

IC SICT-2020

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DESIGN OF SIXTH-ORDER PASSIVE QUADRATURE SIGNAL GENERATION NETWORK BASED ON POLYPHASE FILTER

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Outline

1. Research Background

- Motivation, objectives and achievements
- Review of characteristics of Low-IF receiver

2. Investigation of Multi-Phase Networks

- Superposition theorem for multi-source networks
- Design principle for passive polyphase filters

3. Proposed Designs and Experimental Results

- Analysis of quadrature signal generation networks
- Simulation and measurement results

4. Conclusions

1. Research Background

Motivation of Study

Performance of a system

Signal to
Noise Ratio:

$$\text{SNR} = \frac{\text{Signal power}}{\text{Noise power}}$$

Common types of noise:

- Electronic noise
- Thermal noise,
- Intermodulation noise,
- Cross-talk,
- Impulse noise,
- Shot noise, and
- Transit-time noise.



Performance of a device

Figure of
Merit:

$$F = \frac{\text{Output SNR}}{\text{Input SNR}}$$

Device noise:

- Flicker noise,
- Thermal noise,
- White noise.

Multi-phase networks

- Image noise,
- I/Q mismatches
- DC offsets

1. Research Background

Objectives of Study

- **Derivation of transfer function** in multi-source systems using **superposition theorem**
- **Investigation** of behaviors of high-order passive RC polyphase filter networks
- **Analysis and design of** quadrature signal generation network for measuring frequency response of polyphase and complex filters
- **Implementation** of 6th-order polyphase signal generation based on polyphase filter circuits

1. Research Background

Achievements of Study

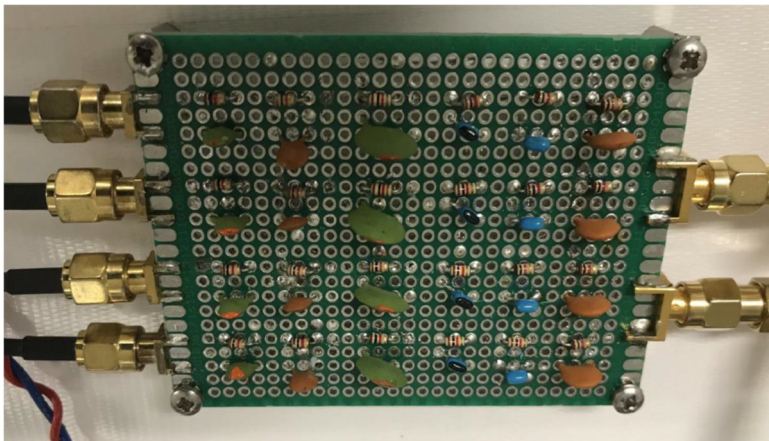
Superposition
formula for
multi-source
networks

$$V_o(t) \sum_{i=1}^n \frac{I}{Z_i} + V_o(t) \sum_{i=1}^n \frac{1}{Z_{si}} + \frac{1}{\sum_{k=1}^n \frac{1}{Z_{pik}}} = \sum_{i=1}^n \left(\frac{V_i(t)}{Z_i} + I_{ai}(t) - I_{gi}(t) \right)$$

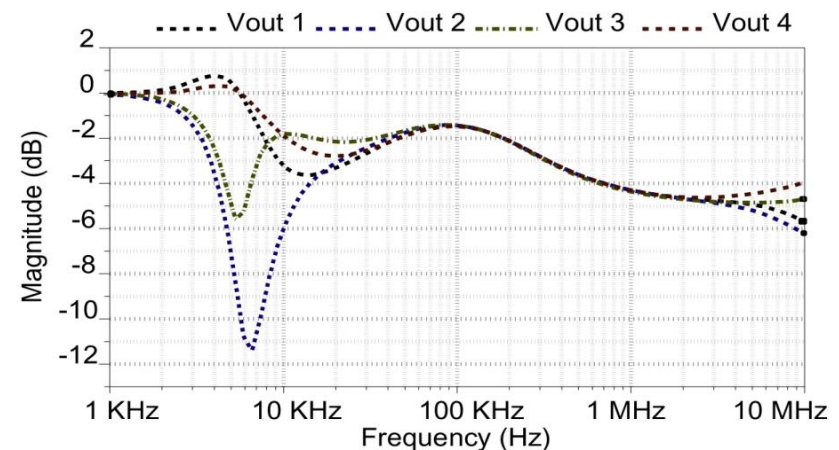
Conventional superposition

→ Solving for every source (**several times**).

Implemented circuit

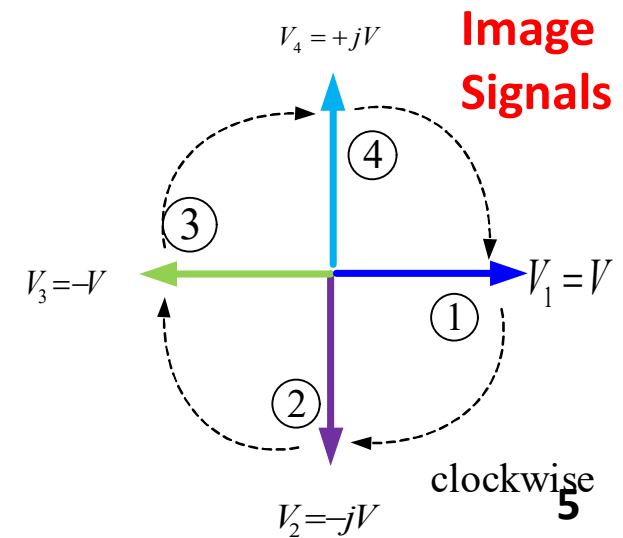
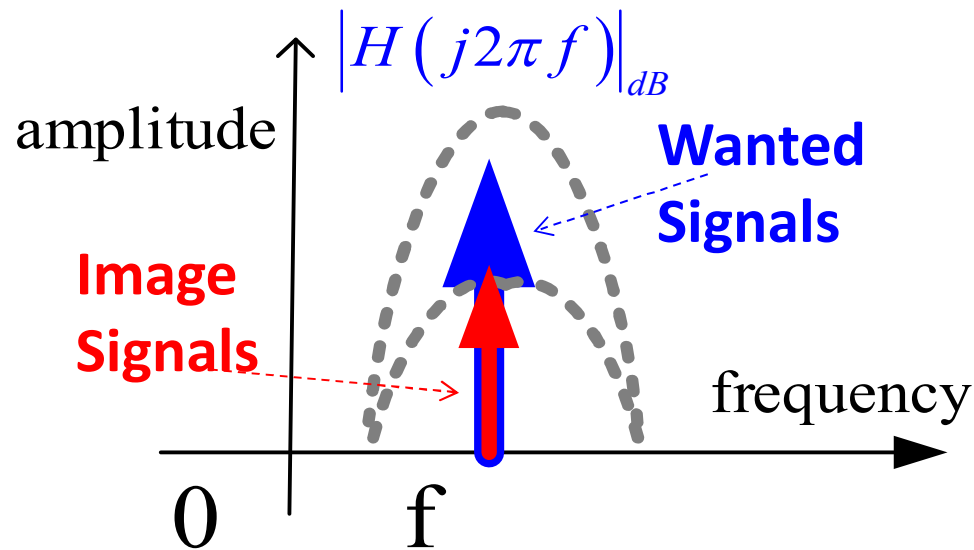
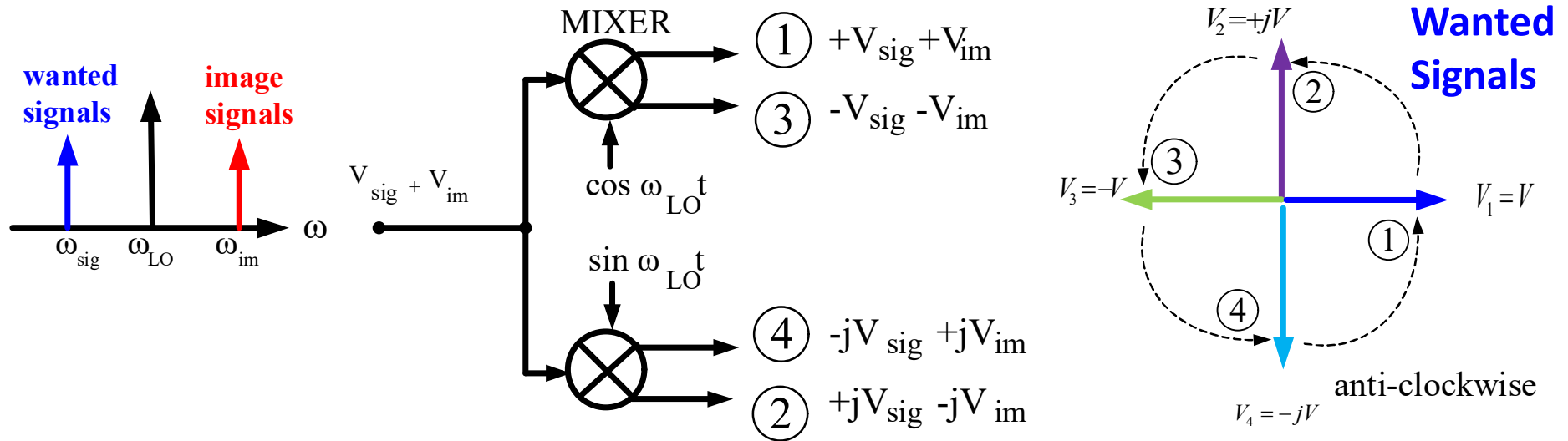


Experimental results



1. Research Background

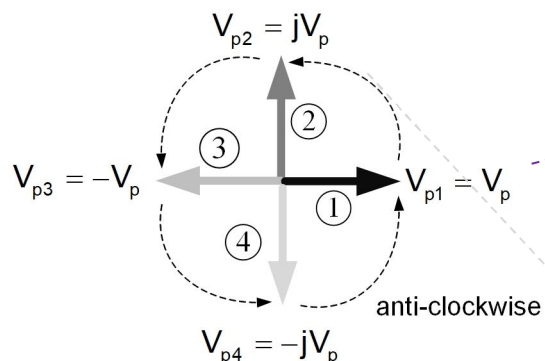
Characteristics of Low-IF Receiver Signals



