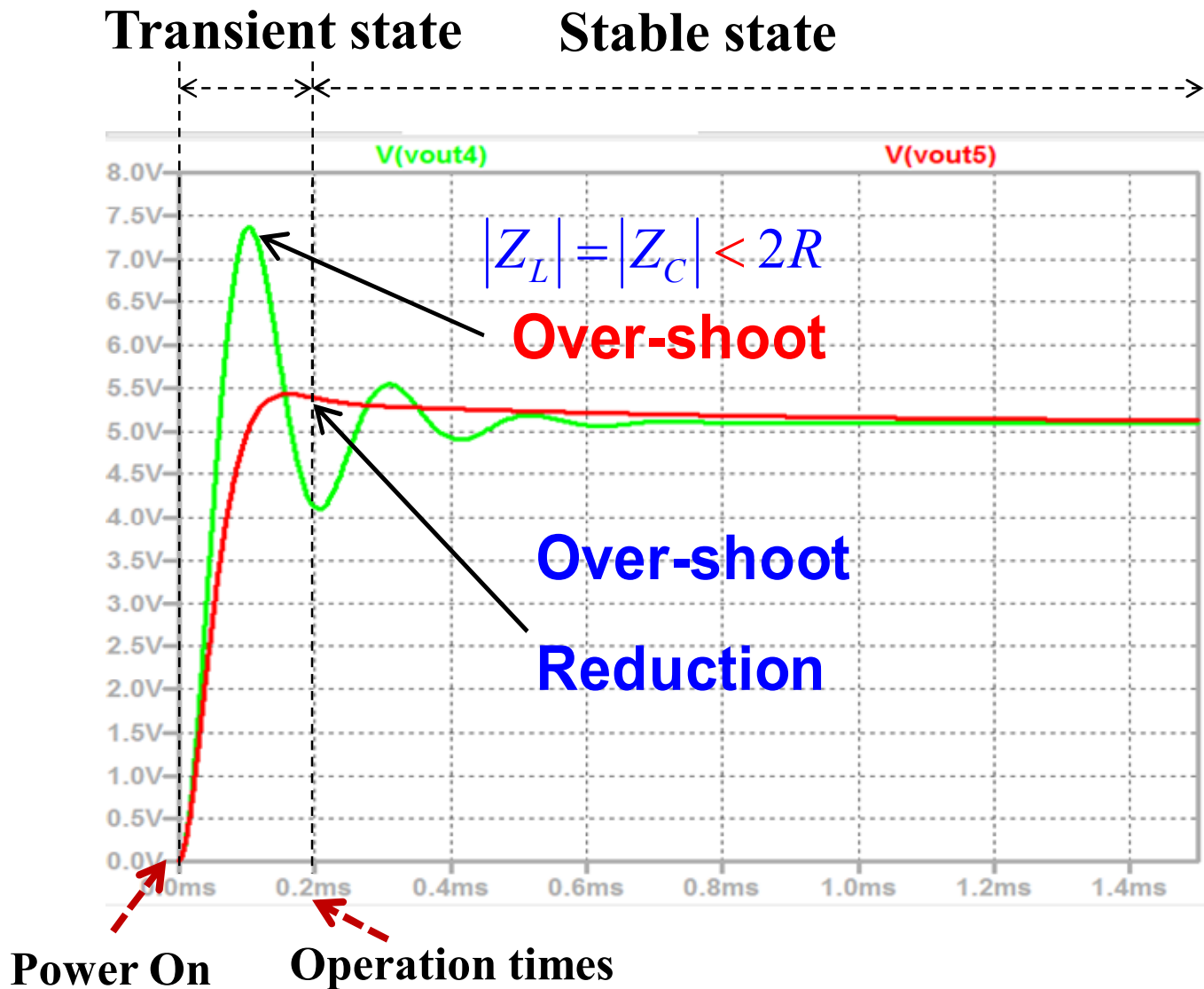
$$|Z_L| = |Z_C| = 10\Omega;$$

$$2R = 40\Omega$$



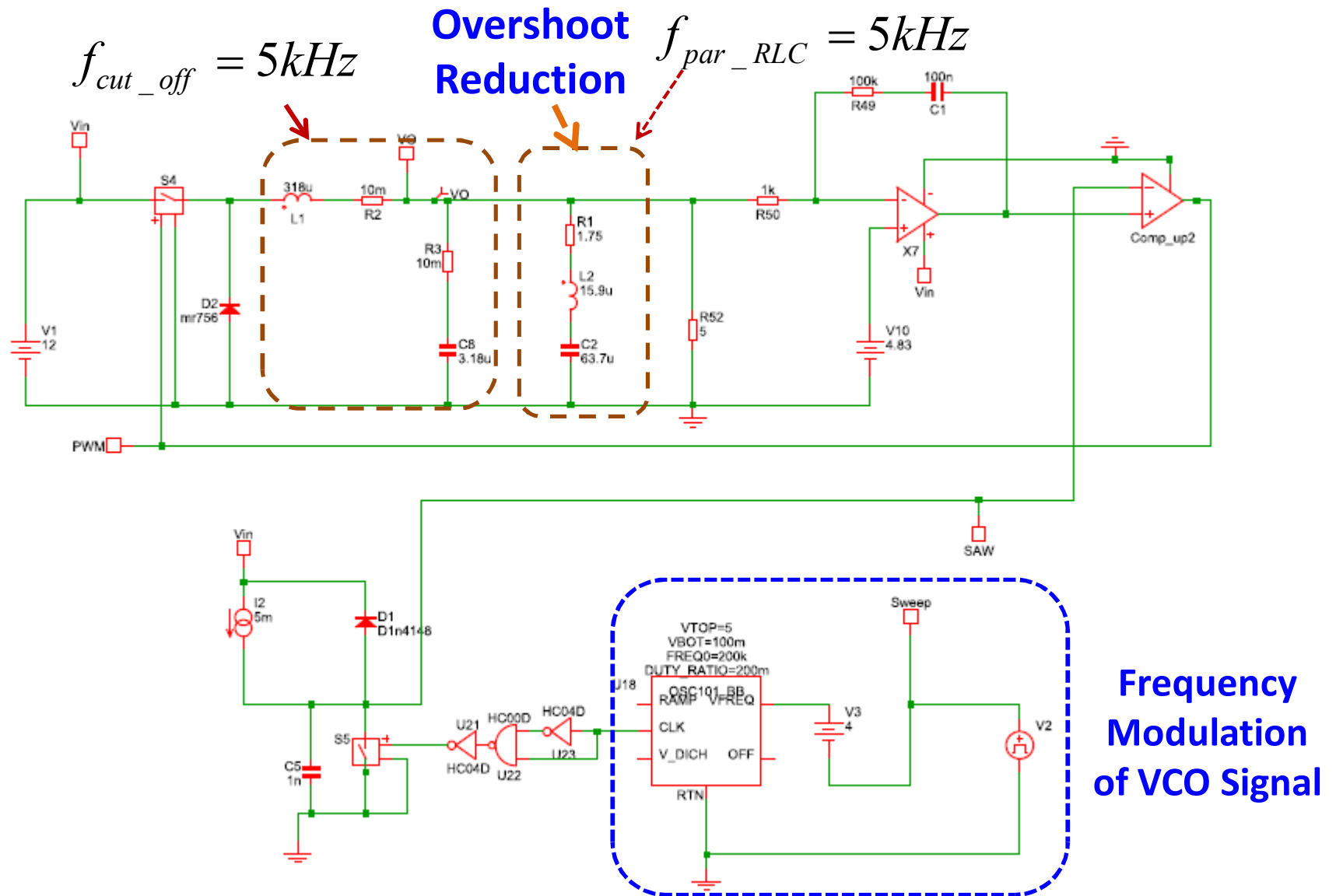
3. Proposed Design of Buck Converter