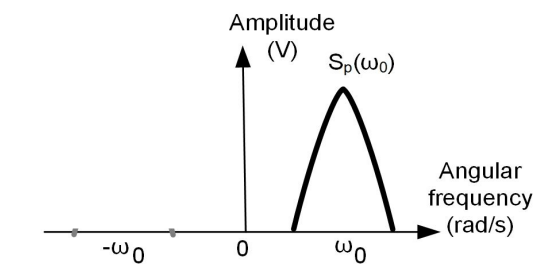
1. Research Background

Positive Polyphase Signals on Frequency Domain

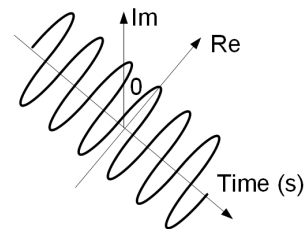
Positive polyphase signals



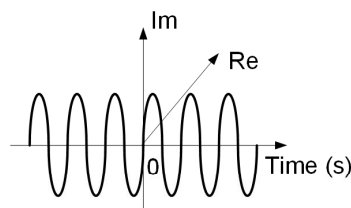
$$S_{Pos_poly} \{V_1(t); V_2(t); V_3(t); V_4(t)\} \\ = \{1; +j; (+j)^2; (+j)^3\} V_{pos}(t)$$



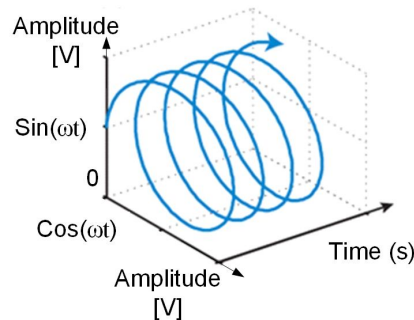
(c) Angular frequency plane for polyphase signals



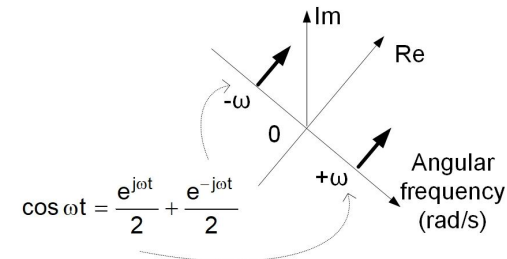
(a) Cosine wave on real axis



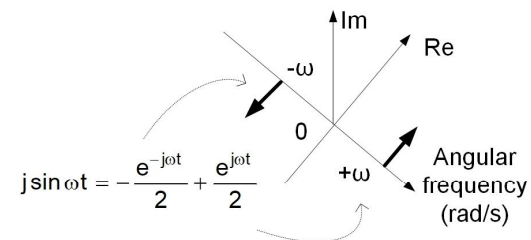
(c) Plus sine wave on imaginary axis



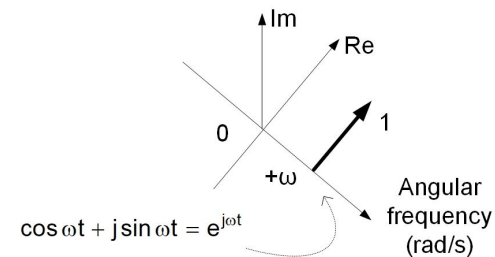
(e) Positive angular frequency wave



(b) Spectrum of cosine wave



(d) Spectrum of plus sine wave

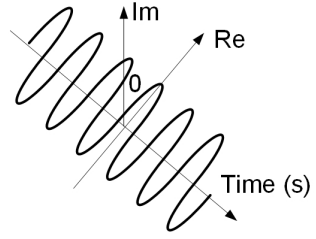
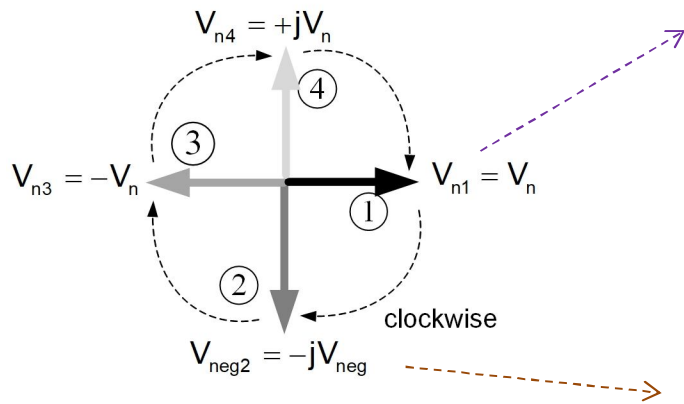


(f) Spectrum of positive angular frequency wave

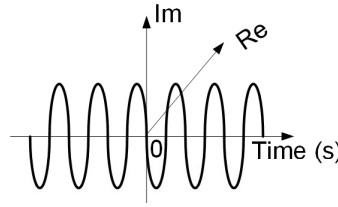
1. Research Background

Negative Polyphase Signals on Frequency Domain

Negative polyphase signals

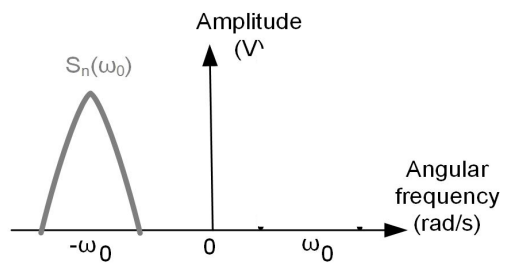


(a) Cosine wave on real plane

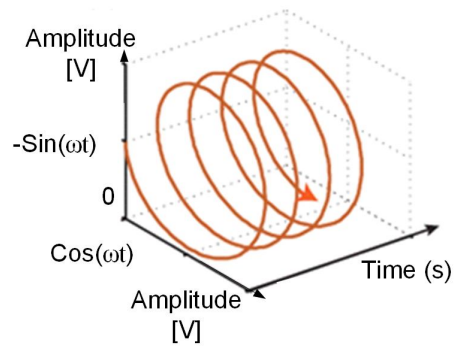


(c) Minus sine wave on imaginary plane

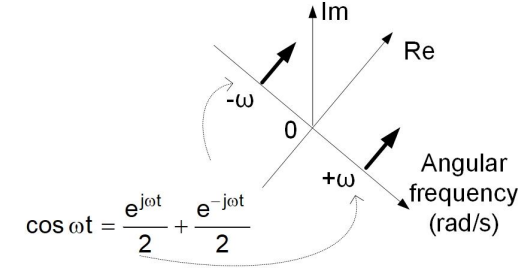
$$S_{Neg_poly} \{V_1(t); V_2(t); V_3(t); V_4(t)\} = \{1; -j; (-j)^2; (-j)^3\} V_{neg}(t)$$



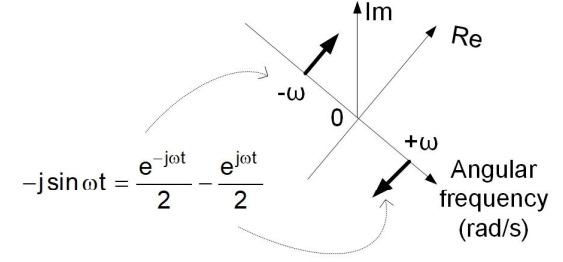
(c) Angular frequency plane for polyphase signals



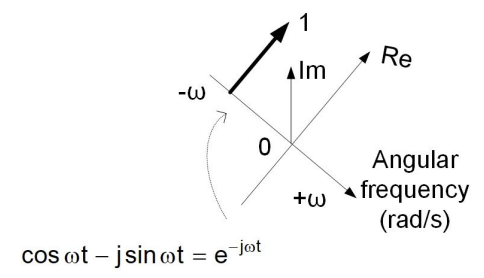
(e) Negative angular frequency wave



(b) Spectrum of cosine wave



(d) Spectrum of minus sine wave

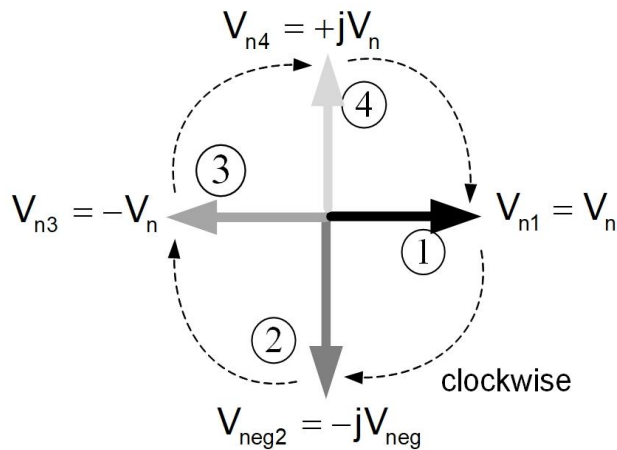


(f) Spectrum of negative angular frequency wave

1. Research Background

Polyphase Signals on Frequency Domain

Negative polyphase signals



Positive polyphase signals

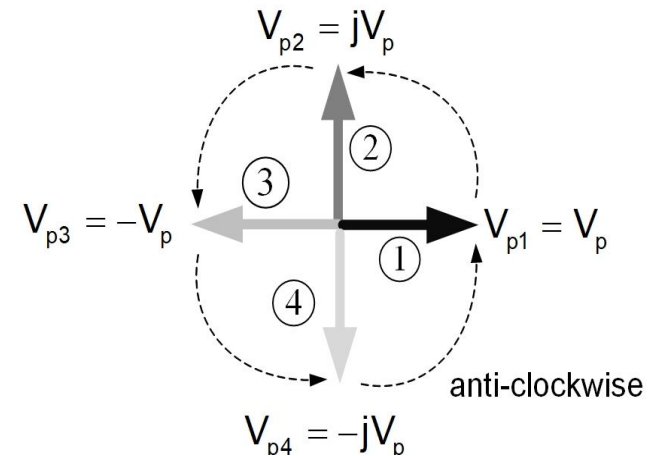
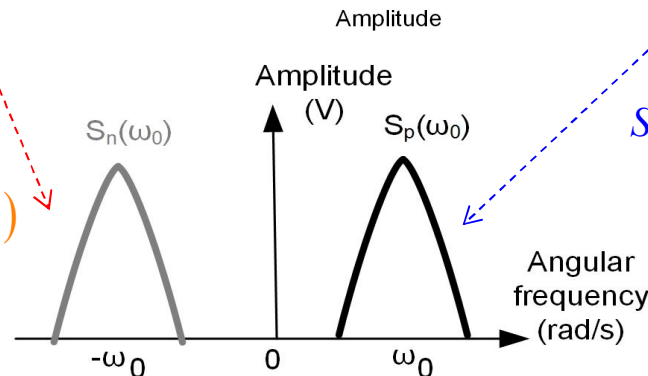


Image Signals

$$S_{Neg_poly} \{V_1(t); V_2(t); V_3(t); V_4(t)\} \\ = \{1; -j; (-j)^2; (-j)^3\} V_{neg}(t)$$

Wanted Signals

$$S_{Pos_poly} \{V_1(t); V_2(t); V_3(t); V_4(t)\} \\ = \{1; +j; (+j)^2; (+j)^3\} V_{pos}(t)$$



(c) Angular frequency plane for polyphase signals

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- **Design principle for passive polyphase filters**

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2. Investigation of Multi-Phase Networks

Superposition Theorem for Multi-Source Systems

Superposition formula:

$$V_o(t) \sum_{i=1}^n \frac{1}{Z_i} + V_o(t) \sum_{i=1}^n \frac{1}{Z_{si}} + \frac{1}{\sum_{k=1}^n \frac{1}{Z_{pik}}} = \sum_{i=1}^n \left(\frac{V_i(t)}{Z_i} + I_{ai}(t) - I_{gi}(t) \right)$$

$V_o(t)$: Voltage at one node

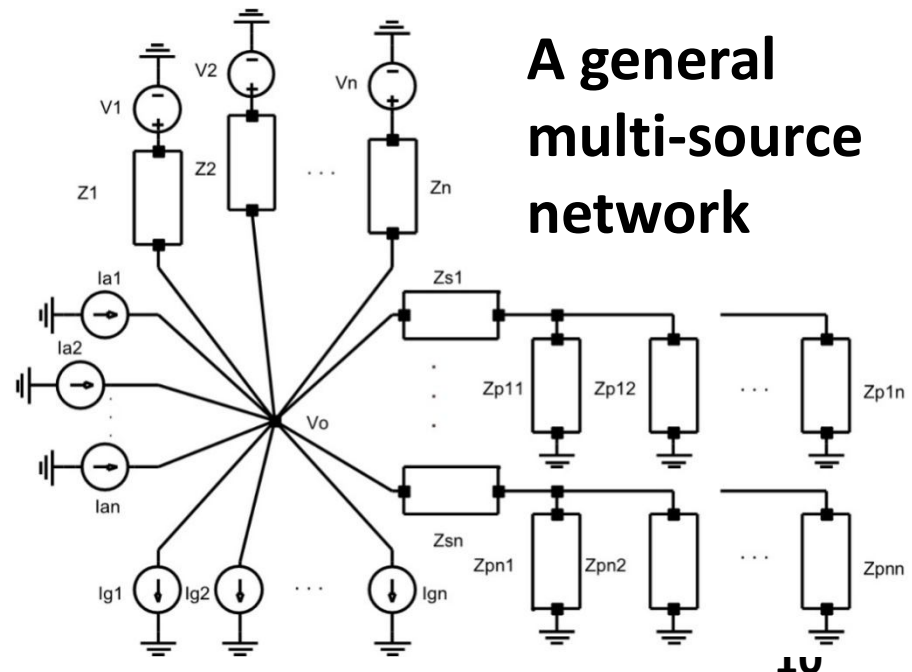
$V_i(t)$: Input voltage sources

$I_{ai}(t)$: Ahead-toward current sources

$I_{gi}(t)$: Ground-toward current sources

$Z_i, s_i, p_i, (t)$: Impedances at each branch

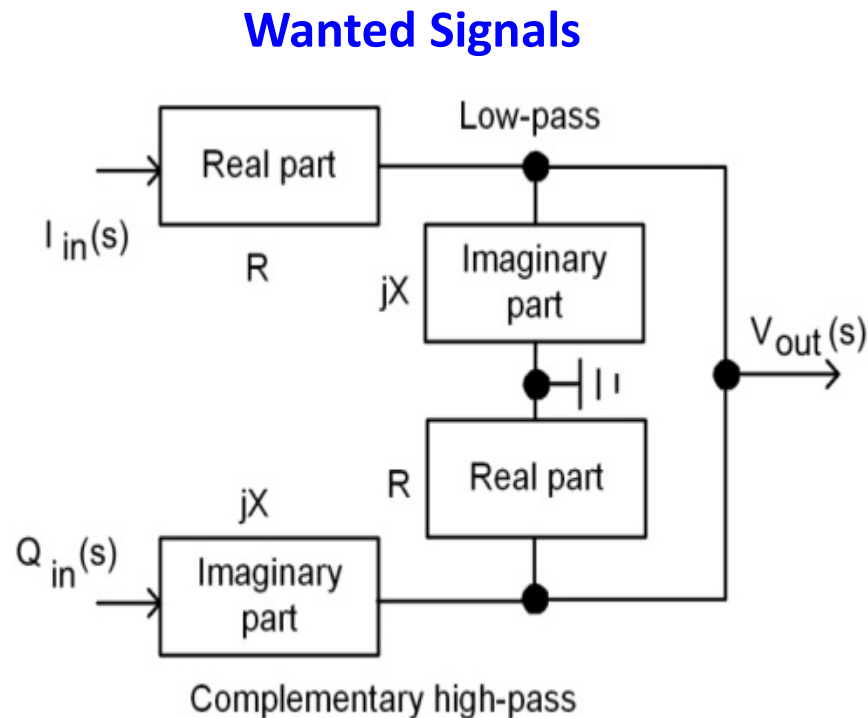
- Multi-source systems, feedback networks (op amps, amplifiers), polyphase filters, complex filters...



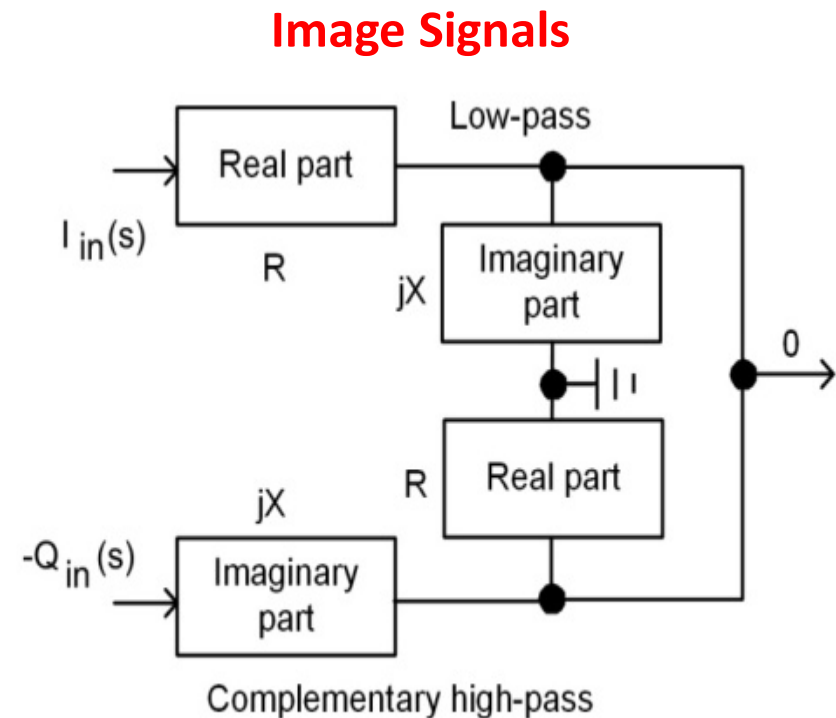
2. Investigation of Multi-Phase Networks

Design Principle for Polyphase Filter Networks

Complementation between **low-pass** and **high-pass** circuits
 → a **passive polyphase filter**



Pass-band filter (wanted signals)

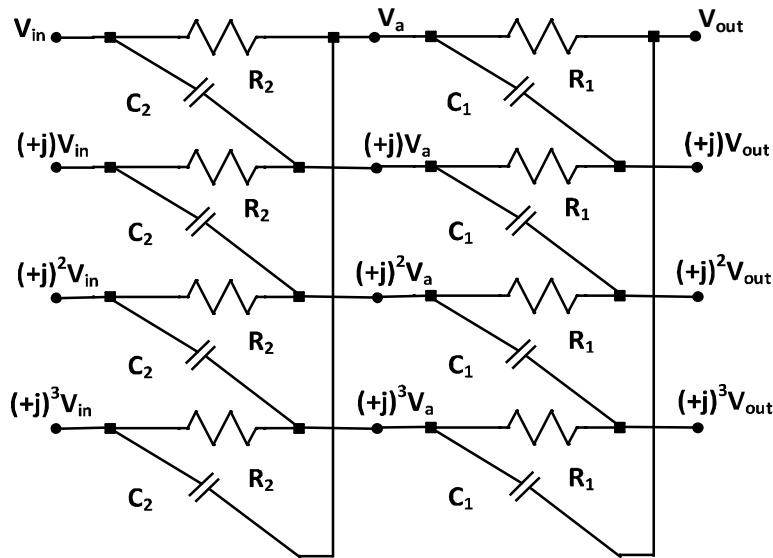


Notch-band filter (image signals)

2. Investigation of Multi-Phase Networks

Analysis of 2nd-Order Polyphase Filter

2nd-order RC polyphase filter



Apply superposition at each node

$$V_{out} \left(\frac{1}{Z_{C_1}} + \frac{1}{R_1} \right) = \frac{V_a}{R_1} + \frac{(+j)^3 V_a}{Z_{C_1}};$$

$$V_a \left(\frac{1}{Z_{C_2}} + \frac{1}{R_2} + \frac{2}{R_1 + Z_{C_1}} \right) = \frac{V_{in}}{R_2} + \frac{(+j)^3 V_{in}}{Z_{C_2}};$$