Transient Response of Parallel RLC Network



3. Proposed Design of Buck Converter

Proposed Design of Step-down Switching Converter



3. Proposed Design of Buck Converter

Overshoot Reduction Waveforms

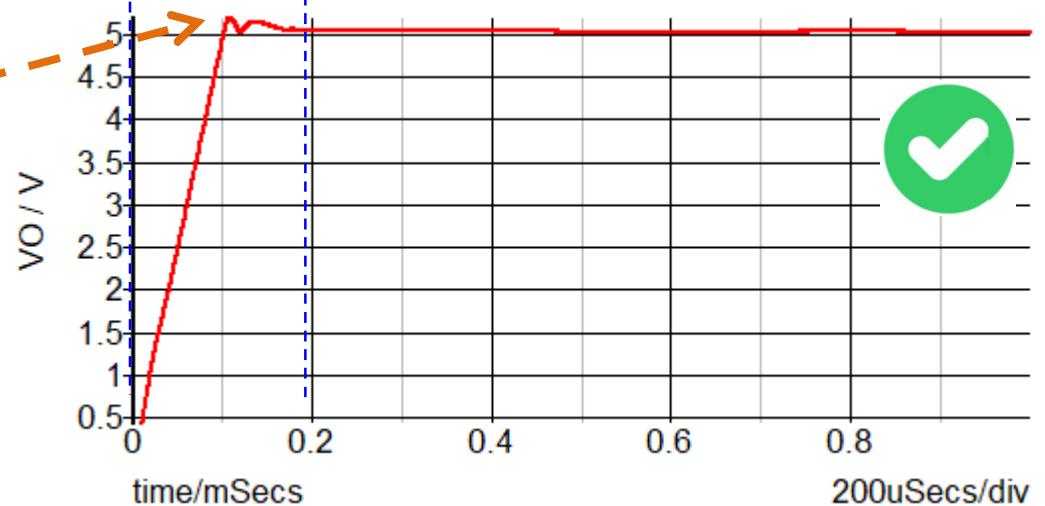
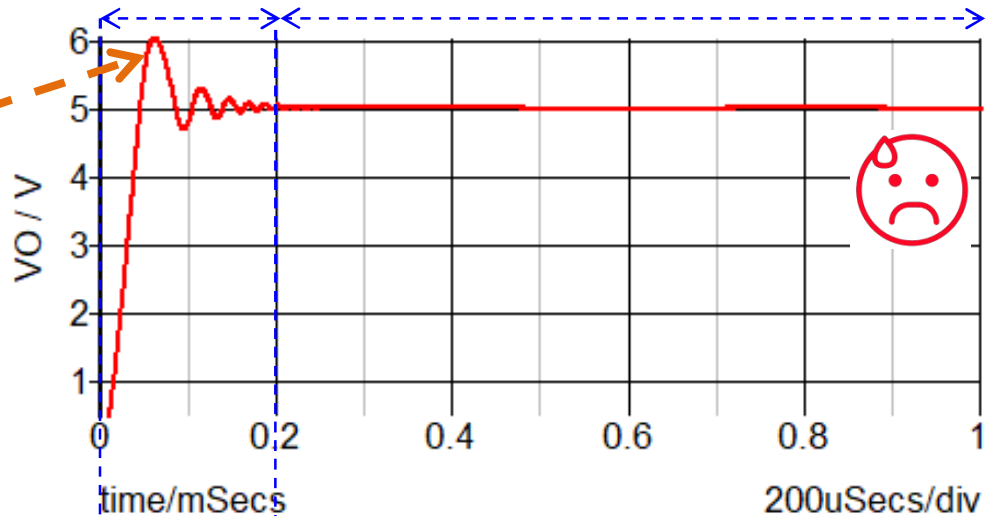
without parallel RLC network
Overshoot Voltage
>1 Vpp