Transfer function for **positive** polyphase signal

$$H_P(\omega) = \frac{V_{out}}{V_{in}} = \frac{\left[1 + (+j)^3 b_1 j\omega \right] \left[1 + (+j)^3 b_2 j\omega \right]}{a_0 (j\omega)^2 + a_1 j\omega + 1};$$

Transfer function for **negative** polyphase signal

$$H_N(\omega) = \frac{V_{out}}{V_{in}} = \frac{\left[1 + (-j)^3 b_1 j\omega \right] \left[1 + (-j)^3 b_2 j\omega \right]}{a_0 (j\omega)^2 + a_1 j\omega + 1};$$

Here: $b_0 = R_1 C_1; b_1 = R_2 C_2; a_0 = b_0 b_1; a_1 = b_0 + b_1 + 2 R_2 C_1;$

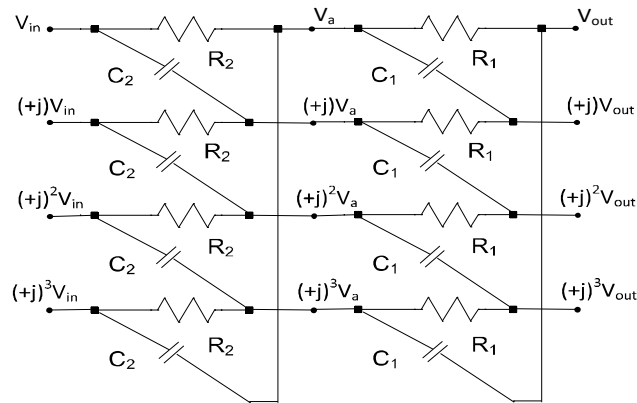
Image rejection ratio (IRR)

$$IRR(\omega) = \frac{|H_P(\omega)|}{|H_N(\omega)|} = \frac{|(1 + b_1 \omega)(1 + b_2 \omega)|}{|(1 - b_1 \omega)(1 - b_2 \omega)|};$$

2. Investigation of Multi-Phase Networks

Behaviors of 2nd-Order Polyphase Filter

2-order RC polyphase filter

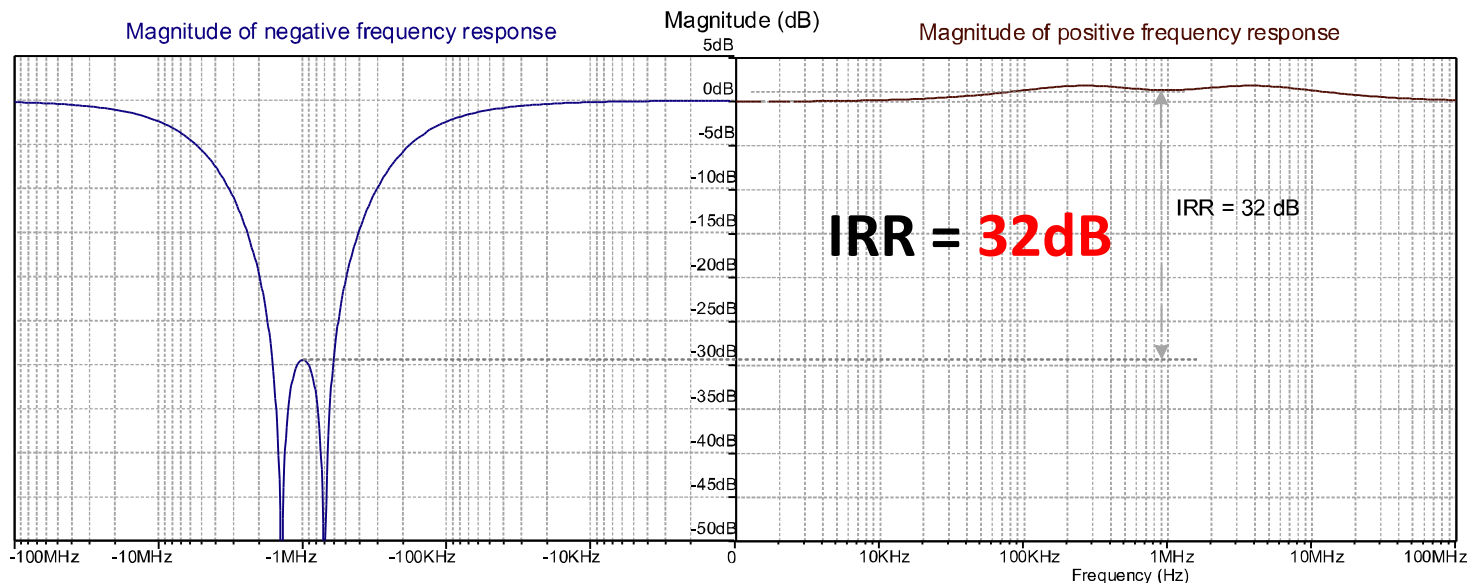


Transfer function in all frequency domain

$$|H(\omega)| = \frac{(1 + b_1\omega)(1 + b_2\omega)}{\sqrt{(1 - a_0\omega^2)^2 + (a_1\omega)^2}}; \omega \in R$$

Here, $R1 = 1 \text{ k}\Omega$, $C1 = 227 \text{ pF}$, $R2 = 1 \text{ k}\Omega$, $C2 = 114 \text{ pF}$, at $f_1 = 700 \text{ kHz}$, $f_2 = 1.4 \text{ MHz}$,

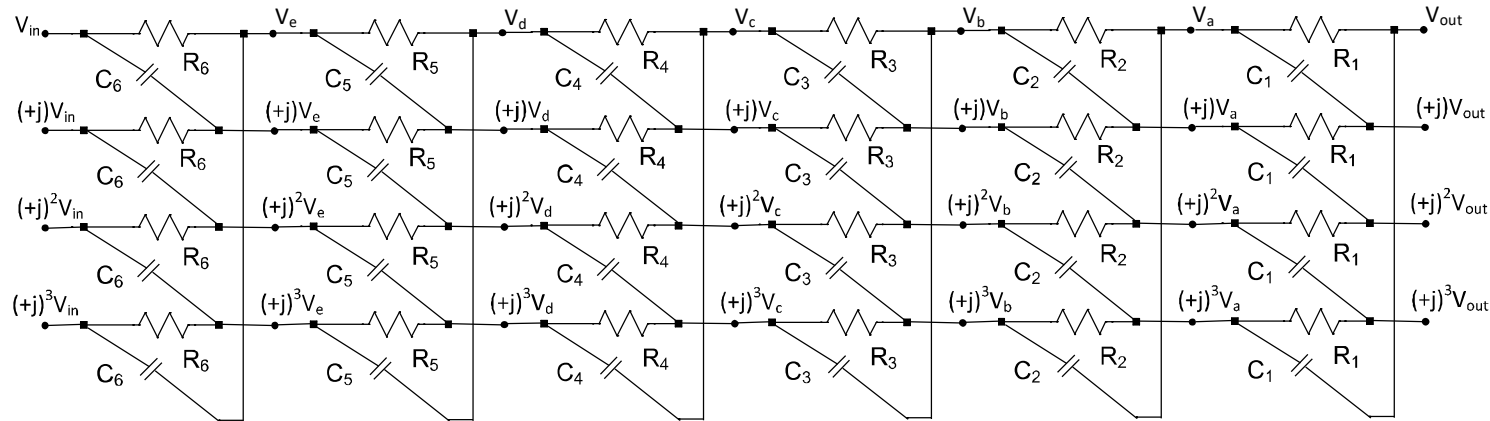
Bode plot of transfer function in all frequency domain



2. Investigation of Multi-Phase Networks

Transfer Function of 6th-Order RC Polyphase Filter

6th-order
polyphase
filter



Apply the superposition principle at nodes V_a , V_b , V_c , V_d , V_e , V_{out} , we get

$$V_{out} \left(\frac{1}{Z_{C1}} + \frac{1}{R_1} \right) = \frac{V_a}{R_1} + \frac{(+j)^3 V_a}{Z_{C1}}; V_a \left(\frac{1}{Z_{C2}} + \frac{1}{R_2} + \frac{2}{M_A} \right) = \frac{V_a}{R_2} + \frac{(+j)^3 V_b}{Z_{C2}};$$

$$V_b \left(\frac{1}{Z_{C3}} + \frac{1}{R_3} + \frac{1}{M_{B1}} + \frac{1}{M_{B2}} \right) = \frac{V_c}{R_3} + \frac{(+j)^3 V_c}{Z_{C3}}; V_c \left(\frac{1}{Z_{C4}} + \frac{1}{R_4} + \frac{1}{M_{C1}} + \frac{1}{M_{C2}} \right) = \frac{V_d}{R_4} + \frac{(+j)^3 V_d}{Z_{C4}};$$

$$V_d \left(\frac{1}{Z_{C5}} + \frac{1}{R_5} + \frac{1}{M_{D1}} + \frac{1}{M_{D2}} \right) = \frac{V_e}{R_5} + \frac{(+j)^3 V_e}{Z_{C5}}; V_e \left(\frac{1}{Z_{C6}} + \frac{1}{R_6} + \frac{1}{M_{E1}} + \frac{1}{M_{E2}} \right) = \frac{V_{in}}{R_6} + \frac{(+j)^3 V_{in}}{Z_{C6}};$$

Transfer function

$$H(\omega) = \frac{[1 + b_1 \omega][1 + b_2 \omega][1 + b_3 \omega][1 + b_4 \omega][1 + b_5 \omega][1 + b_6 \omega]}{a_0 (j\omega)^6 + a_1 (j\omega)^5 + a_2 (j\omega)^4 + a_3 (j\omega)^3 + a_4 (j\omega)^2 + a_5 j\omega + 1};$$

2. Investigation of Multi-Phase Networks

Characteristics of 6th-order RC Polyphase Filter

Behaviors of transfer function in all frequency domain

$$\begin{aligned}
 |H_p(\omega)| &= \begin{cases} \lim_{\omega \rightarrow 0^+} |H_p(\omega)| = 1 \\ \text{Max}_1 \{H_p(\omega)\} \text{ as } \omega_{\max 1} \\ \text{Min} \{H_p(\omega)\} \text{ as } \omega_{\min} = \frac{1}{\sqrt[6]{b_1 b_2 b_3 b_4 b_5 b_6}} \\ \text{Max}_2 \{H_p(\omega)\} \text{ as } \omega_{\max 2} \\ \lim_{\omega \rightarrow +\infty} |H_p(\omega)| = 1 \end{cases} & |H_n(\omega)| = \begin{cases} \lim_{\omega \rightarrow 0^-} H_n(\omega) = 1; \text{Min}_1 \{H_n(\omega)\} = 0 \text{ as } \omega_1 = -\frac{1}{b_1} \\ \text{Max}_1 \{H_n(\omega)\} \text{ as } \omega_{\max 1} = -\frac{1}{\sqrt{b_1 b_2}}; \text{Min}_2 \{H_n(\omega)\} \text{ as } \omega_2 = -\frac{1}{b_2} \\ \text{Max}_2 \{H_n(\omega)\} \text{ as } \omega_{\max 2} = -\frac{1}{\sqrt{b_2 b_3}}; \text{Min}_3 \{H_n(\omega)\} \text{ as } \omega_3 = -\frac{1}{b_3} \\ \text{Max}_3 \{H_n(\omega)\} \text{ as } \omega_{\max 3} = -\frac{1}{\sqrt{b_3 b_4}}; \text{Min}_4 \{H_n(\omega)\} \text{ as } \omega_4 = -\frac{1}{b_4} \\ \text{Max}_4 \{H_n(\omega)\} \text{ as } \omega_{\max 4} = -\frac{1}{\sqrt{b_4 b_5}}; \text{Min}_5 \{H_n(\omega)\} \text{ as } \omega_5 = -\frac{1}{b_5} \\ \text{Max}_5 \{H_n(\omega)\} \text{ as } \omega_{\max 5} = -\frac{1}{\sqrt{b_5 b_6}}; \text{Min}_6 \{H_n(\omega)\} \text{ as } \omega_6 = -\frac{1}{b_6}; \lim_{\omega \rightarrow -\infty} H_n(\omega) = 1 \end{cases} ; \\
 \theta_p(\omega) &= \begin{cases} \theta_{p1} = 0; \omega \rightarrow 0^+ \\ \theta_{p2} = \frac{-\pi}{4}; \omega_{\max 1} \\ \theta_{p3} = \frac{-3\pi}{2}; \omega_{\min} = \frac{1}{\sqrt[6]{b_1 b_2 b_3 b_4 b_5 b_6}} \\ \theta_{p4} = \frac{-11\pi}{4}; \omega_{\max 2} \\ \theta_{p5} = -3\pi; \omega \rightarrow +\infty \end{cases} \quad \text{Positive frequency} & \theta_n(\omega) = \begin{cases} \theta_1 = 0; \omega \rightarrow 0^-; \theta_2 = \frac{-5\pi}{8} \rightarrow \frac{3\pi}{8}; \omega_1 = -\frac{1}{b_1} \\ \theta_3 = \frac{\pi}{4}; \omega_{\max 1} = -\frac{1}{\sqrt{b_1 b_2}}; \theta_4 = \frac{\pi}{8} \rightarrow \frac{9\pi}{8}; \omega_2 = -\frac{1}{b_2} \\ \theta_5 = \frac{15\pi}{16}; \omega_{\max 2} = -\frac{1}{\sqrt{b_2 b_3}}; \theta_6 = \frac{3\pi}{4} \rightarrow \frac{7\pi}{4}; \omega_3 = -\frac{1}{b_3} \\ \theta_7 = \frac{25\pi}{16}; \omega_{\max 3} = -\frac{1}{\sqrt{b_3 b_4}}; \theta_8 = \frac{11\pi}{8} \rightarrow \frac{19\pi}{8}; \omega_4 = -\frac{1}{b_4} \\ \theta_9 = \frac{37\pi}{16}; \omega_{\max 4} = -\frac{1}{\sqrt{b_4 b_5}}; \theta_{10} = \frac{9\pi}{4} \rightarrow \frac{13\pi}{4}; \omega_5 = -\frac{1}{b_5} \\ \theta_{11} = \frac{37\pi}{16}; \omega_{\max 5} = -\frac{1}{\sqrt{b_5 b_6}}; \theta_{12} = \frac{9\pi}{4} \rightarrow \frac{13\pi}{4}; \omega_6 = -\frac{1}{b_6}; \theta_{13} = \frac{5\pi}{2}; \omega \rightarrow -\infty \end{cases} \quad \text{Negative frequency}
 \end{aligned}$$

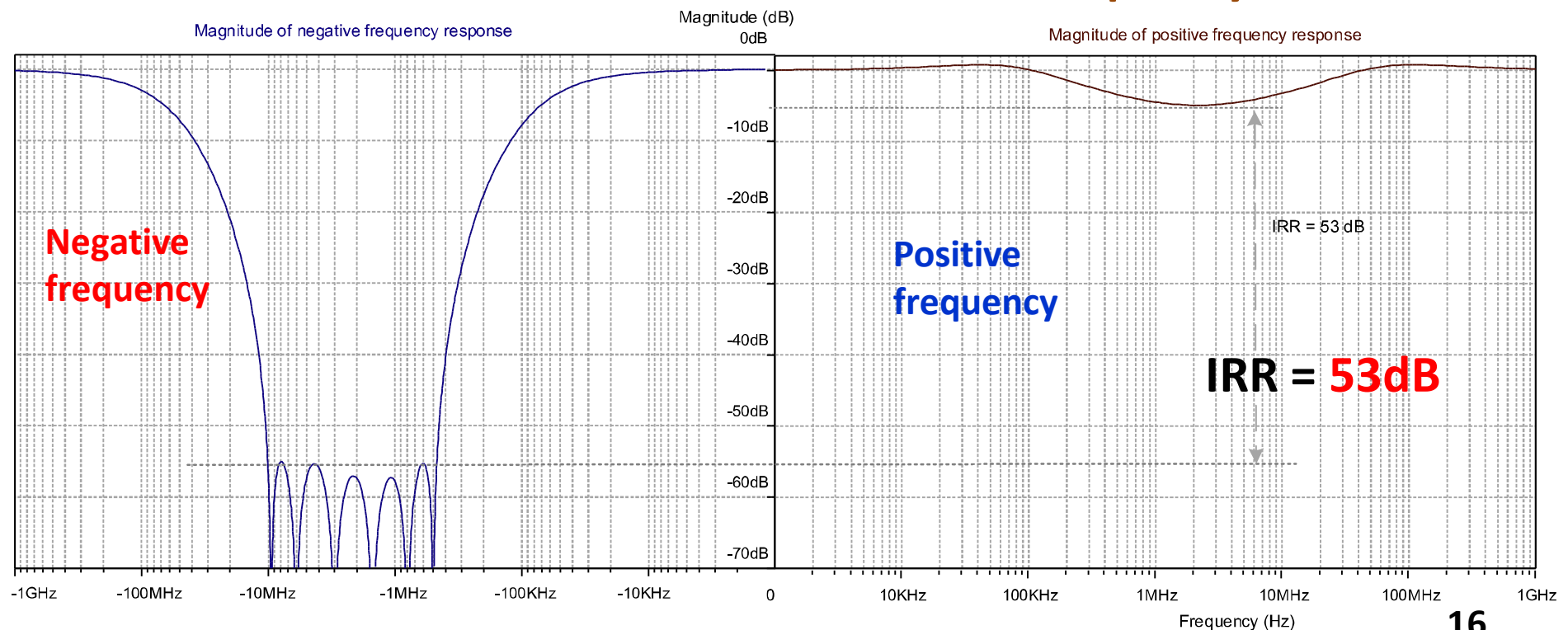
2. Investigation of Multi-Phase Networks

Bode Plot of 6th-Order RC Polyphase Filter

Passive component parameters

$R_1 = 1 \text{ k}\Omega$, $C_1 = 318 \text{ pF}$, $R_2 = 1 \text{ k}\Omega$, $C_2 = 199 \text{ pF}$, $R_3 = 1 \text{ k}\Omega$, $C_3 = 106 \text{ pF}$, $R_4 = 1 \text{ k}\Omega$,
 $C_4 = 53.1 \text{ pF}$, $R_5 = 1 \text{ k}\Omega$, $C_5 = 26.5 \text{ pF}$, $R_6 = 1 \text{ k}\Omega$, $C_6 = 16.8 \text{ pF}$,
 $f_1 = 500 \text{ kHz}$, $f_2 = 800 \text{ kHz}$, and $f_3 = 1.5 \text{ MHz}$, $f_4 = 3 \text{ MHz}$, $f_5 = 6 \text{ MHz}$, $f_6 = 9.5 \text{ MHz}$,

Simulation results of transfer function in all frequency domain



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3. **Proposed Designs and Experimental Results**

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- **Simulation and measurement results**

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3. Proposed Designs and Experimental Results

Design Principle for Quadrature Signal Generation

Complementation between **low-pass** and **high-pass** circuits
 → a **passive quadrature signal generation network**