with parallel RLC network
Overshoot Voltage
Reduction
< 0.1 Vpp

Transient state

Stable state

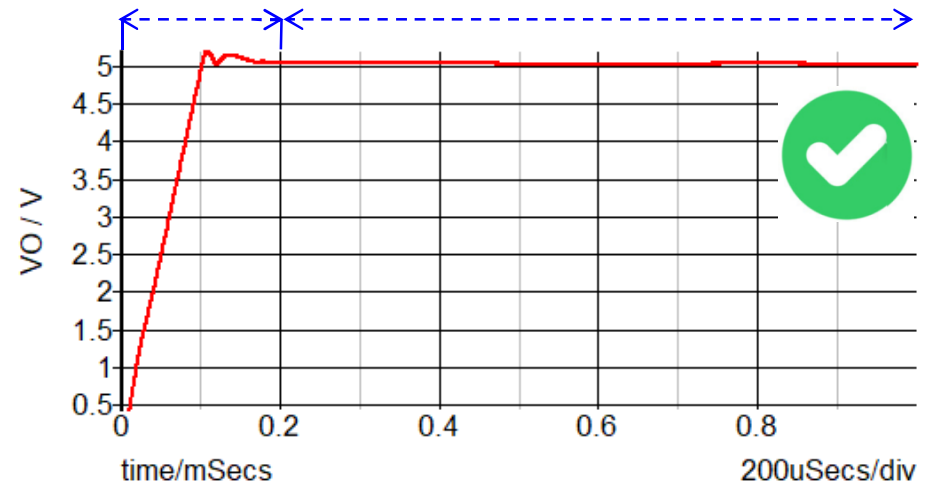


3. Proposed Design of Buck Converter

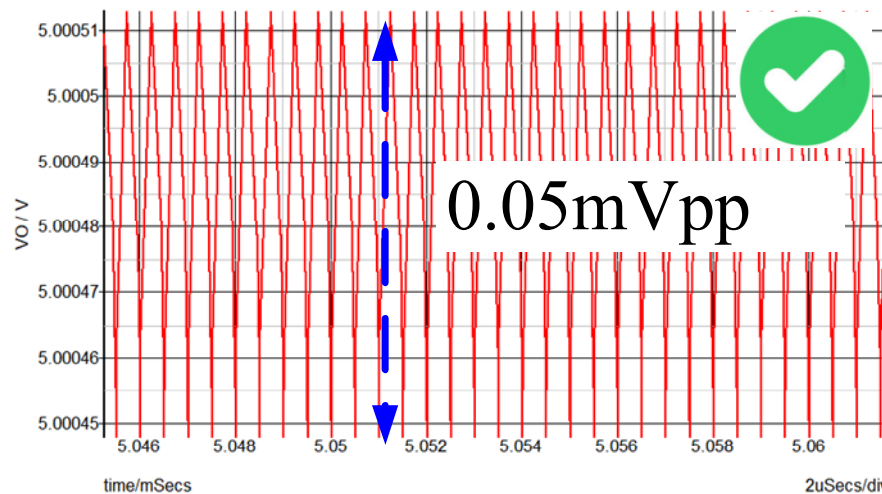
Waveforms of Proposed Buck Converter

- Input Voltage (V_{in}): 12V
- Output Voltage (V_o): 5.0V
- Output Current (I_o): 1A
- Clock Frequency (F_{ck}): 200kHz
- Overshoot: 0.1V
- Ripple Voltage: 0.05mVpp

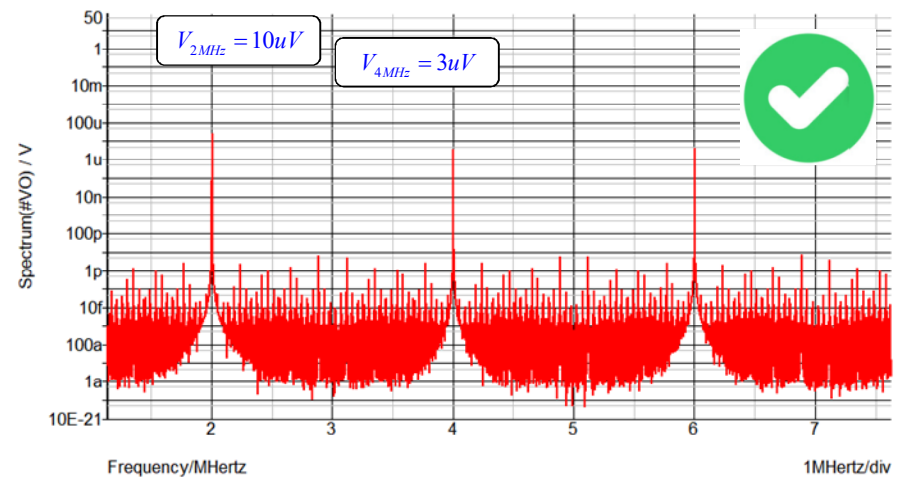
Transient state Stable state



Ripple voltages



Spectrum of ripple voltages



4. Conclusions

This work:

- **Balanced charge-discharge time condition**

$$|Z_L| = |Z_C| = 2R \Rightarrow \omega L = \frac{1}{\omega C} = 2R \quad \omega = \frac{1}{\sqrt{LC}} = \frac{1}{2RC}$$

- **Analysis model of Buck converter system based on classical technique and superposition principle**
- **Overshoot improvement with parallel RLC network**
→ **Overshoot reduction from 1Vpp into 0.1Vpp**

Future of Work

- **Analysis of parasitic of RLC and other components**

Thanks for your kind attention!



谢谢