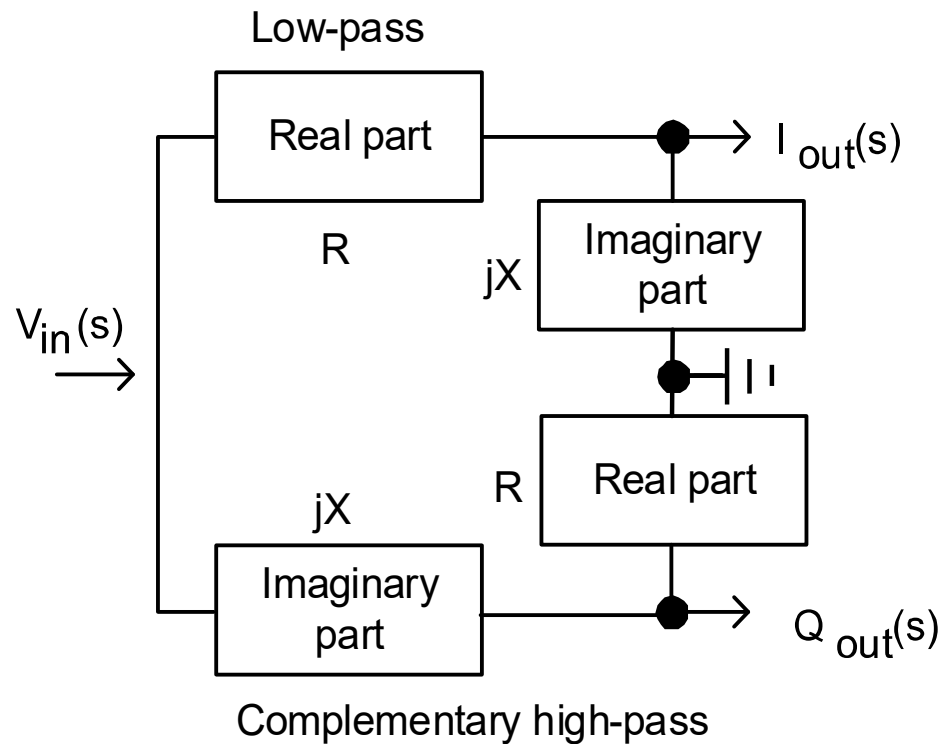
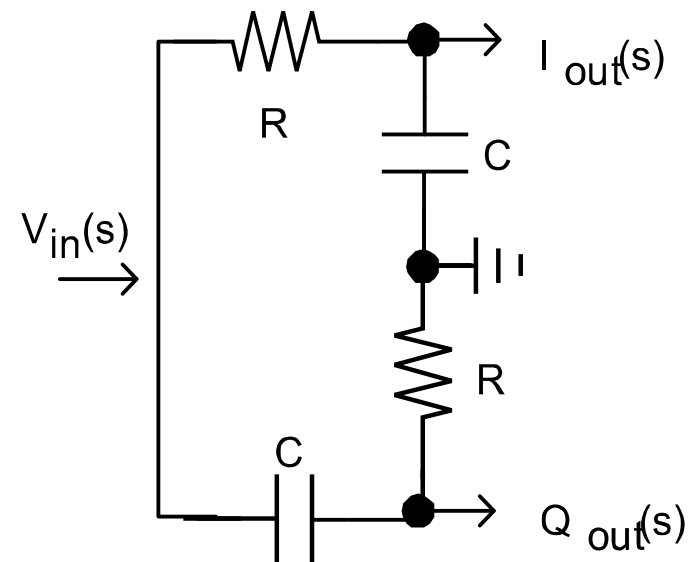


Diagram of a quadratic generator

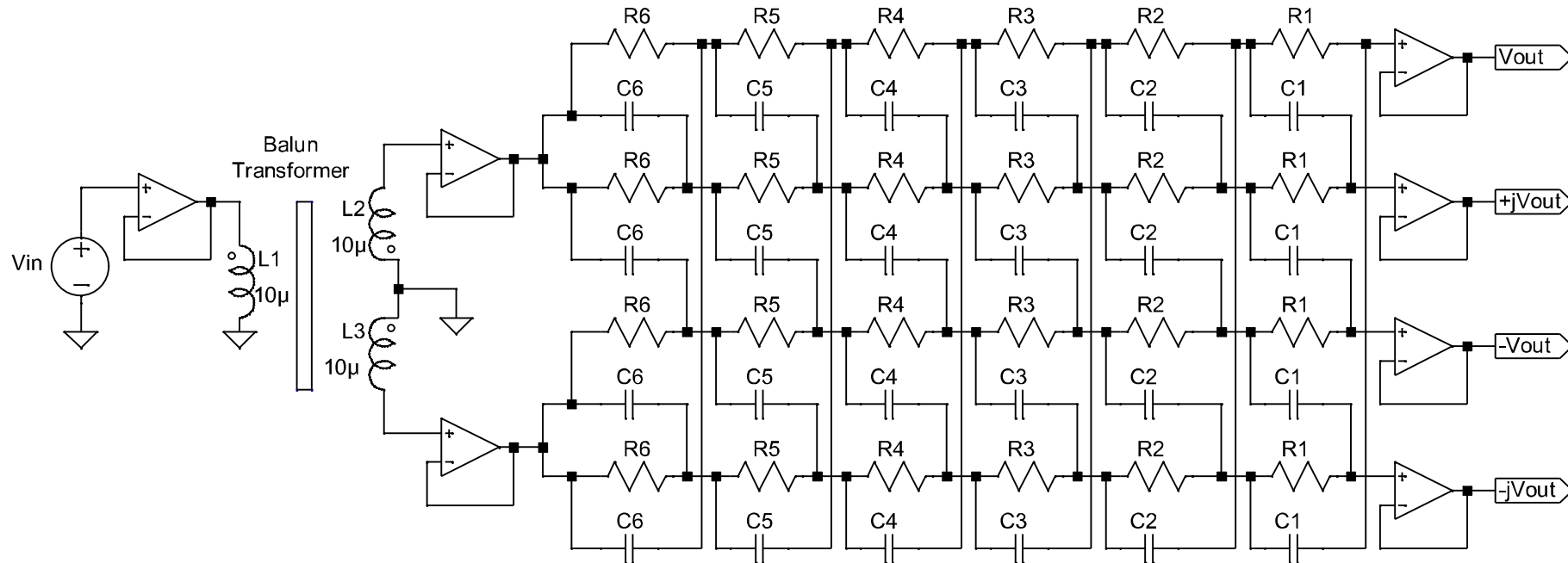


Circuit of a quadratic generator

3. Proposed Designs and Experimental Results

Design of 6th-Order Polyphase Signal Generation

Proposed design of 6th-order polyphase signal generation



Transfer function

$$H(\omega) = \frac{[1 + b_1\omega][1 + b_2\omega][1 + b_3\omega][1 + b_4\omega][1 + b_5\omega][1 + b_6\omega]}{a_0(j\omega)^6 + a_1(j\omega)^5 + a_2(j\omega)^4 + a_3(j\omega)^3 + a_4(j\omega)^2 + a_5j\omega + 1};$$

3. Proposed Designs and Experimental Results

Behavior of 6th-order Quadrature Signal Generation

Transfer function

$$H(f) = \frac{\left(1 + \frac{1}{5 \cdot 10^5} f\right) \left(1 + \frac{1}{8 \cdot 10^5} f\right) \left(1 + \frac{1}{1.5 \cdot 10^6} f\right) \left(1 + \frac{1}{3 \cdot 10^6} f\right) \left(1 + \frac{1}{6 \cdot 10^6} f\right) \left(1 + \frac{1}{9.5 \cdot 10^6} f\right)}{1.54 \cdot 10^{-38} (jf)^6 + 1.85 \cdot 10^{-30} (jf)^5 + 2.88 \cdot 10^{-23} (jf)^4 + 1.14 \cdot 10^{-16} (jf)^3 + 1.35 \cdot 10^{-10} (jf)^2 + 4.02 \cdot 10^{-5} jf + 1}$$

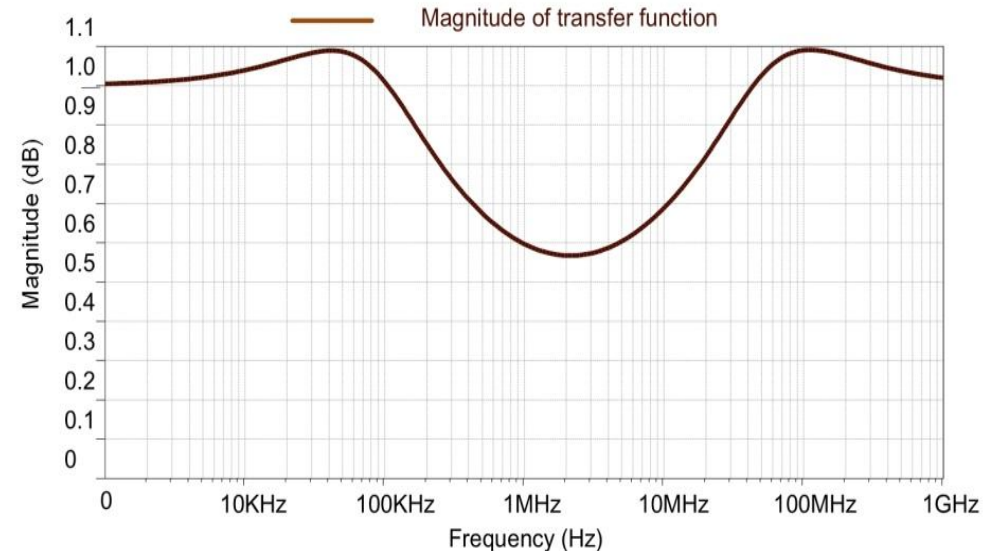
Behaviors of transfer function

$$|H(f)| = \begin{cases} \lim_{f \rightarrow 0^+} |H(f)| = 1 \\ \text{Max}_1 = 1.09; f_{\text{max}1} = 4.08 \cdot 10^4 \text{ Hz} \\ \text{Min} = 0.812; f_{\text{min}} = 2.2 \cdot 10^6 \text{ Hz} ; \\ \text{Max}_2 = 1.09; f_{\text{max}2} = 107 \cdot 10^6 \text{ Hz} \\ \lim_{f \rightarrow +\infty} |H(f)| = 1 \end{cases}$$

$$\theta(f) = \begin{cases} \theta_{P1} = 0 ; f \rightarrow 0^+ \\ \theta_{P2} = \frac{-\pi}{4} ; f_{\text{max}1} = 4.08 \cdot 10^4 \text{ Hz} \\ \theta_{P3} = \frac{-3\pi}{2} ; f_{\text{min}} = 2.2 \cdot 10^6 \text{ Hz} \\ \theta_{P4} = \frac{-11\pi}{4} ; f_{\text{max}2} = 107 \cdot 10^6 \text{ Hz} \\ \theta_{P5} = -3\pi ; f \rightarrow +\infty \end{cases}$$

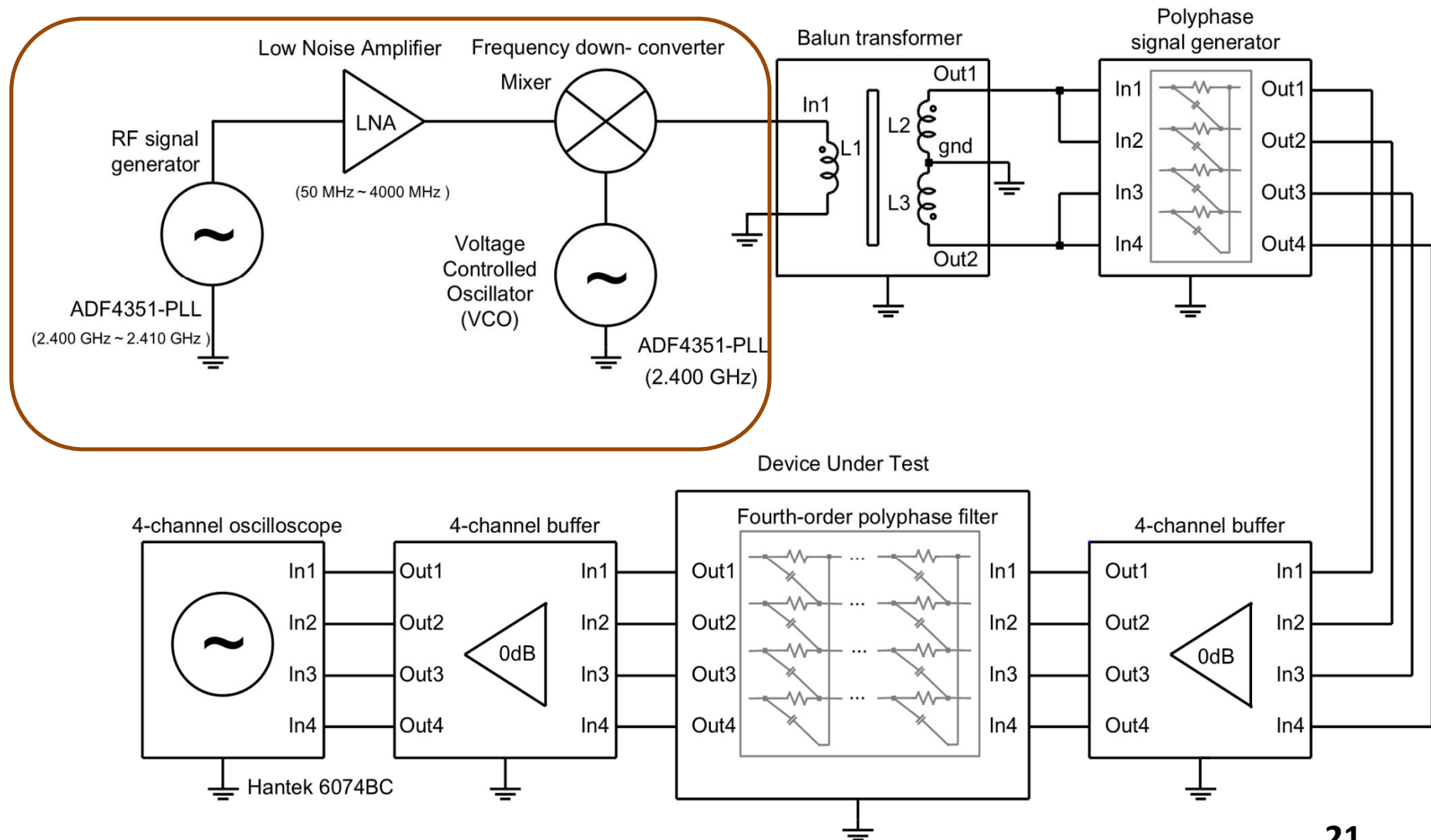
**R₁ = 1 kΩ, C₁ = 318 pF, R₂ = 1 kΩ, C₂ = 199 pF,
R₃ = 1 kΩ, C₃ = 106 pF, R₄ = 1 kΩ, C₄ = 53.1 pF,
R₅ = 1 kΩ, C₅ = 26.5 pF, R₆ = 1 kΩ, C₆ = 16.8 pF**

Simulation result of transfer function



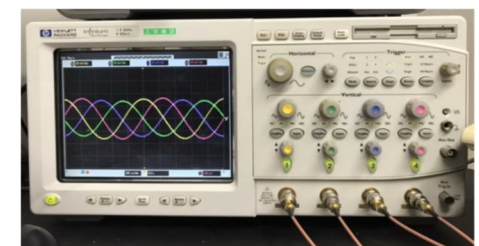
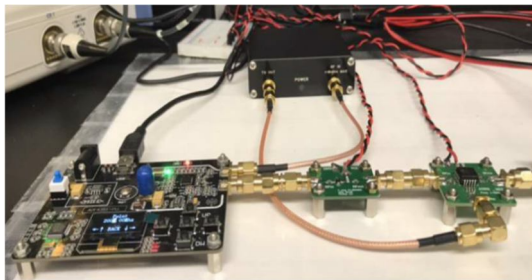
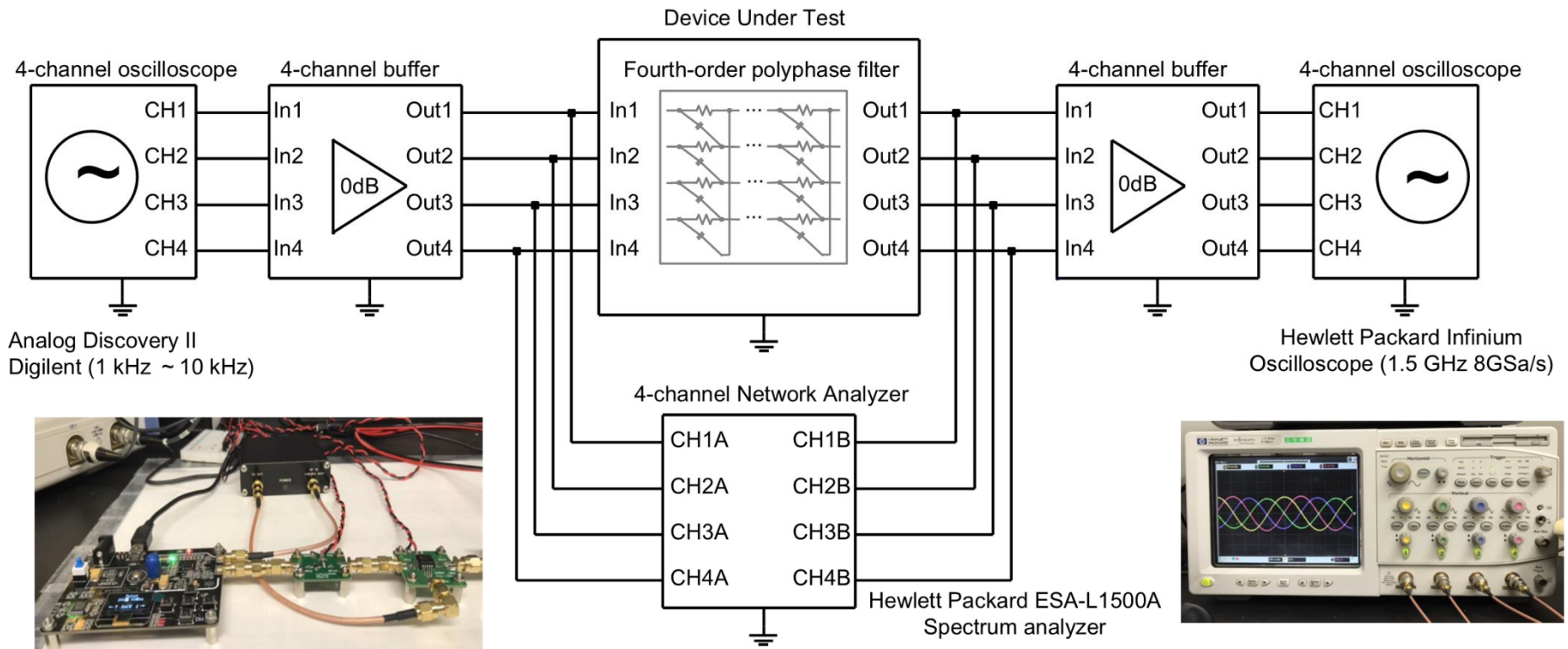
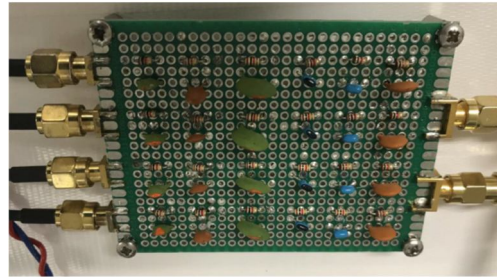
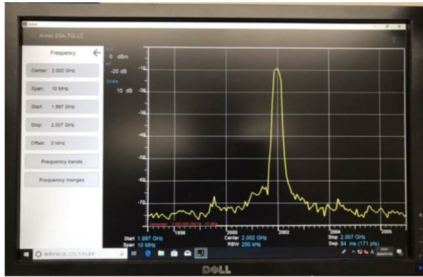
3. Proposed Designs and Experimental Results

Block Diagram of Measurement Set Up



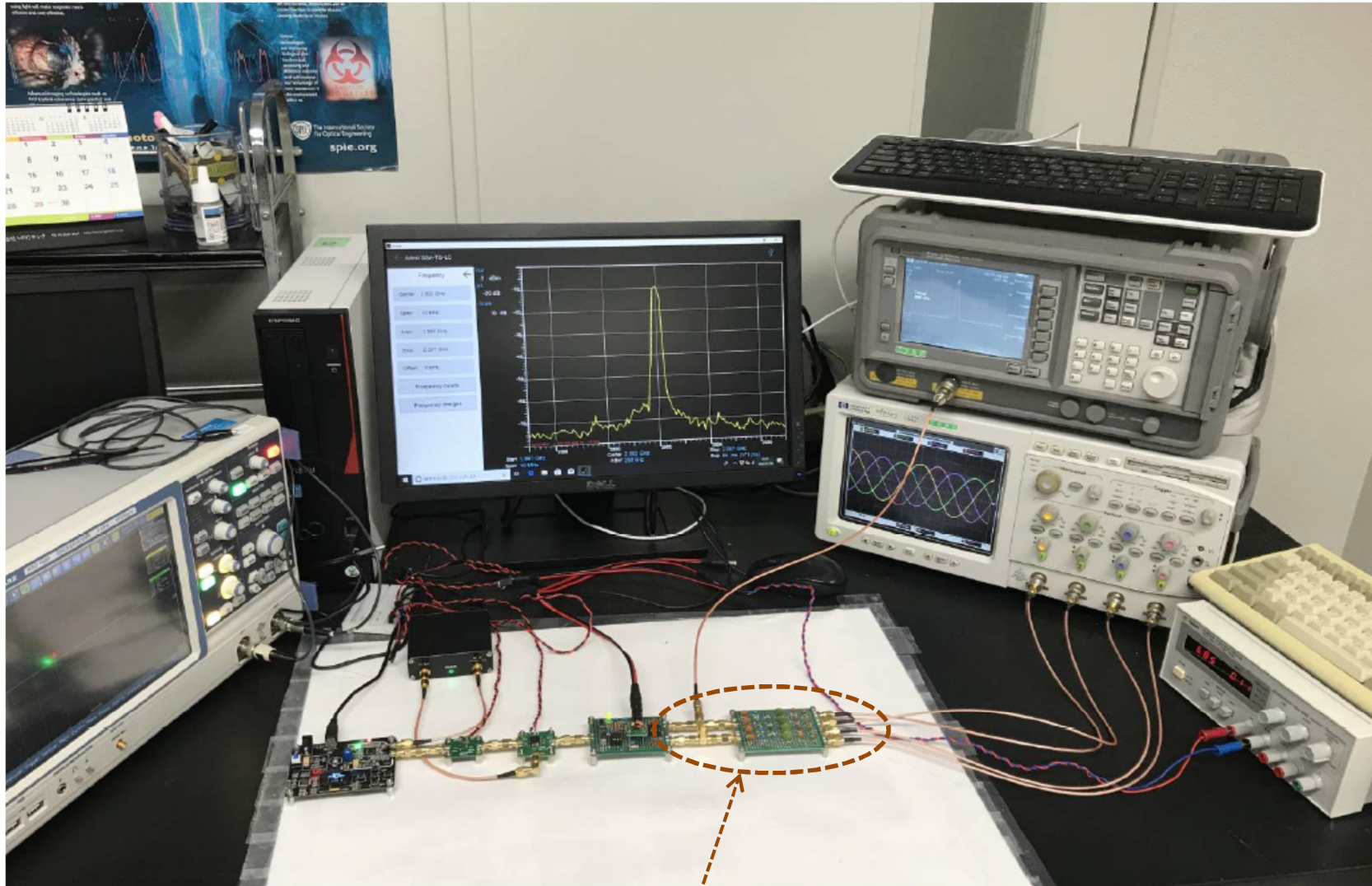
3. Proposed Designs and Experimental Results

Simplified Block Diagram of Measurement Set Up



3. Proposed Designs and Experimental Results

Measurement Set Up for Device Under Test

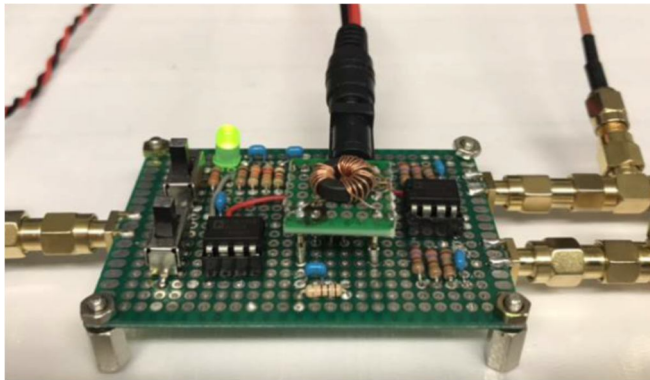


Device under test

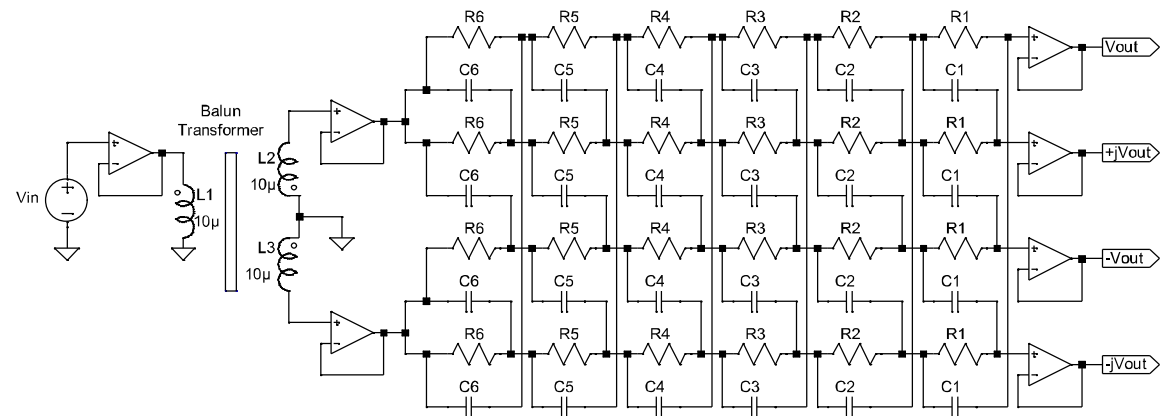
3. Proposed Designs and Experimental Results

Measurement Results of Implemented Circuit

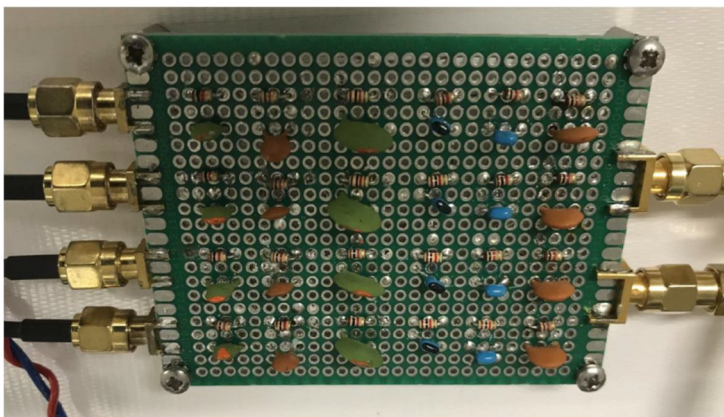
Passive balun transfer



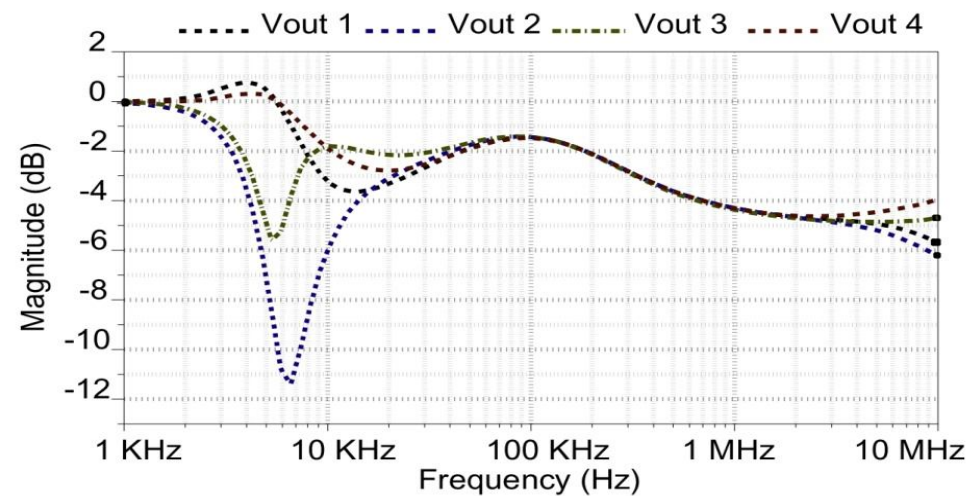
6th-order polyphase signal generation



Implemented circuit



Measurement results



Outline

1. Research Background

- Motivation, objectives and achievements
- Review of characteristics of Low-IF receiver

2. Investigation of Multi-Phase Networks

- Superposition theorem for multi-source networks
- Design principle for passive polyphase filters

3. Proposed Designs and Experimental Results

- Analysis of quadrature signal generation networks
- Simulation and measurement results

4. Conclusions

4. Comparison

Features	Proposed formula	Conventional Superposition	Millan's theorem
Effects of all actuating sources	At one time	Several times	At one time
Transfer function accuracy	Yes	No	No
Single-input network analysis	Yes	Yes	Yes
Polyphase network analysis	Yes	No	No
Complex network analysis	Yes	No	No
Image rejection ratio accuracy	Yes	No	No

4. Discussions

Transfer function and **image rejection ratio** give useful information about the behaviors of **polyphase filters** and **complex filters**.

Fundamental network analysis theory for **multi-source systems**:

- **Compute** the effects of all sources at one time,
- **Reduce** the wasteful time,
- **Decrease** the hand calculation times,
- **Get** the transfer function faster, and
- **Reduce** the network complexity.

4. Conclusions

This work:

- **Proposal of superposition formula** for multi-source network analysis
- **Analysis of high-order passive RC poly-phase filters** in all frequency domain
- **Design of quadrature signal generation network**
- **Implementation and measurement of 6th-order quadrature signal generation circuit**

Future of work:

- **Analysis of I/Q mismatches, DC offsets, and parasitic components** in polyphase and complex filters

References

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Thank you very much!

谢谢

